



Exploring strategies to exploit machine learning in HPC-CFD

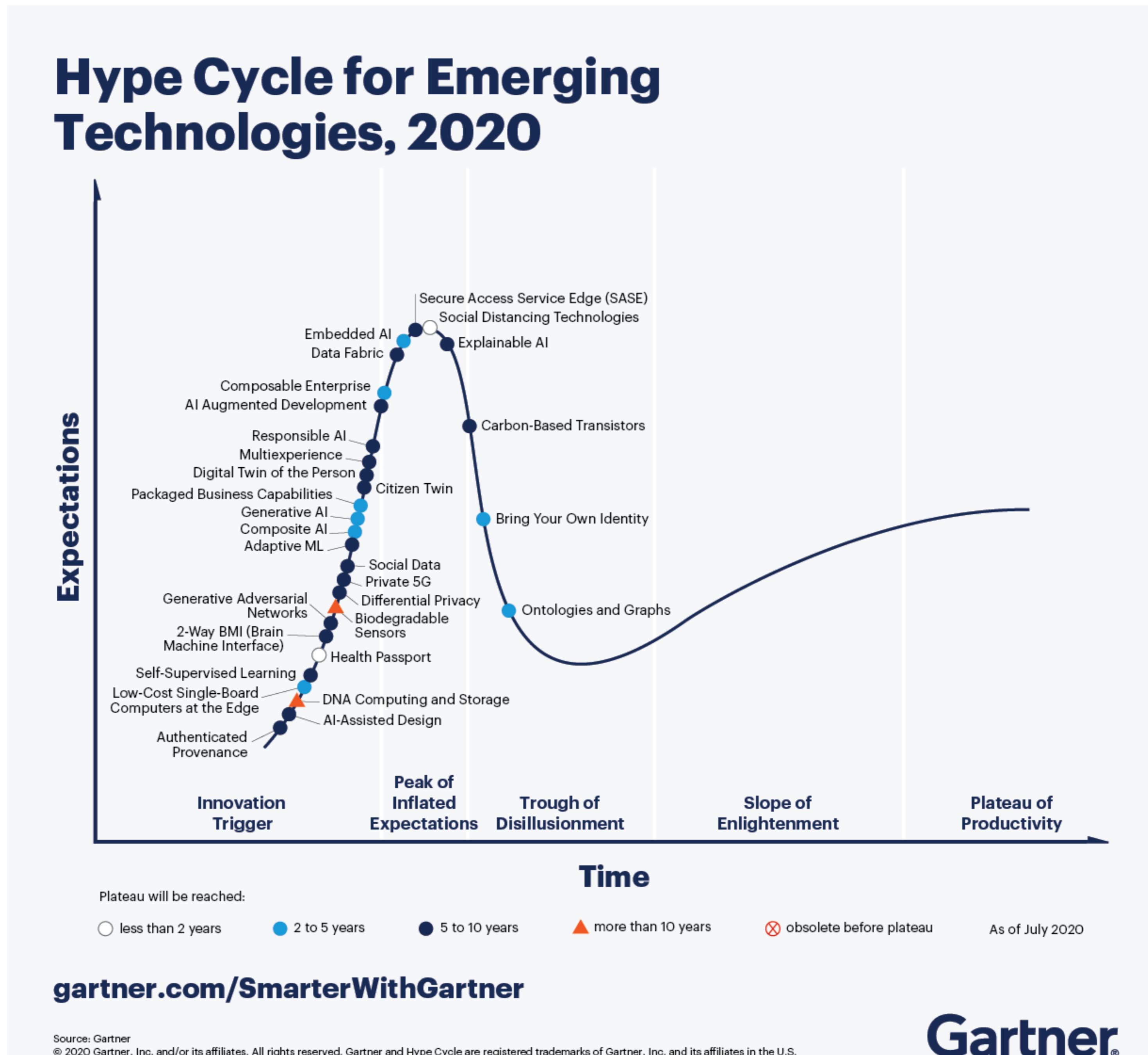
Corentin Lapeyre

MAGISTER • 2020.09.15

Acknowledgments: A. Misdariis, N. Cazard, C. Besombes, V. Xing, E. Gullaud, L. Drozda, T. Poinsot, M. Bauerheim (ISAE), R. Selmi (TOTAL)
and many more contributors...

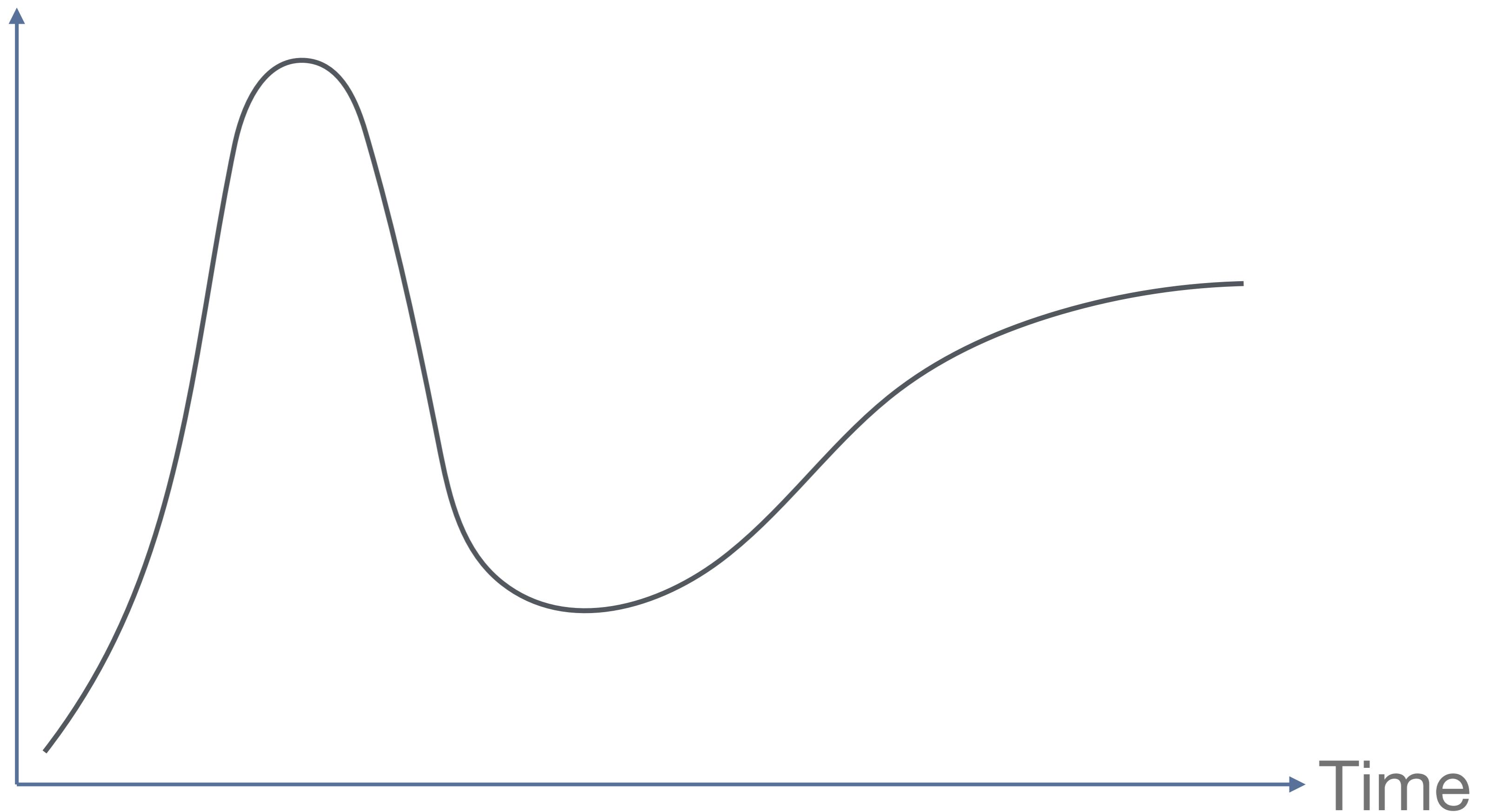


The hype



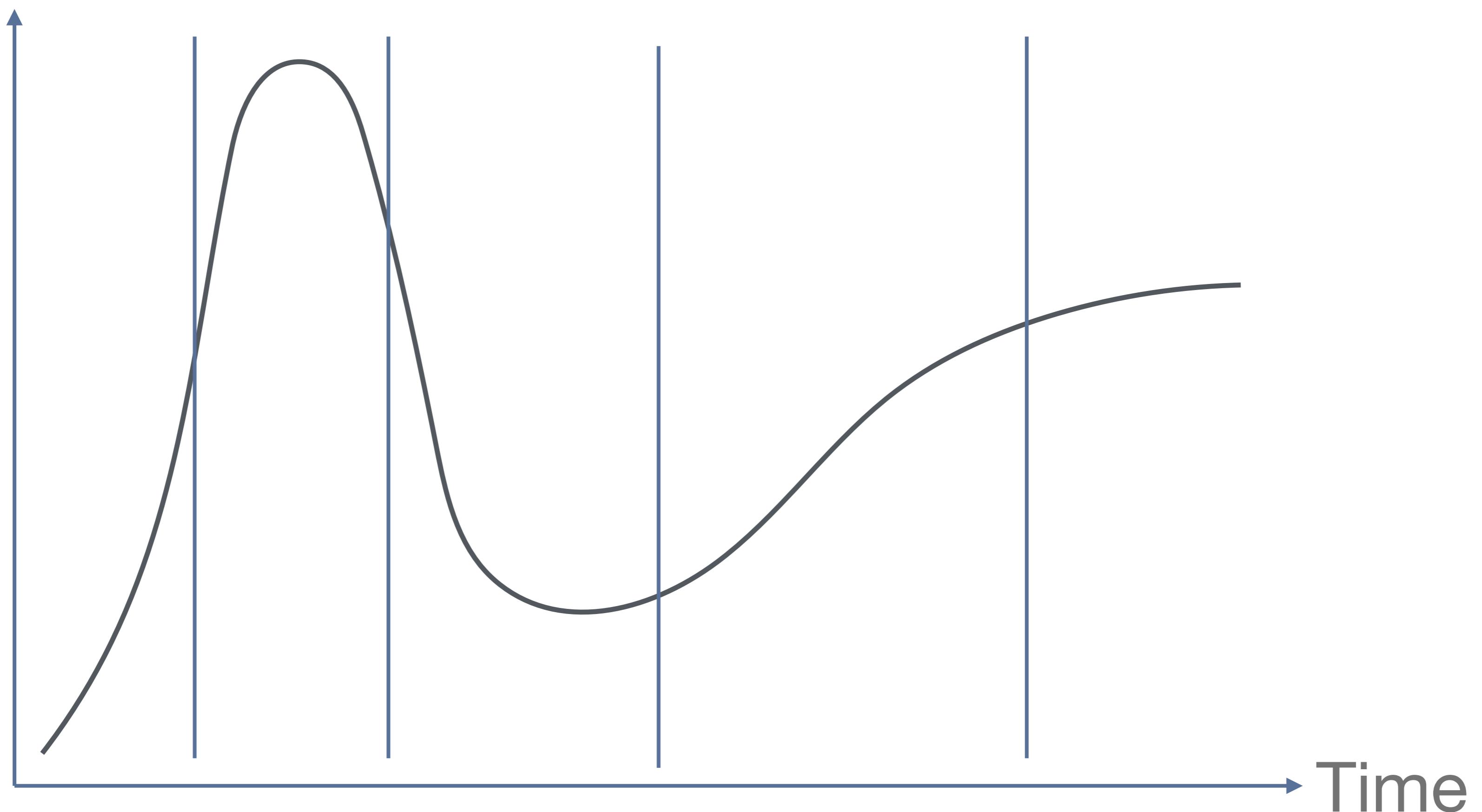
The hype

Expectations



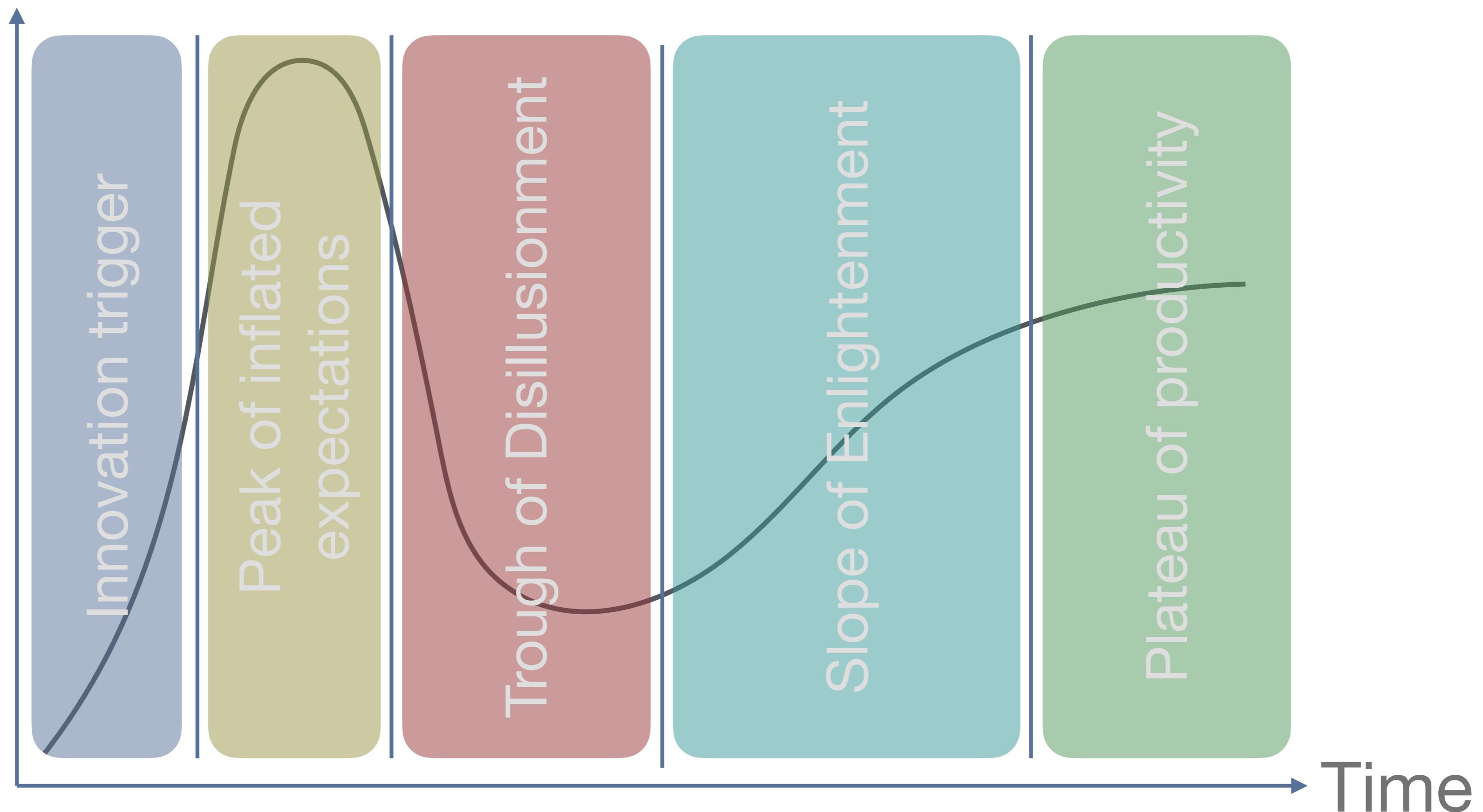
The hype

Expectations

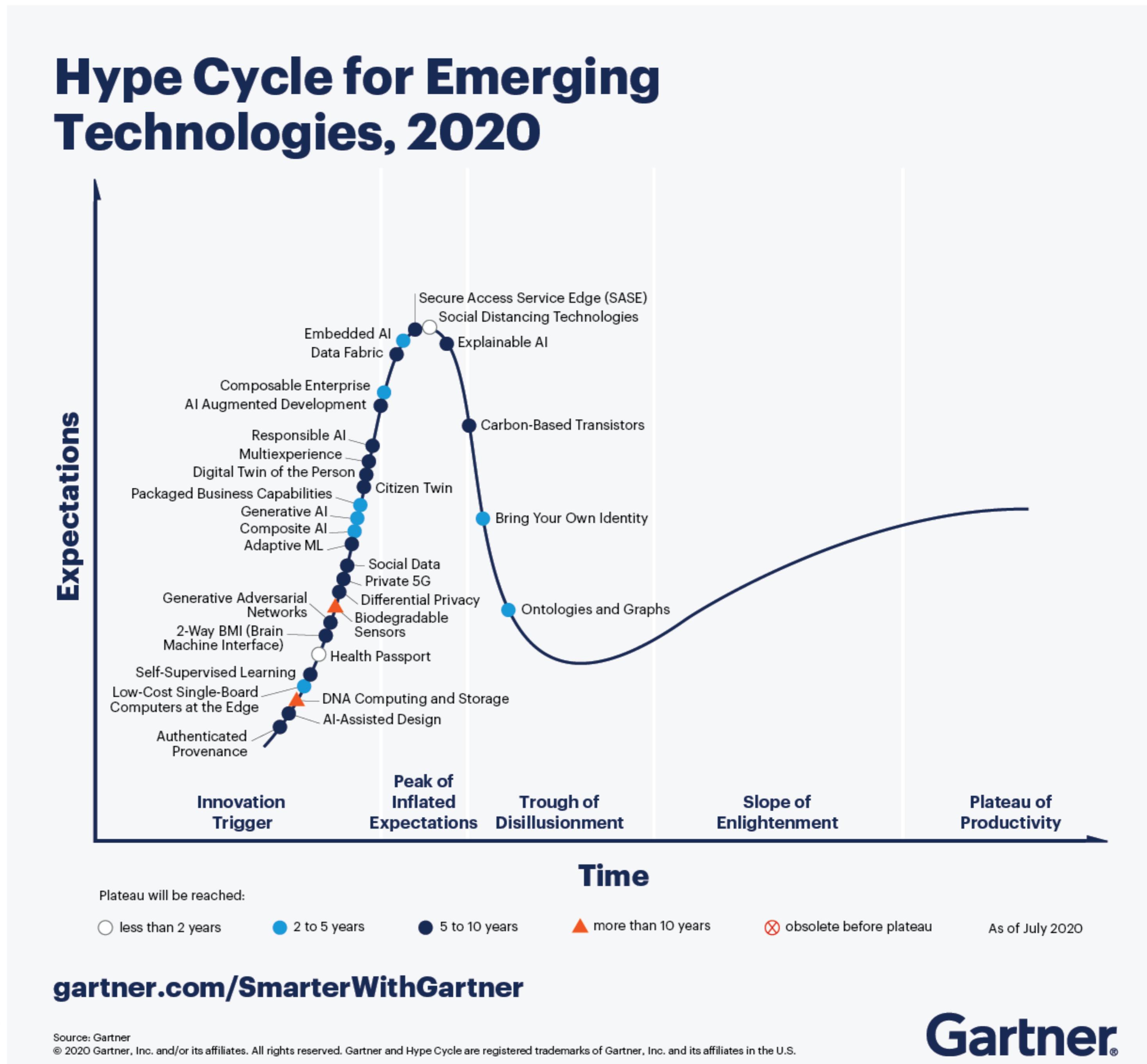


The hype

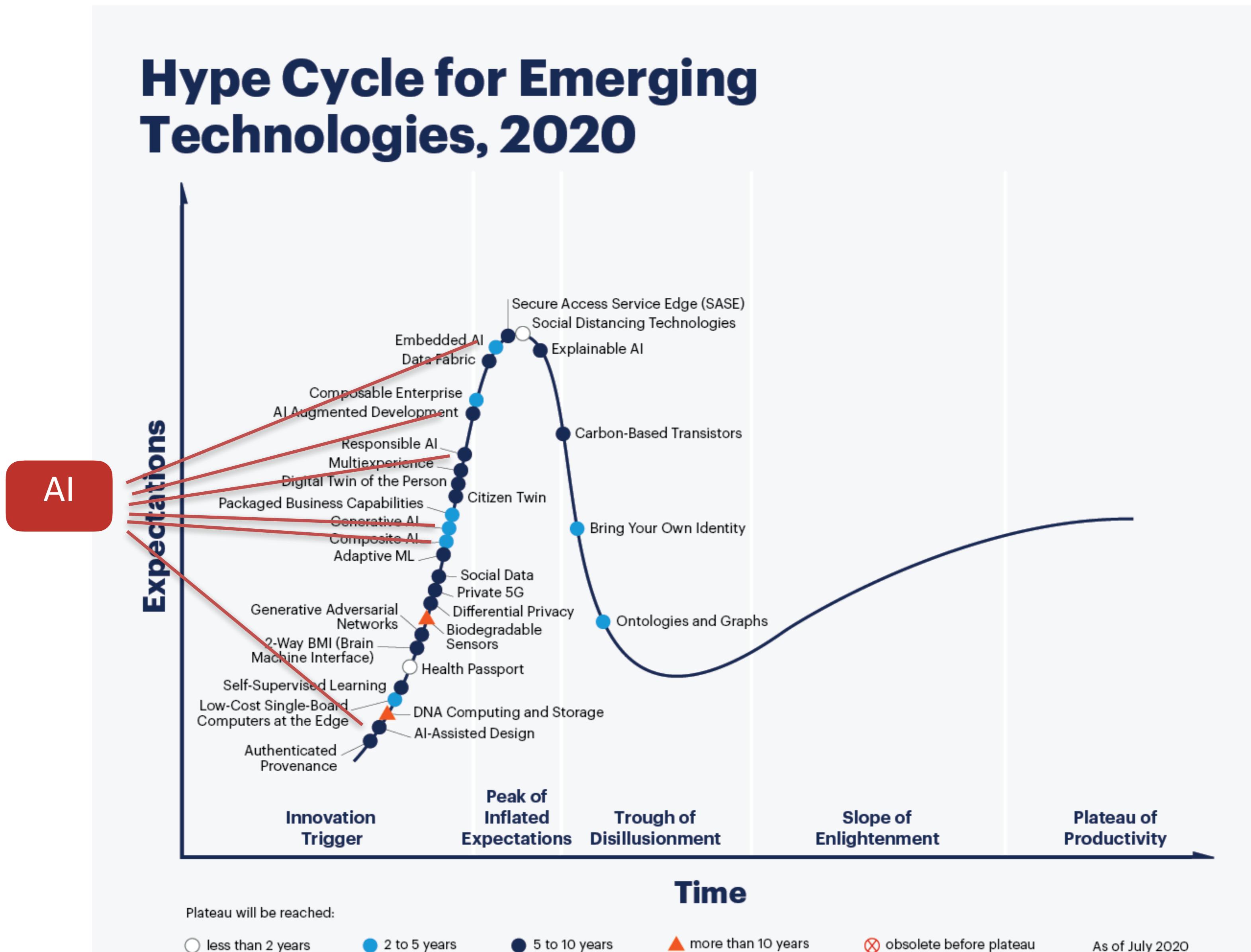
Expectations



The hype

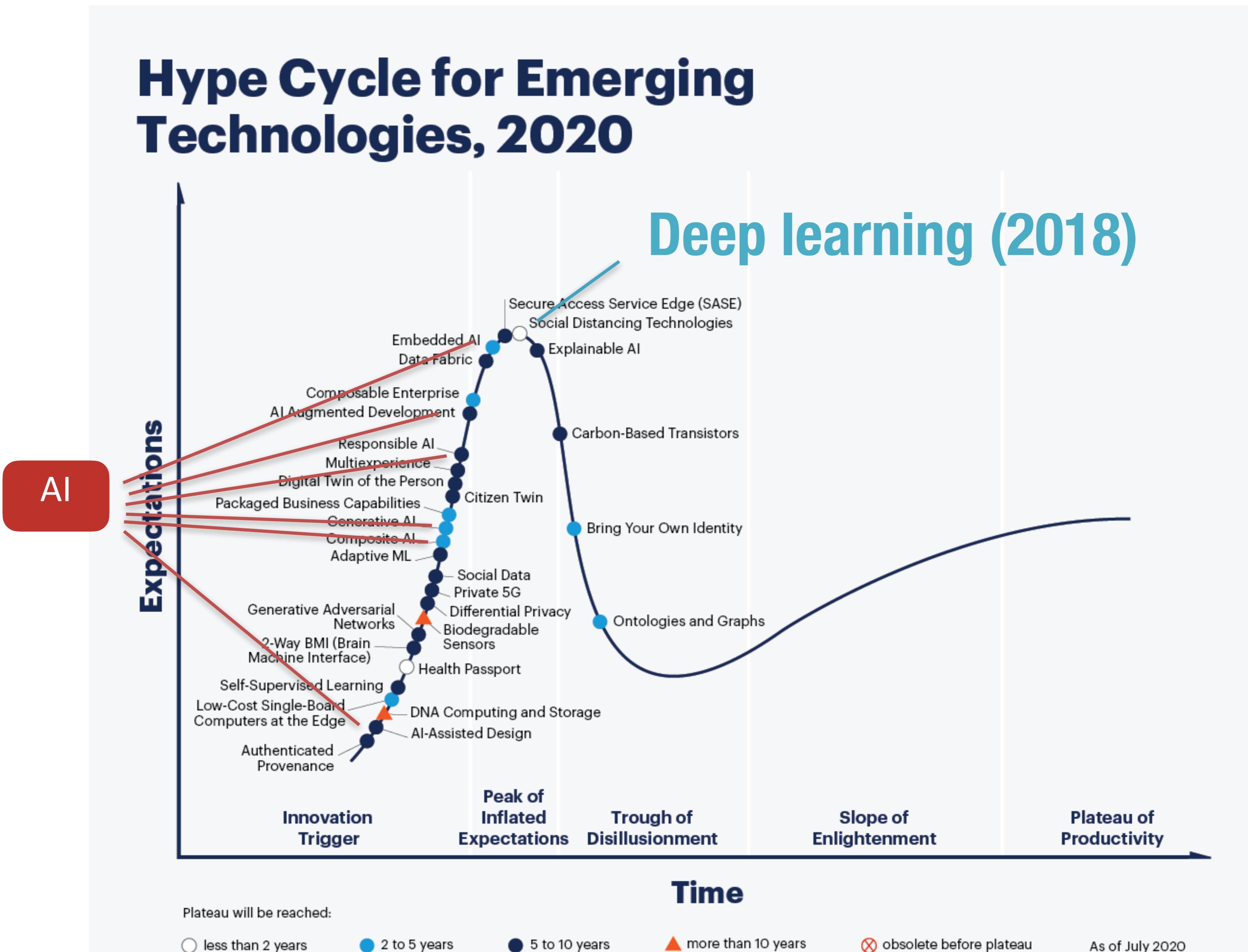


The hype

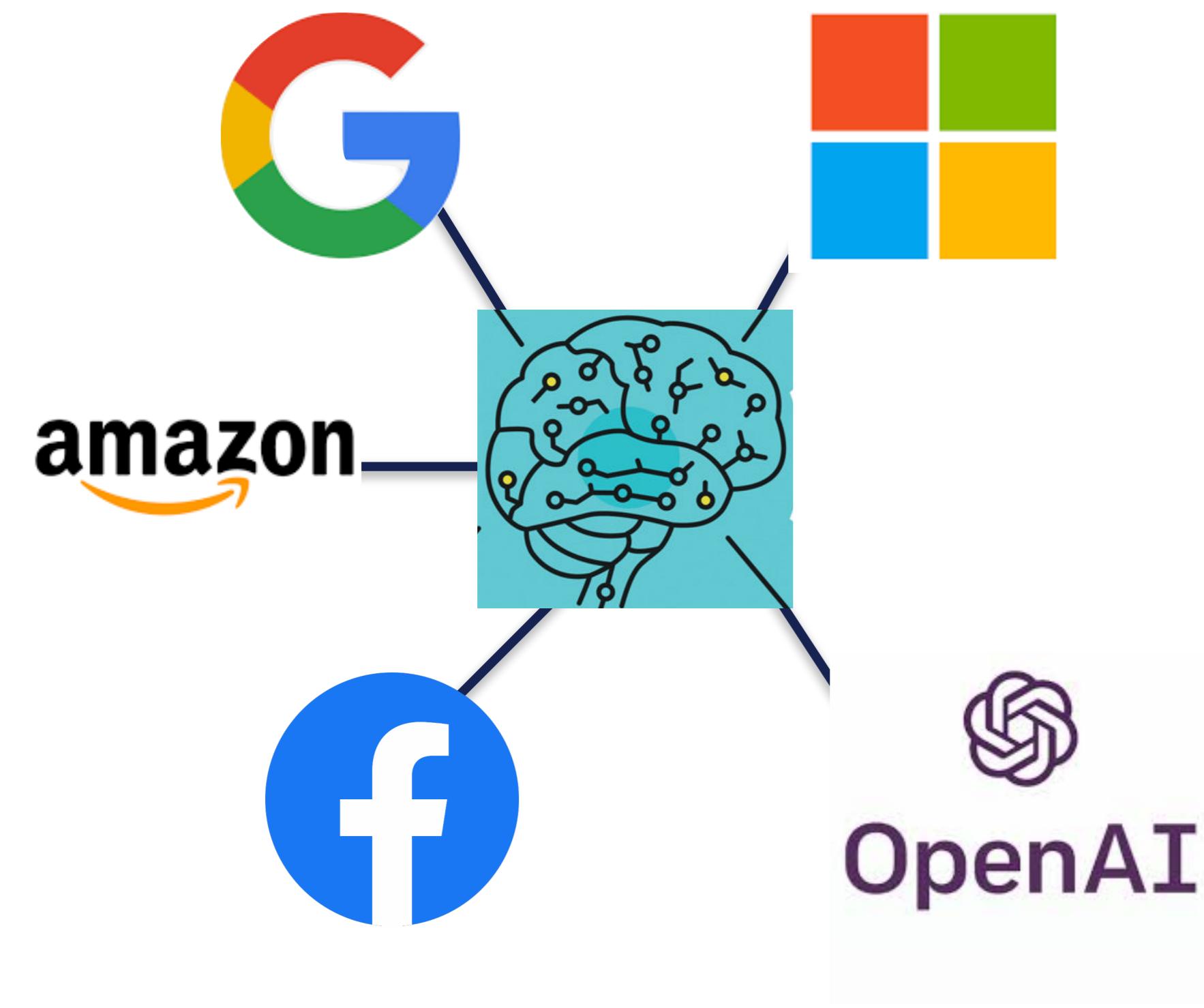


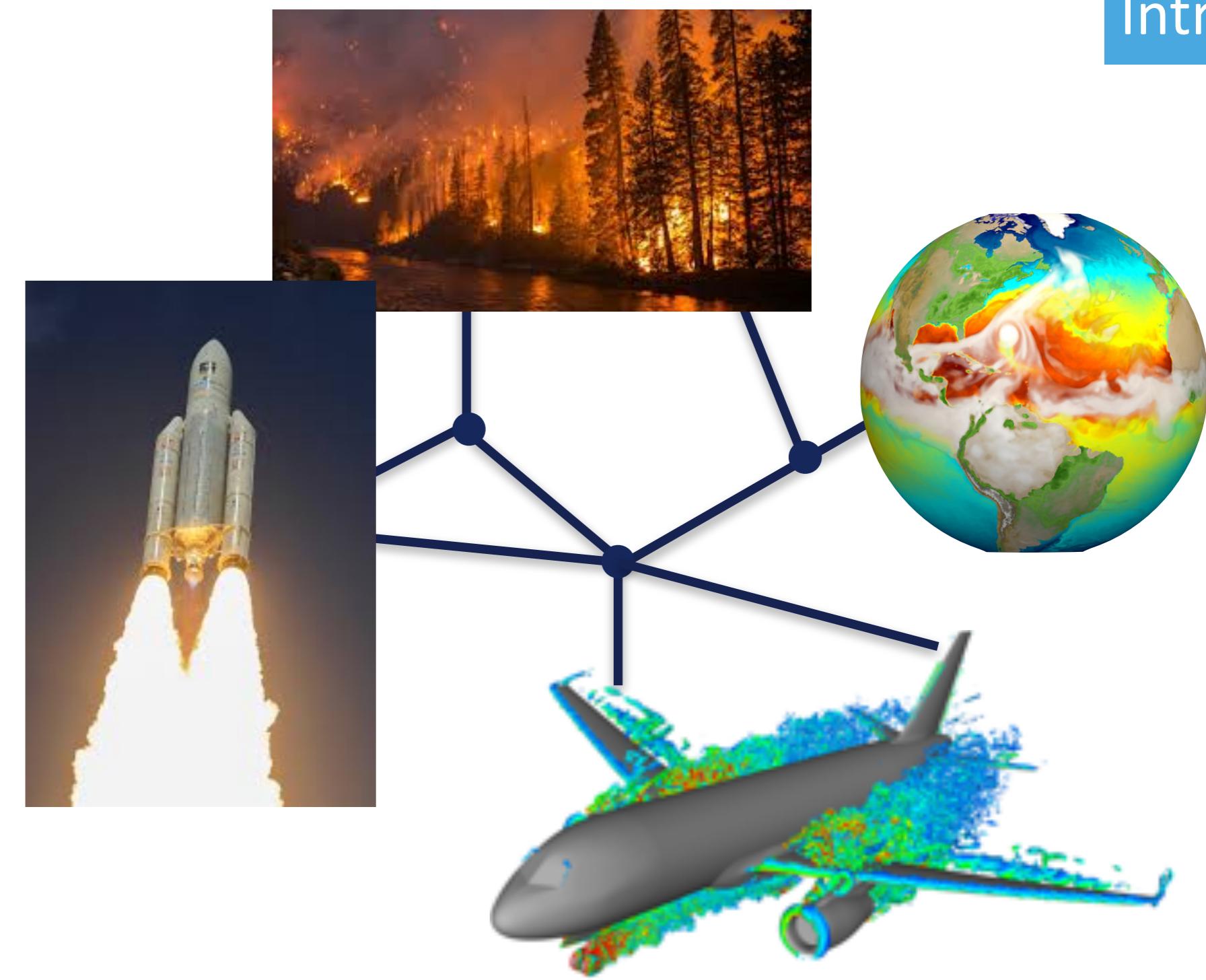
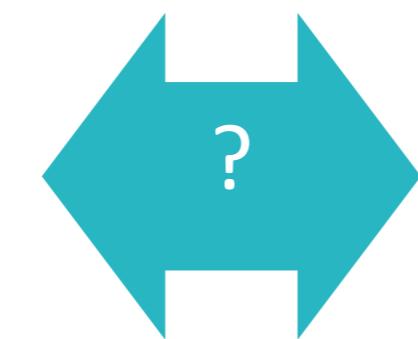
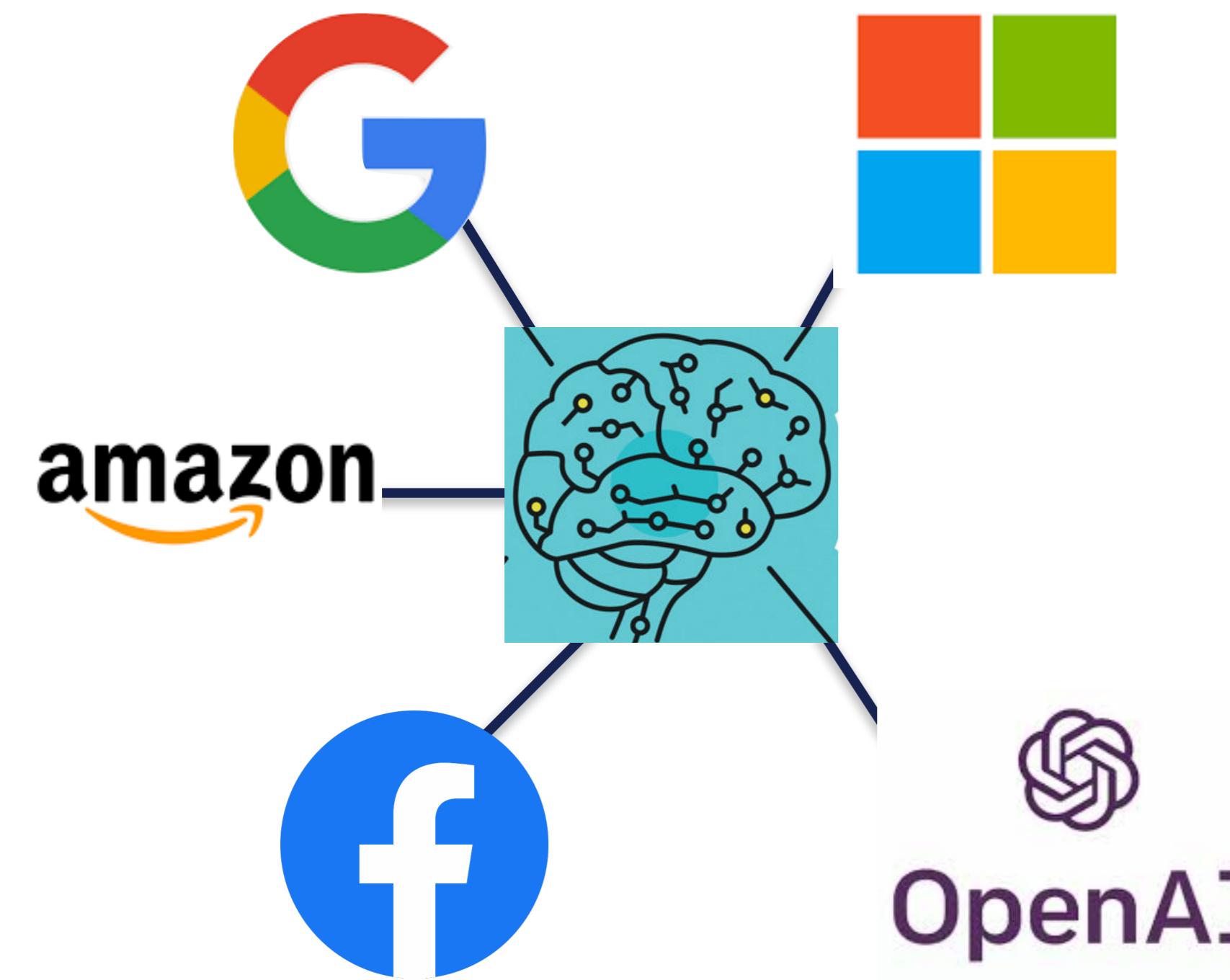
gartner.com/SmarterWithGartner

The hype

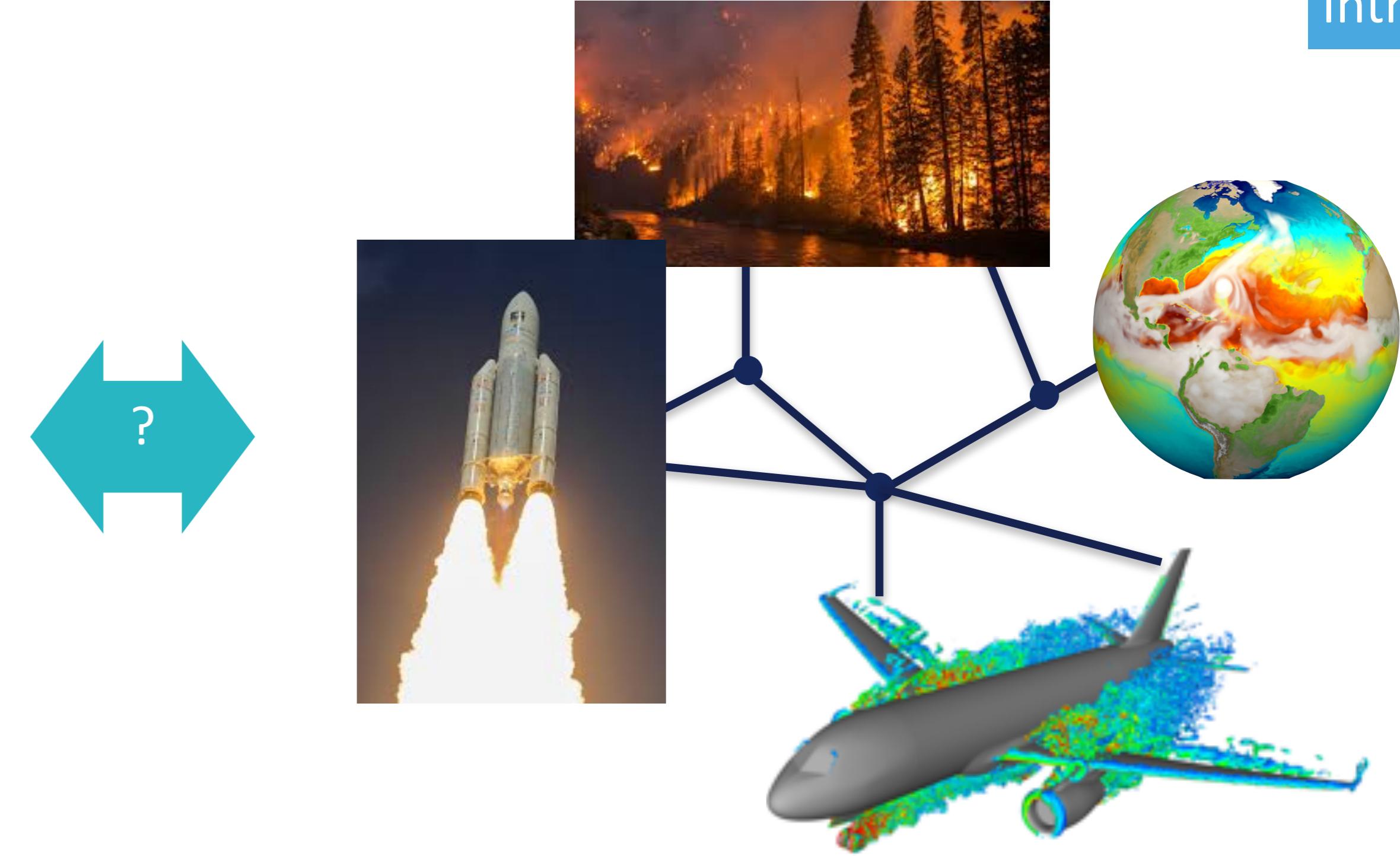
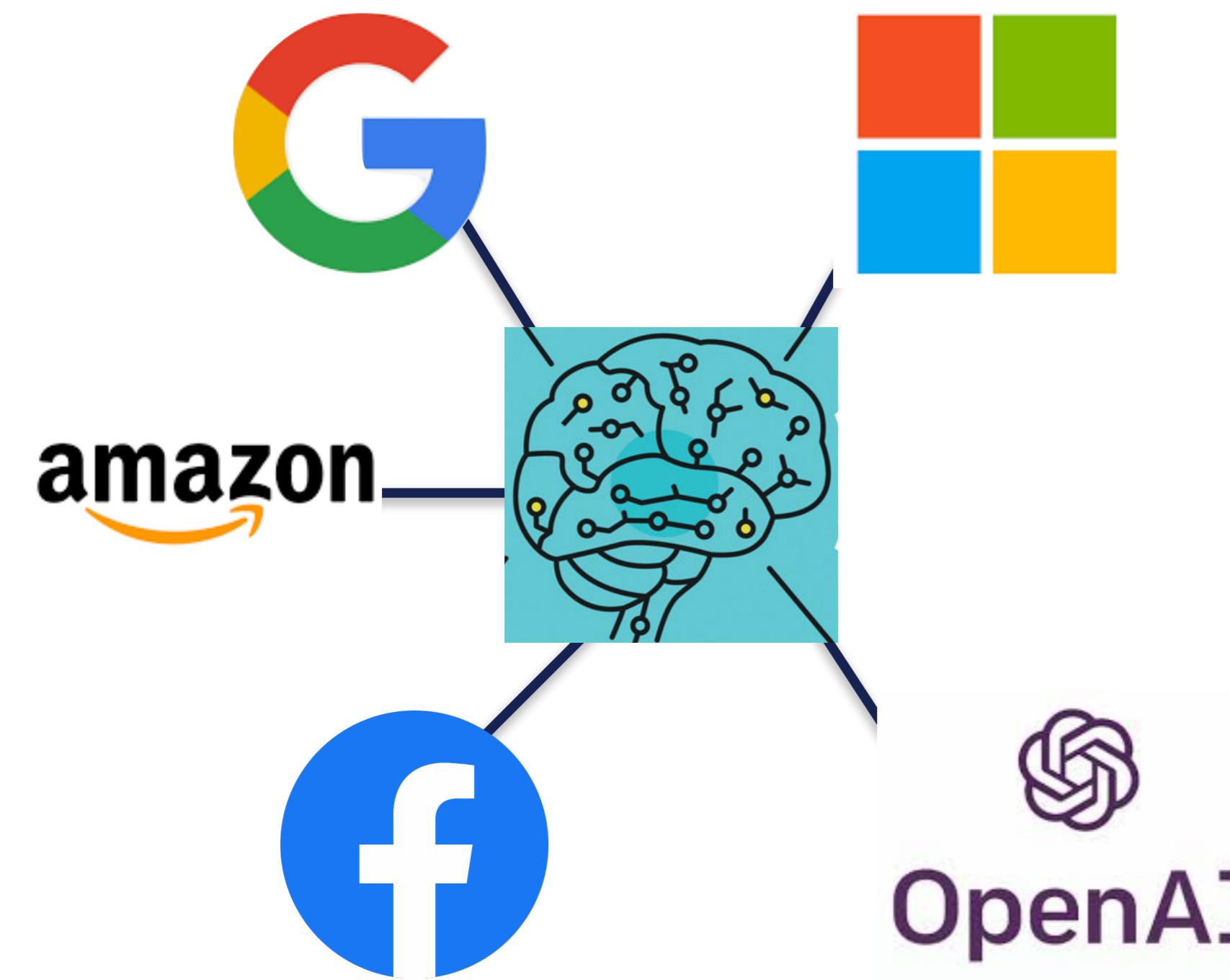


gartner.com/SmarterWithGartner

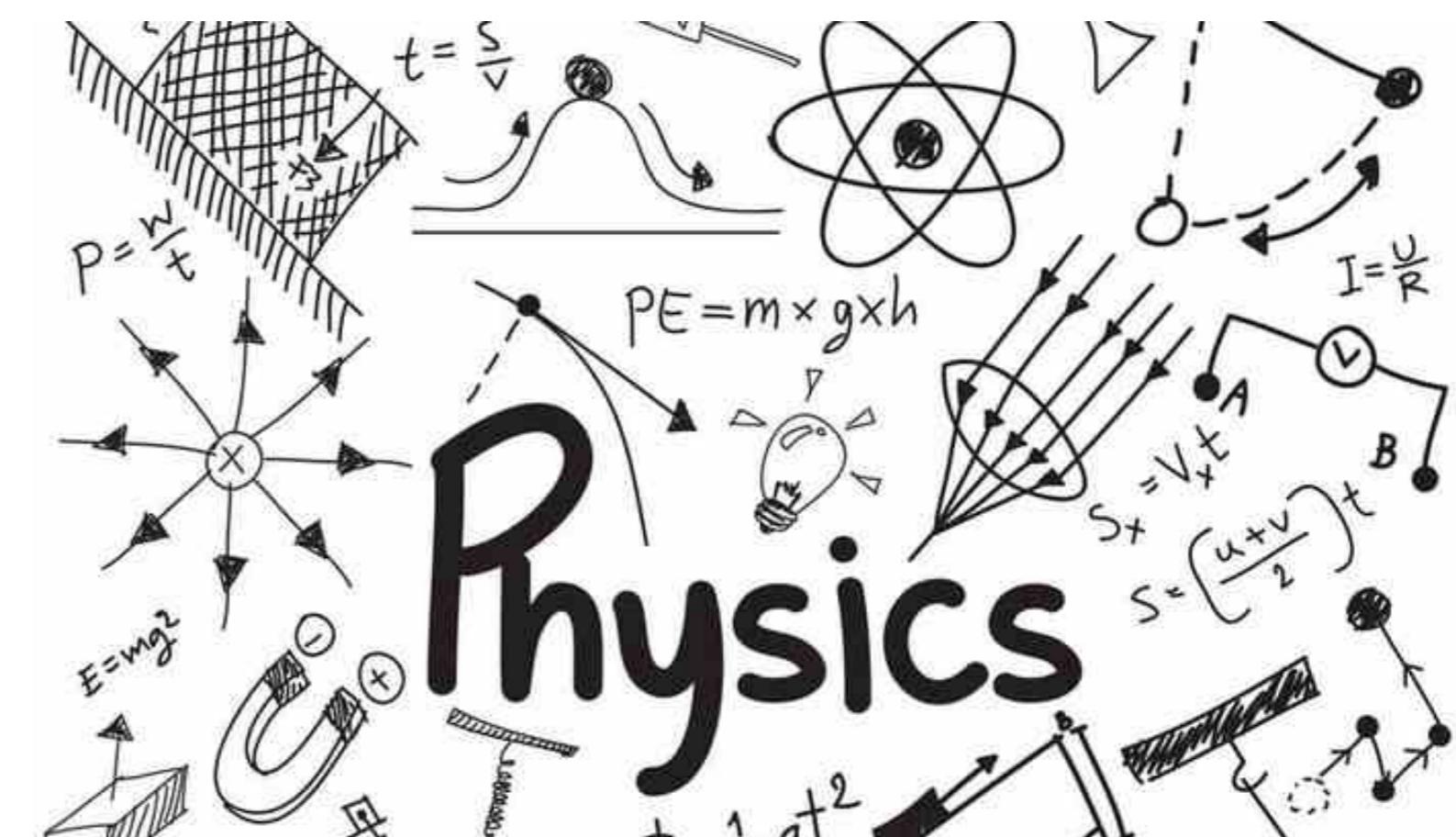
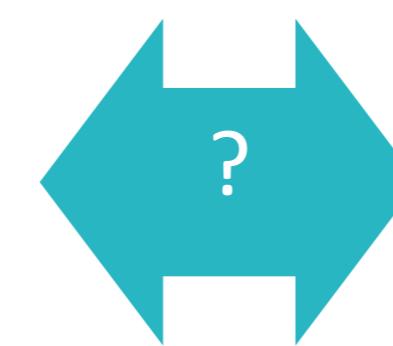
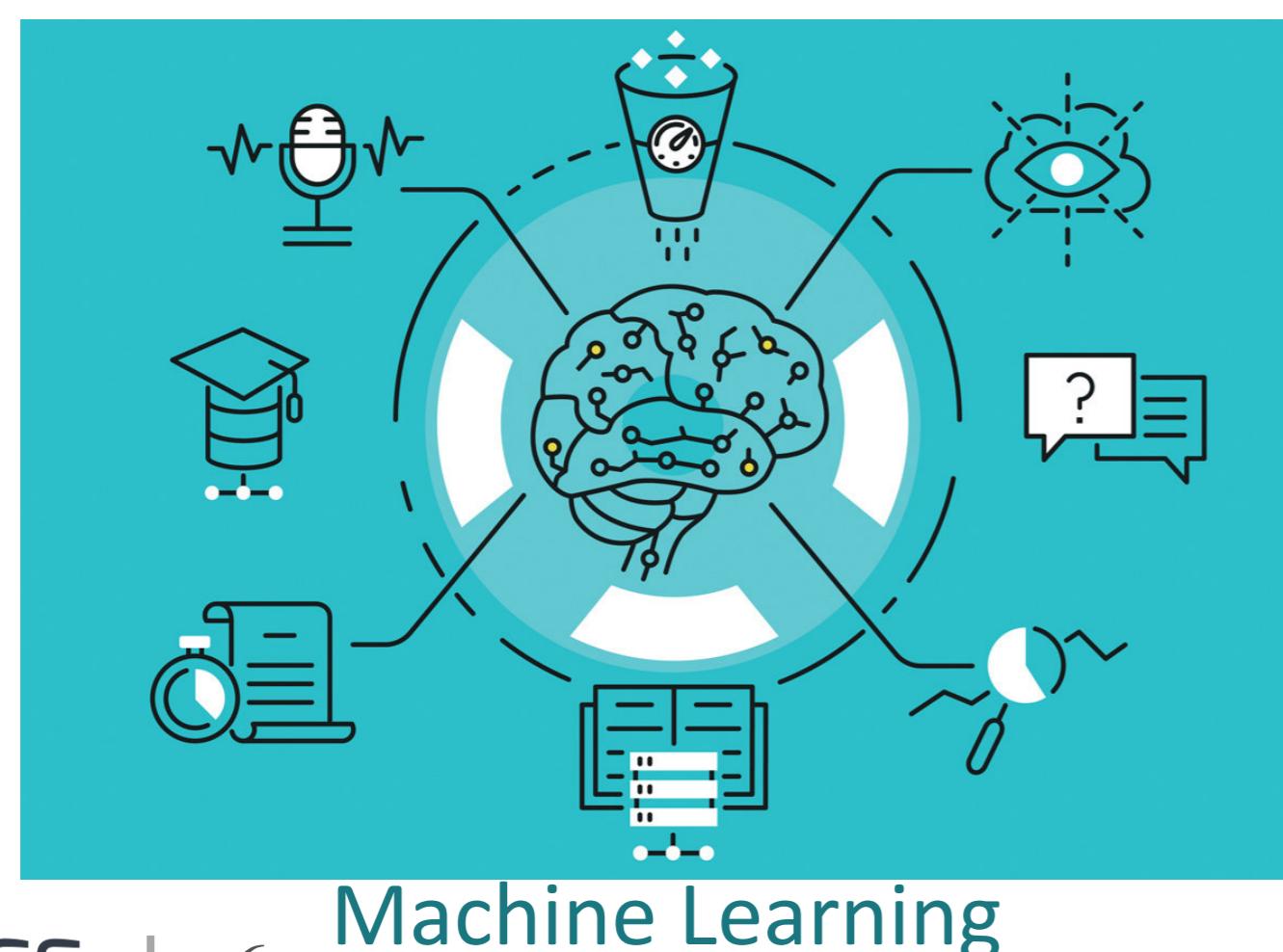




How is Data Science (DS) relevant to the Physical sciences?
A.k.a. how do we separate the hype from what's truly useful?



How is Data Science (DS) relevant to the Physical sciences?
A.k.a. how do we separate the hype from what's truly useful?



Machines that learn ?

The Data Science landscape

Statistics: The science of collecting, displaying, and analysing data
oxfordreference.com

Data science

The Data Science landscape

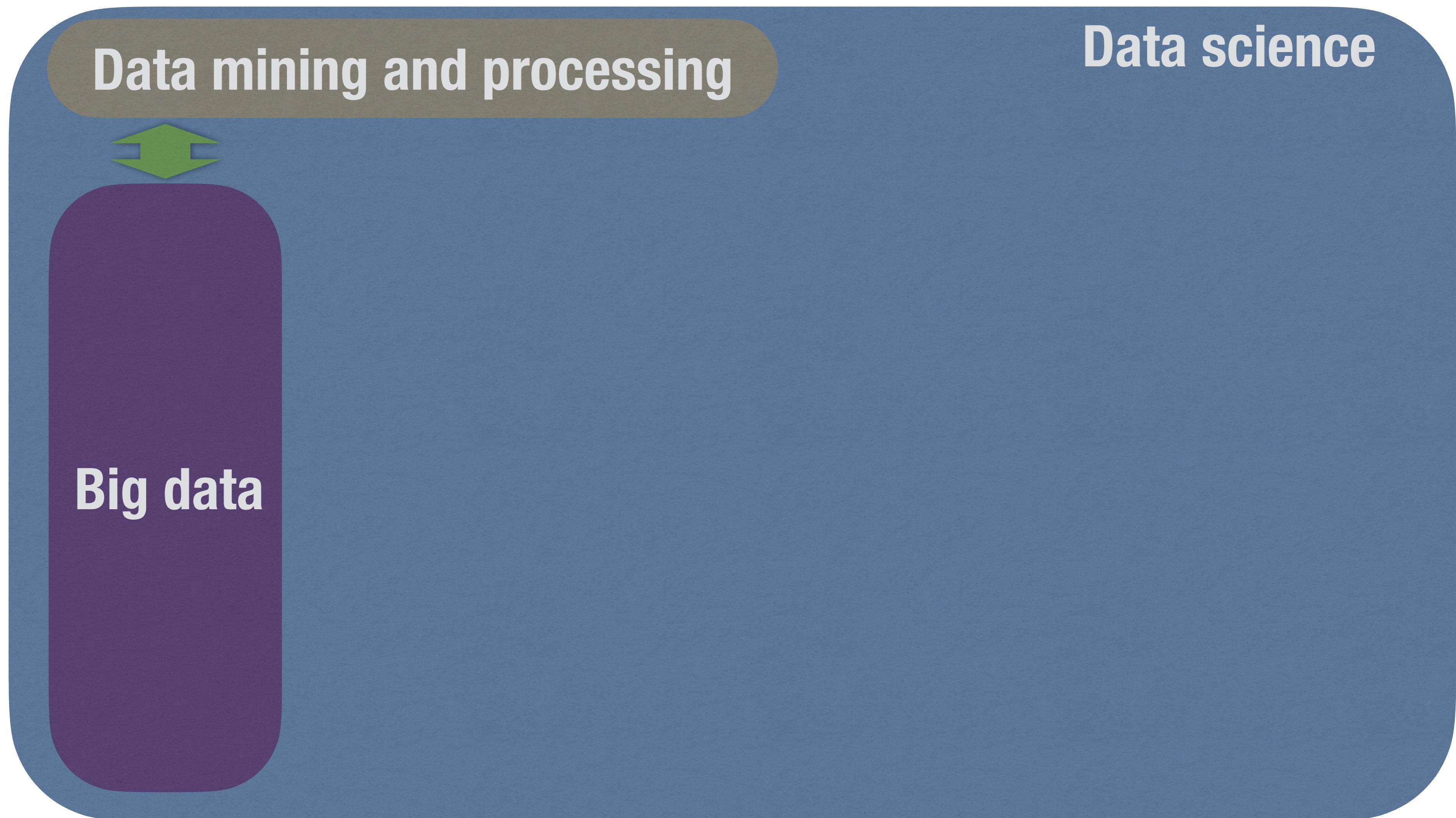
Statistics: The science of collecting, displaying, and analysing data
oxfordreference.com

Data mining and processing

Data science

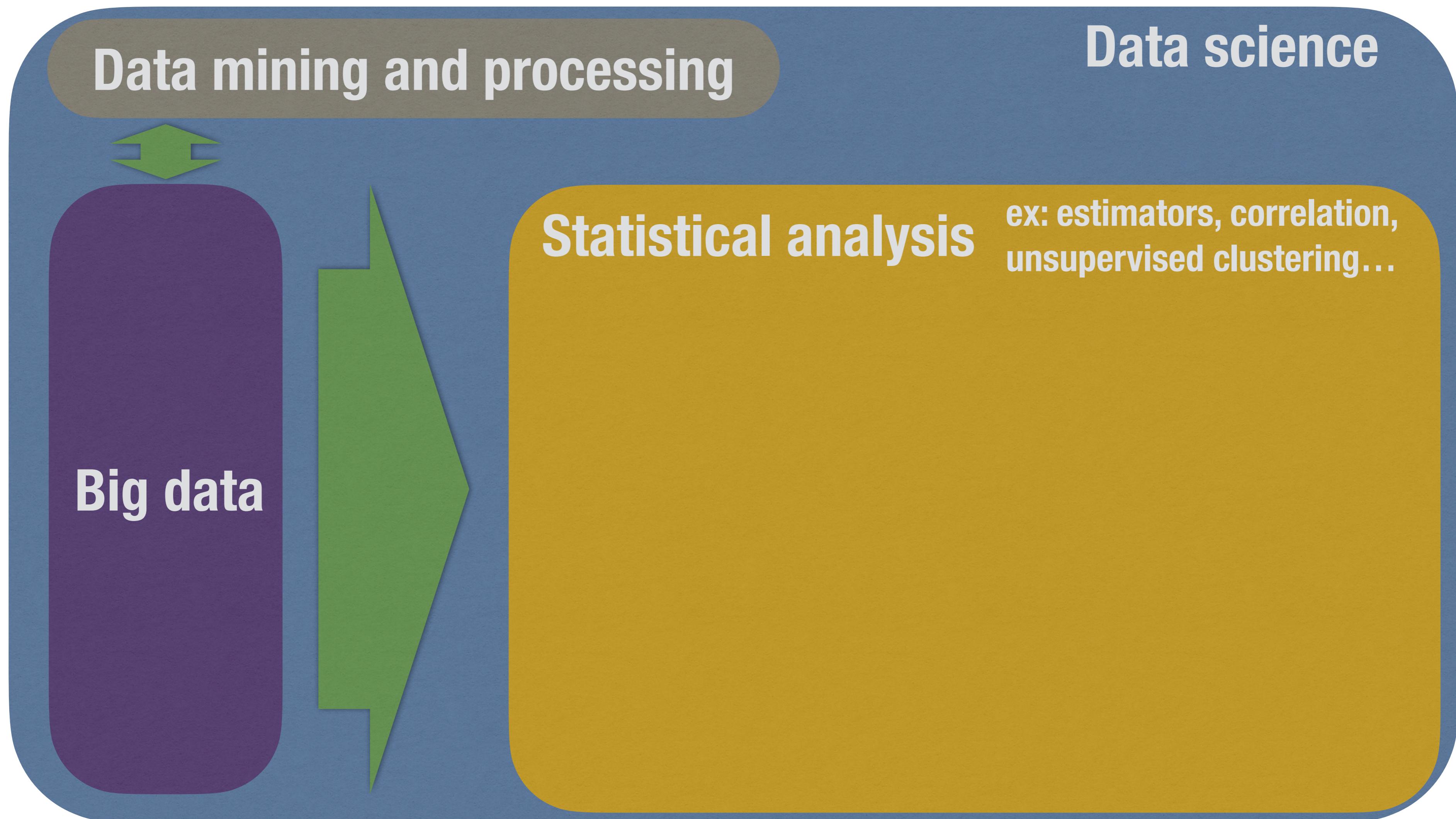
The Data Science landscape

Statistics: The science of collecting, displaying, and analysing data
oxfordreference.com



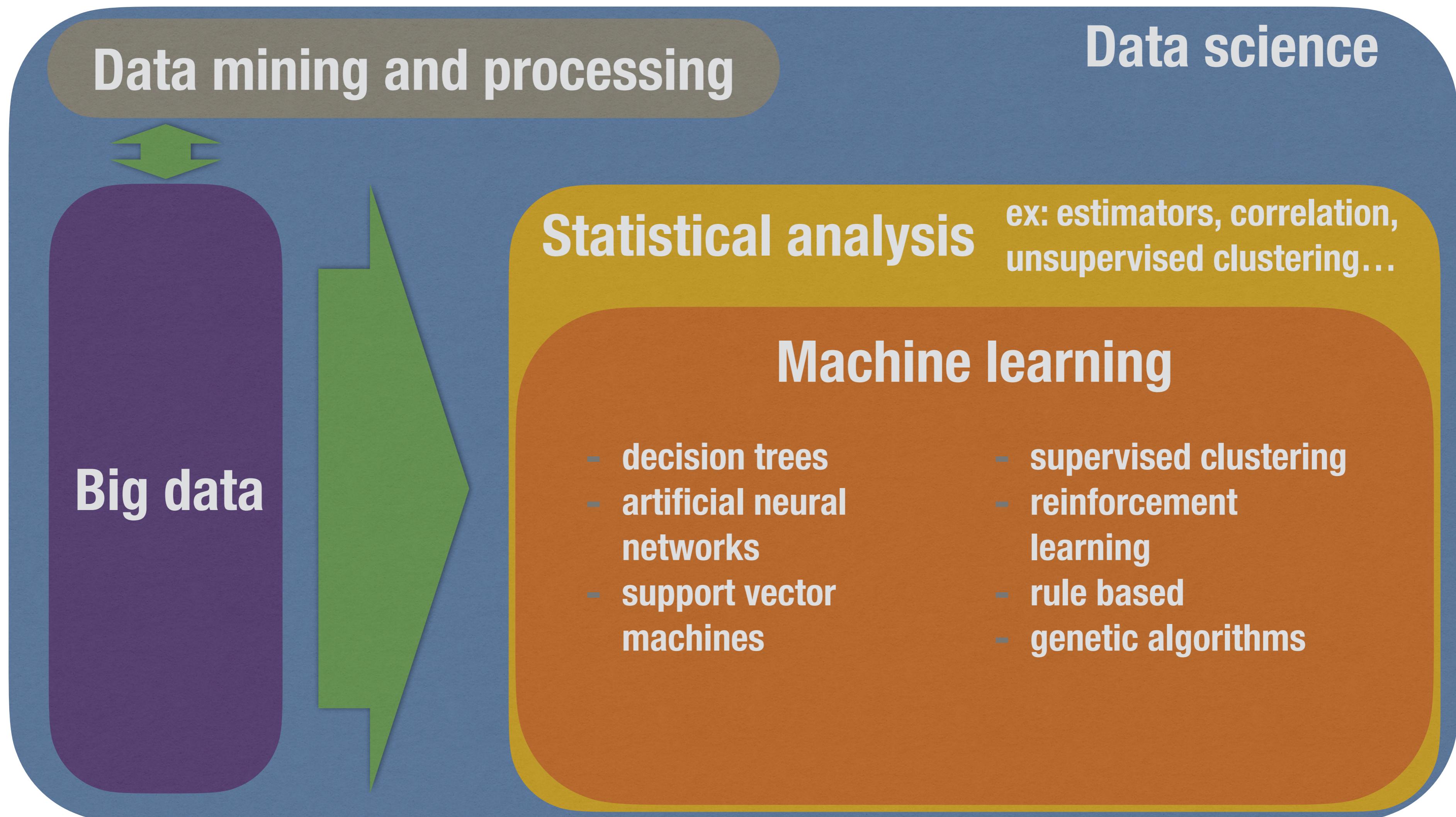
The Data Science landscape

Statistics: The science of collecting, displaying, and analysing data
oxfordreference.com



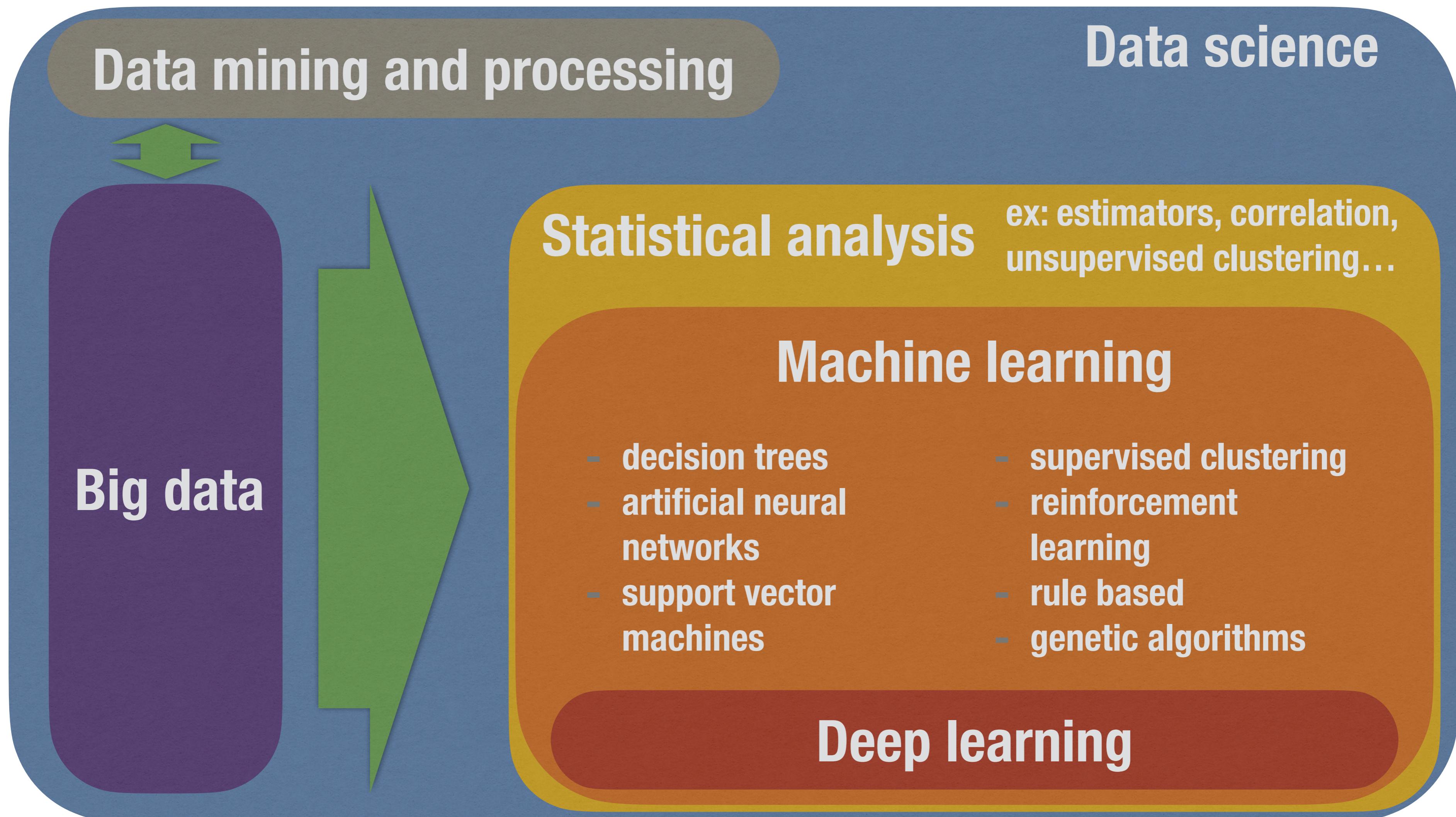
The Data Science landscape

Statistics: The science of collecting, displaying, and analysing data
oxfordreference.com



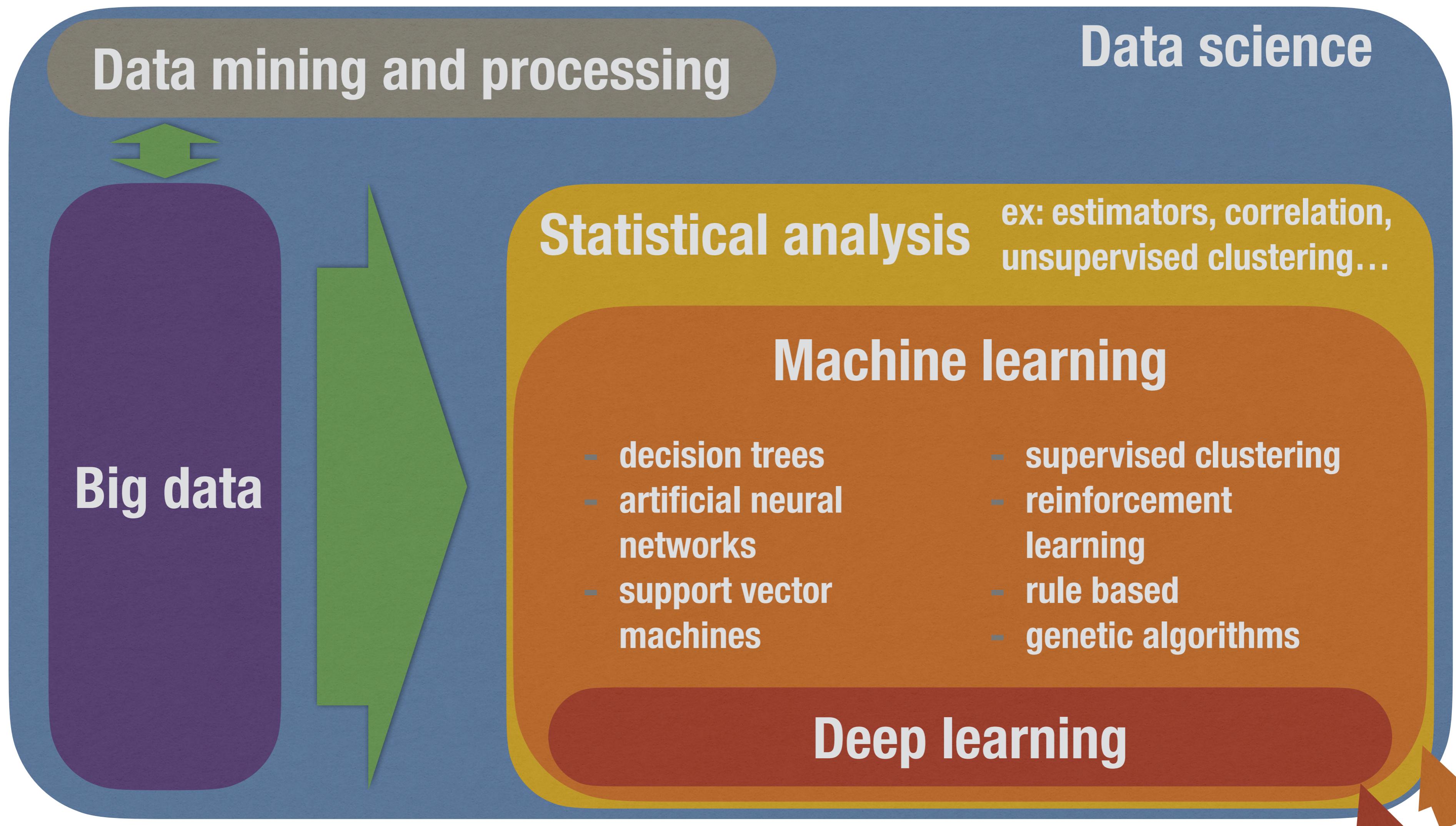
The Data Science landscape

Statistics: The science of collecting, displaying, and analysing data
oxfordreference.com



The Data Science landscape

Statistics: The science of collecting, displaying, and analysing data
oxfordreference.com



What is *learning*?

Multiplication Square										
X	1	2	3	4	5	6	7	8	9	10
1	1	2	3	4	5	6	7	8	9	10
2	2	4	6	8	10	12	14	16	18	20
3	3	6	9	12	15	18	21	24	27	30
4	4	8	12	16	20	24	28	32	36	40
5	5	10	15	20	25	30	35	40	45	50
6	6	12	18	24	30	36	42	48	54	60
7	7	14	21	28	35	42	49	56	63	70
8	8	16	24	32	40	48	56	64	72	80
9	9	18	27	36	45	54	63	72	81	90
10	10	20	30	40	50	60	70	80	90	100

Learn by heart

What is *learning*?



Learn by heart

What is learning?



Learn by heart

$$\begin{aligned}
 & \det[(E_i^{(n)} - E) \delta_{ij} + V_{ij}] = 0, \quad (j=1,2) \\
 & V_j^{(n)} = \int U_i^{(n)*} \hat{V} U_j^{(n)} d\tau_A, \quad \Psi_n^{(n)} = \{\alpha_1^{(n)}, \alpha_2^{(n)}, \dots, \alpha_m^{(n)}\} \\
 & \sum |\alpha_i|_i^2 = 1 \\
 & V_{12} \frac{1}{E^{(1)} - H_2} V_{12}^+ \rightarrow \langle \Phi_2^{(1)} | \cdot \rangle \cdot \frac{1}{E^{(1)} - H_2} V_{12}^+ \\
 & \text{Energy levels: } E_1, E_2 + i\frac{\Gamma_2}{2}, E_2 - i\frac{\Gamma_2}{2} \\
 & \langle \Phi_2^{(1)} | V_{12}^+ \cdot \int dE \frac{1}{E - E'} \frac{1}{E^{(1)} - E'} \cdot \langle \Phi_2^{(1)} | \cdot \rangle \cdot \frac{1}{E - (E_2 + i\frac{\Gamma_2}{2})} \\
 & M_{0 \rightarrow 1} = \langle \Psi_1 | \hat{H}_y | \Psi_1 \rangle + \frac{\langle \Phi_2^{(1)} | V_{12}^+ | U_1 \rangle}{E - (E_2 + i\frac{\Gamma_2}{2})} \langle \Psi_2 | \hat{E}_2^{(1)} | \Psi_1 \rangle \\
 & \langle M_{0 \rightarrow 1} \rangle \sim \frac{1}{4E} \sum \langle \Psi_0 | \hat{D} | \Phi_r^{(1)} \rangle \times
 \end{aligned}$$

Learn abstract concepts

What is learning?



Learn by heart

$$\begin{aligned}
 & \det[(E_i^{(n)} - E) \delta_{ij} + V_{ij}] = 0, \quad (j=1,2) \\
 & V_j^{(n)} = \int U_i^{(n)*} \hat{V} U_j^{(n)} d\tau_A, \quad \Psi_n^{(n)} = \{\alpha_1^{(n)}, \alpha_2^{(n)}, \dots, \alpha_m^{(n)}\} \\
 & \sum |\alpha_i|_2^2 = 1 \\
 & V_{12} \frac{1}{E^{(1)} - H_2} V_{12}^+ \rightarrow \langle \Phi_2^{(1)} | \cdot \rangle \cdot \frac{1}{E^{(1)} - H_2} \\
 & \text{Energy levels: } E_1, E_2, E_1 + \frac{R_2}{2}, E_2 - \frac{R_2}{2} \\
 & \langle \Phi_2^{(1)} | V_{12}^+ | U_1 \rangle = \frac{V_{12} \Phi_2^{(1)} \times \Phi_1^{(1)}}{E - (E_2 + \frac{R_2}{2})} \\
 & M_{0 \rightarrow 1} = \langle \Psi_{U_1} | H_y | \Psi_1 \rangle + \frac{\langle \Phi_2^{(1)} | V_{12}^+ | U_1 \rangle}{E - (E_2 + \frac{R_2}{2})} \langle \Psi_2 | H_y | \Psi_1 \rangle \\
 & \langle M_{0 \rightarrow 1} \rangle \sim \frac{1}{AE} \sum \langle \Psi_0 | \hat{D} | \Phi_r^{(1)} \rangle \times
 \end{aligned}$$

Learn abstract concepts

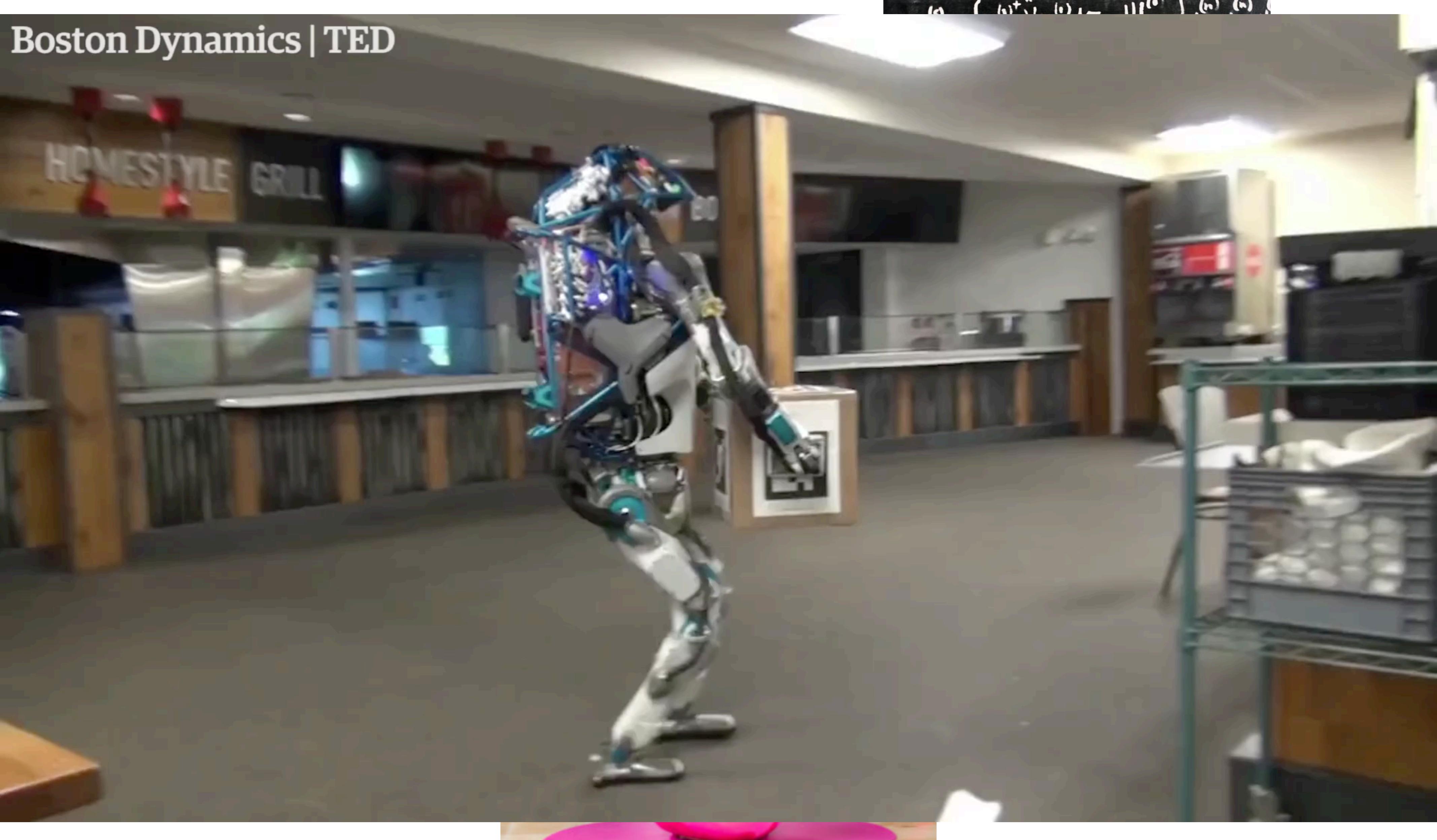


Learn motor skills

What is learning?

Boston Dynamics | TED

$$\det[(E_i^{(n)} - E) \delta_{ij} + V_{ij}] = 0, \quad i, j = 1, 2, \dots, n$$



Learn motor skills

How about machine learning?

At its heart: *Bayesian Inference*:
(just like humans! [1])

Hypothesis H
Evidence E

$$P(H|E) \propto P(E|H) \cdot P(H)$$

[1] Dehaene, S. (2020). How We Learn: Why Brains Learn Better Than Any Machine... for Now. Penguin.

How about machine learning?

At its heart: *Bayesian Inference*:
(just like humans! [1])

Hypothesis H
Evidence E

$$P(H|E) \propto P(E|H) \cdot \underline{P(H)}$$

Prior

[1] Dehaene, S. (2020). How We Learn: Why Brains Learn Better Than Any Machine... for Now. Penguin.

How about machine learning?

At its heart: *Bayesian Inference*:
(just like humans! [1])

Hypothesis H
Evidence E

$$P(H|E) \propto \frac{P(E|H) \cdot P(H)}{\text{Likelihood} \quad \text{Prior}}$$

[1] Dehaene, S. (2020). How We Learn: Why Brains Learn Better Than Any Machine... for Now. Penguin.

How about machine learning?

At its heart: *Bayesian Inference*:
(just like humans! [1])

Hypothesis H
Evidence E

$$\frac{P(H|E)}{\text{Posterior}} \propto \frac{P(E|H) \cdot P(H)}{\text{Likelihood} \quad \text{Prior}}$$

[1] Dehaene, S. (2020). How We Learn: Why Brains Learn Better Than Any Machine... for Now. Penguin.

How about machine learning?

At its heart: *Bayesian Inference*:
(just like humans! [1])

Hypothesis H
Evidence E

$$\frac{P(H|E)}{\text{Posterior}} \propto \frac{P(E|H) \cdot P(H)}{\text{Likelihood} \quad \text{Prior}}$$

- Procedure:
 - Choose **Prior** (e.g. « linear relation »)
 - Compute **Likelihood**
 - Evaluate **Posterior**
 - Repeat (with new **Prior**)
- *Prior beliefs (H)* are **updated** according to **evidence (E)**, using Bayes' rule

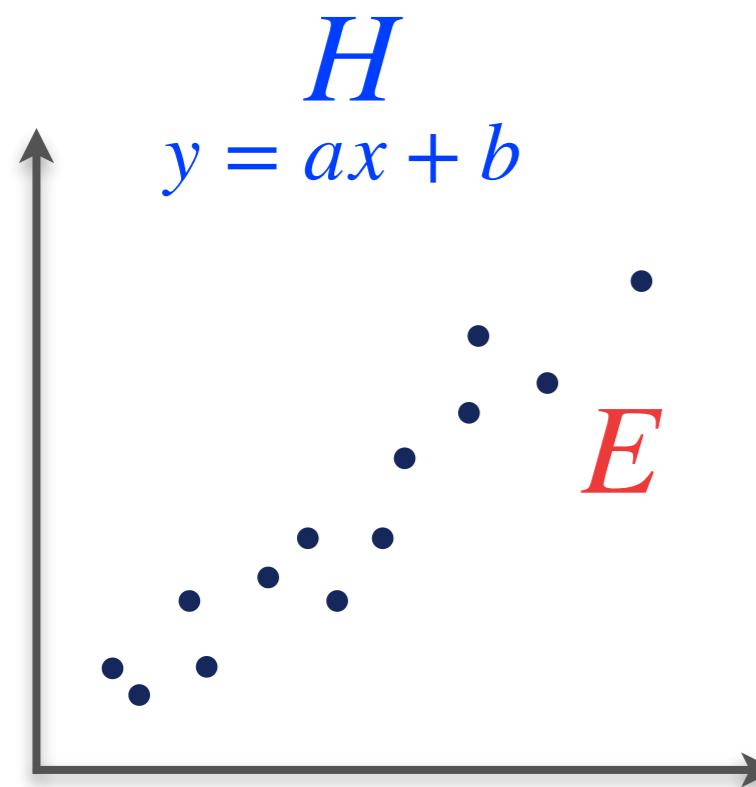
[1] Dehaene, S. (2020). How We Learn: Why Brains Learn Better Than Any Machine... for Now. Penguin.

How about machine learning?

Often called « glorified curve-fitting »

Objective: find the prior beliefs (H) that lead to the best posterior

$$P(H | E)$$



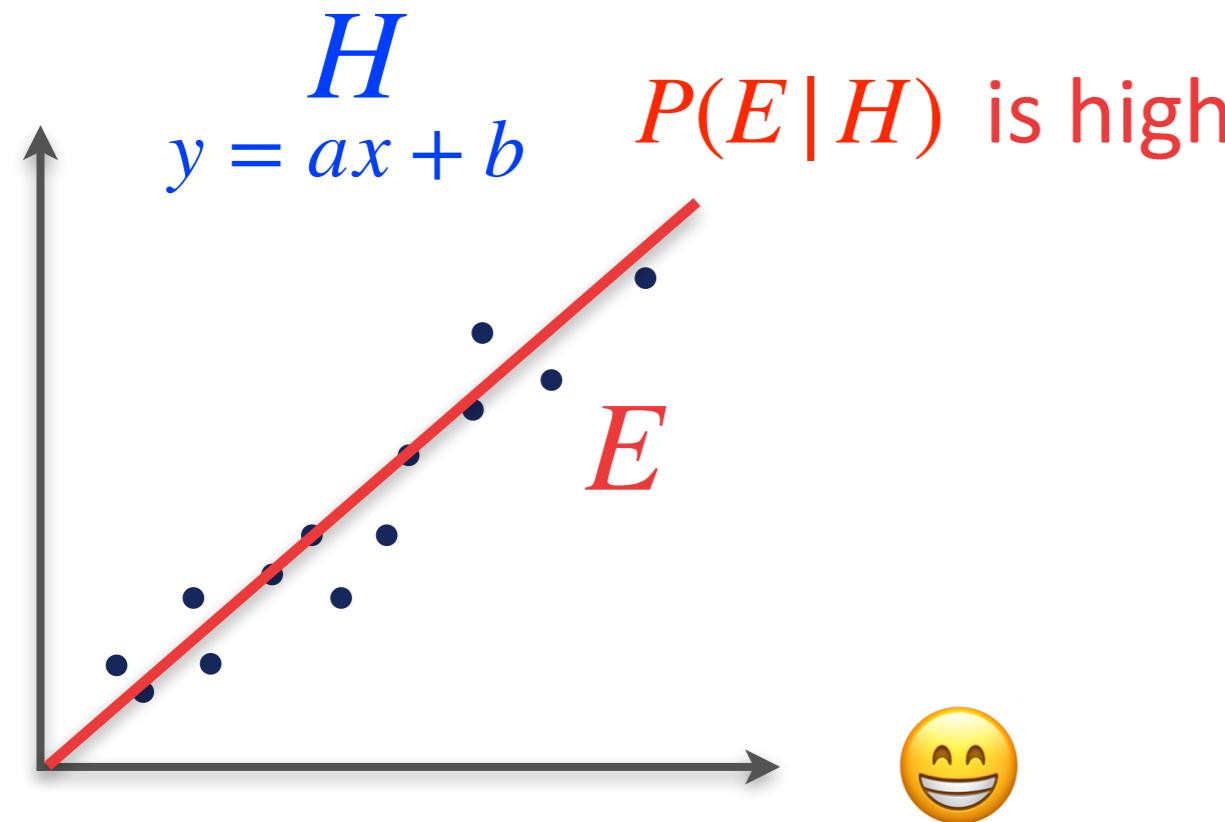
[1] Wolpert, David H. "The lack of a priori distinctions between learning algorithms." Neural computation 8.7 (1996): 1341-1390.

How about machine learning?

Often called « glorified curve-fitting »

Objective: find the prior beliefs (H) that lead to the best posterior

$$P(H|E)$$



Conclusion: my **hypothesis** is supported by the **data**, so I'm now **more confident** in it

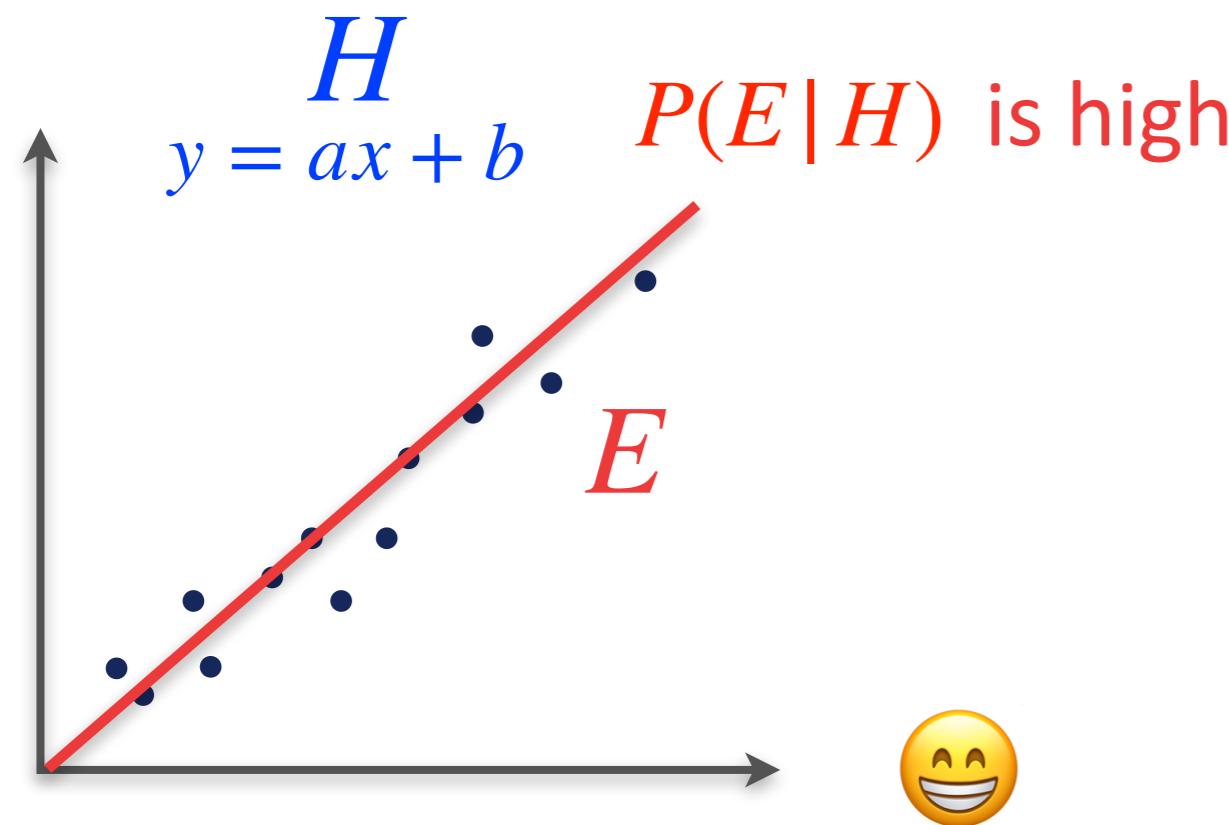
[1] Wolpert, David H. "The lack of a priori distinctions between learning algorithms." Neural computation 8.7 (1996): 1341-1390.

How about machine learning?

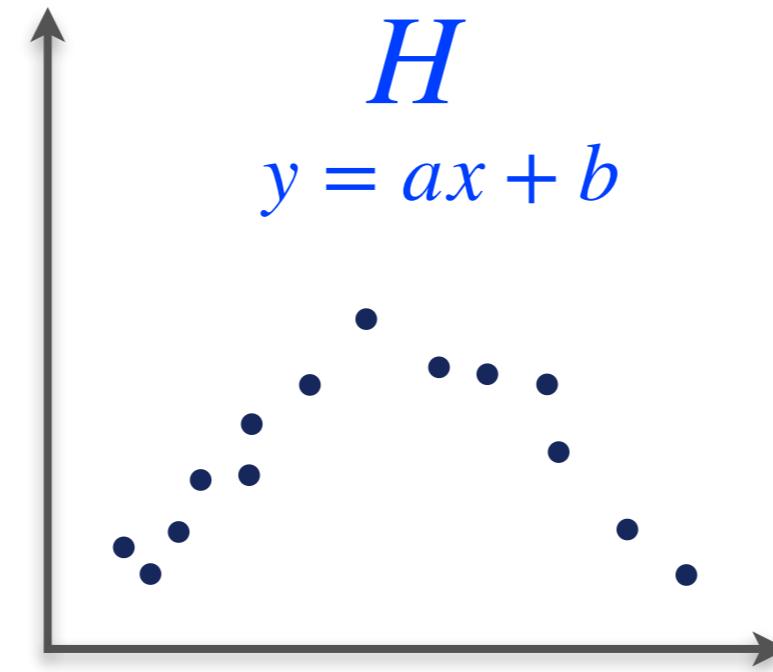
Often called « glorified curve-fitting »

Objective: find the prior beliefs (H) that lead to the best posterior

$$P(H|E)$$



Conclusion: my **hypothesis** is supported by the **data**, so I'm now **more confident** in it



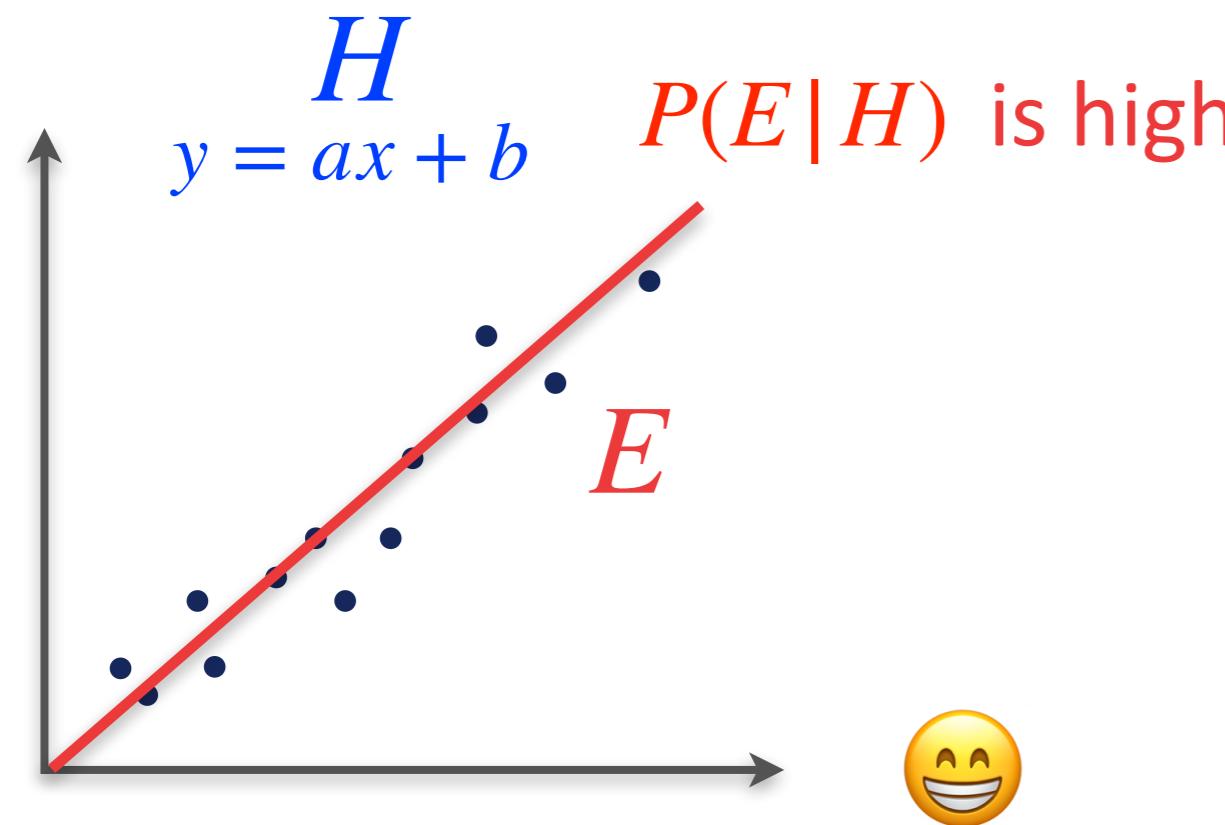
[1] Wolpert, David H. "The lack of a priori distinctions between learning algorithms." *Neural computation* 8.7 (1996): 1341-1390.

How about machine learning?

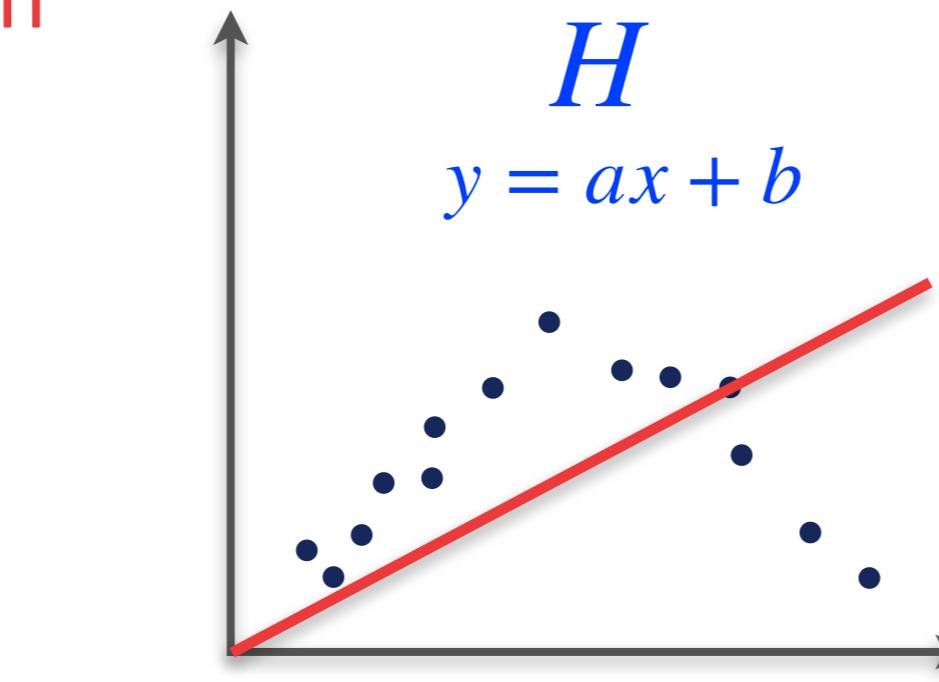
Often called « glorified curve-fitting »

Objective: find the prior beliefs (H) that lead to the best posterior

$$P(H|E)$$



Conclusion: my **hypothesis** is supported by the **data**, so I'm now **more confident** in it



Conclusion:
The **data** doesn't support **H**

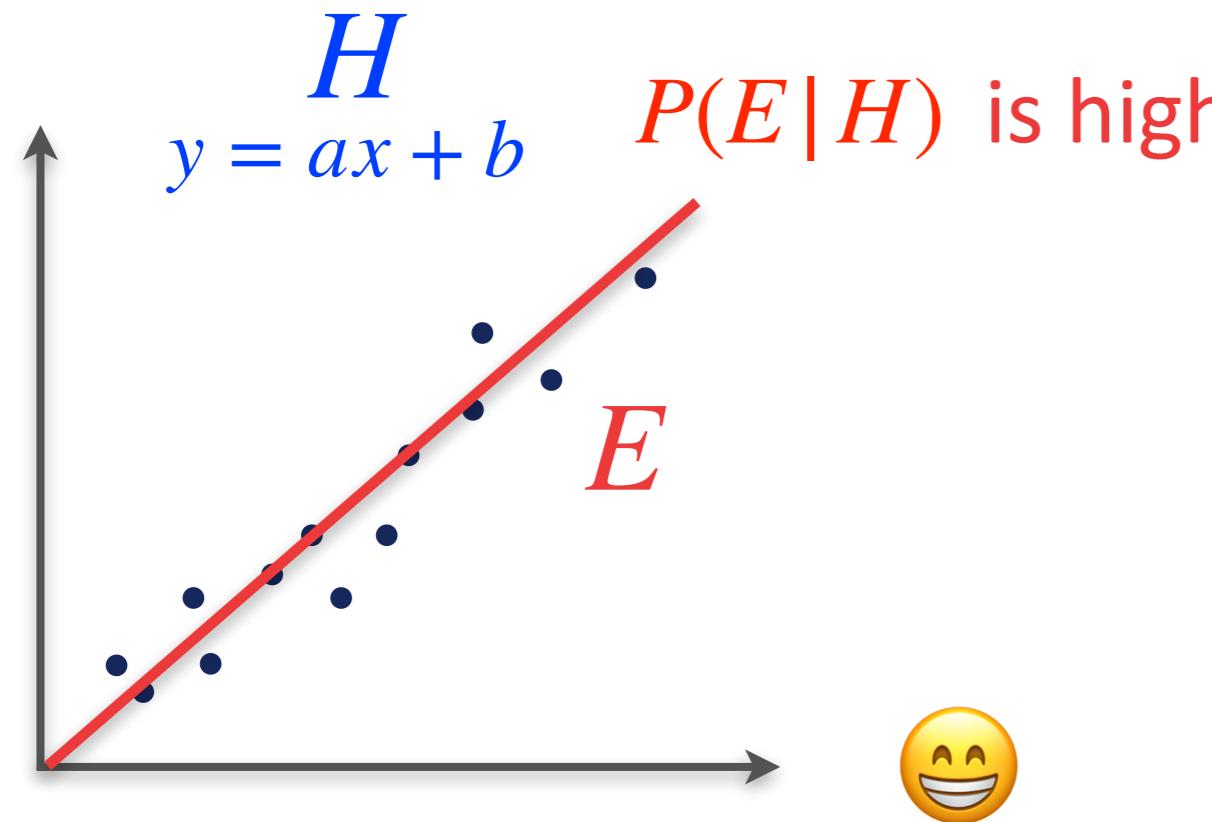
[1] Wolpert, David H. "The lack of a priori distinctions between learning algorithms." Neural computation 8.7 (1996): 1341-1390.

How about machine learning?

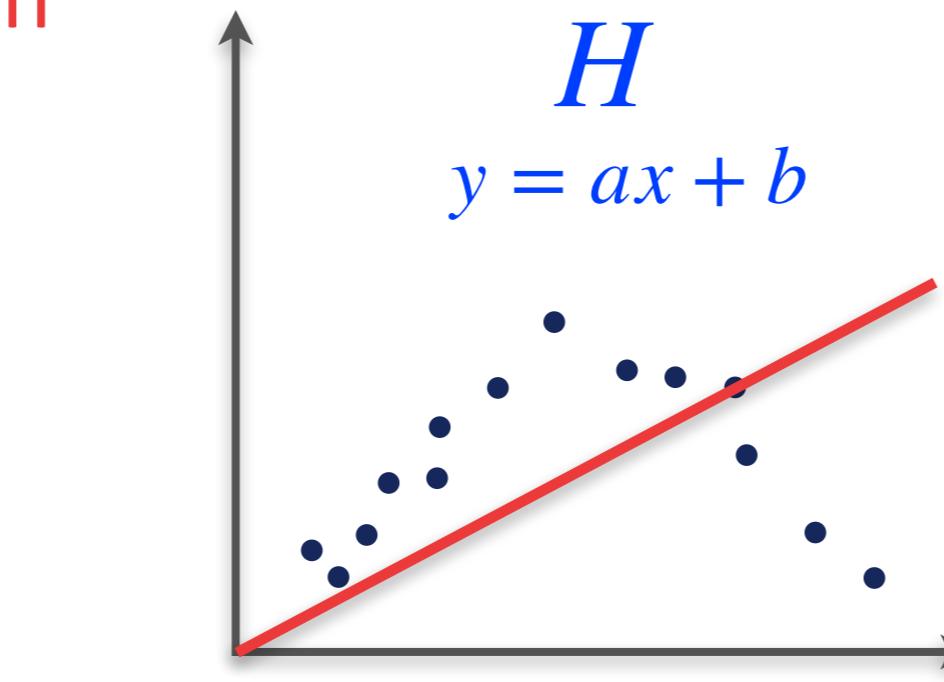
Often called « glorified curve-fitting »

Objective: find the prior beliefs (H) that lead to the best posterior

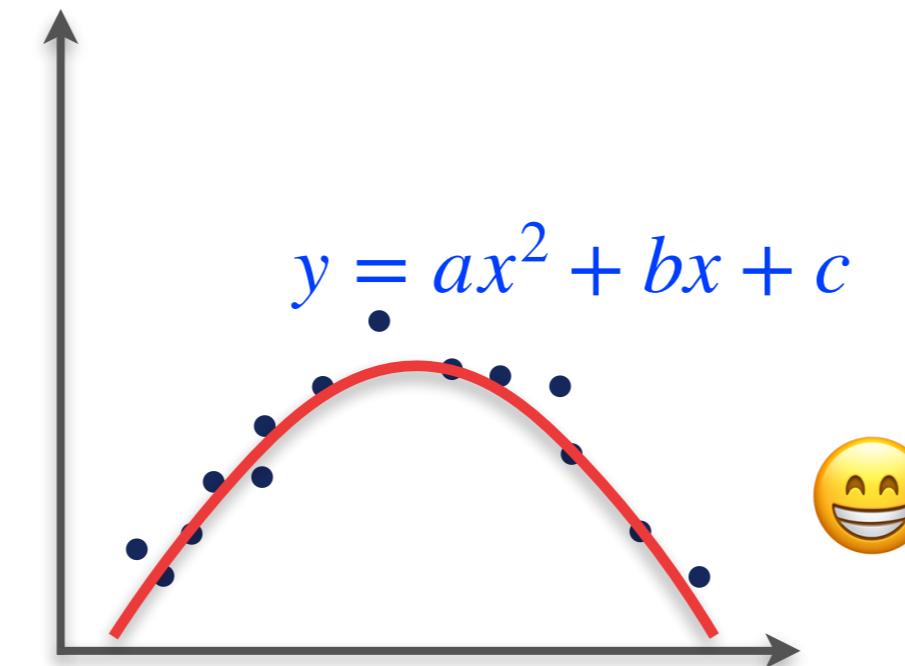
$$P(H|E)$$



Conclusion: my **hypothesis** is supported by the **data**, so I'm now **more confident** in it



The no-free lunch theorem [1]
« there are no a priori distinctions between learning algorithms »



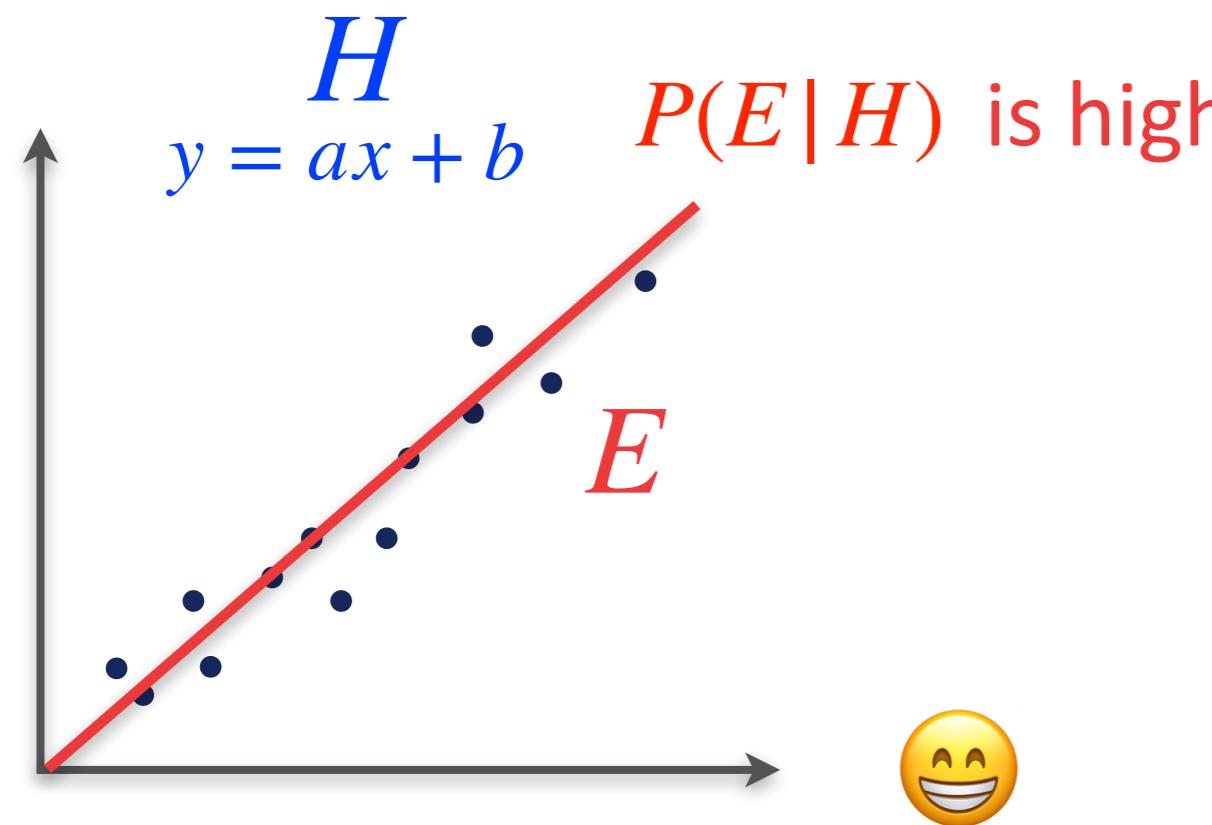
[1] Wolpert, David H. "The lack of a priori distinctions between learning algorithms." Neural computation 8.7 (1996): 1341-1390.

How about machine learning?

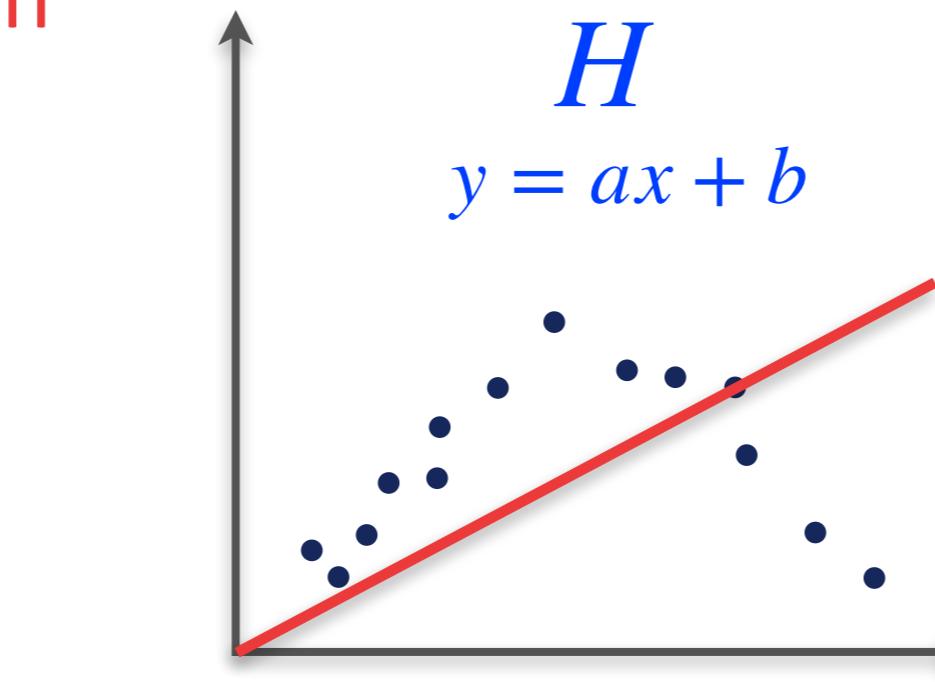
Often called « glorified curve-fitting »

Objective: find the prior beliefs (H) that lead to the best posterior

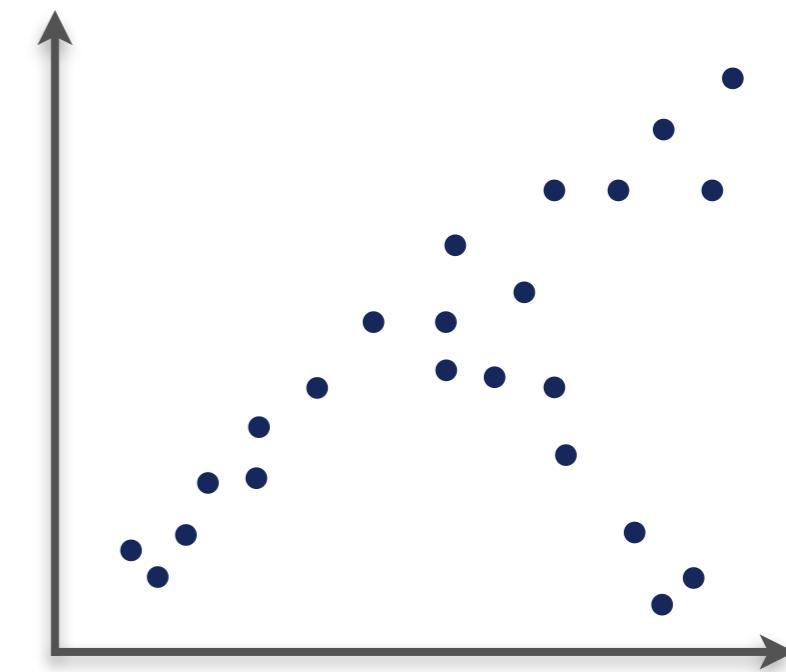
$$P(H|E)$$



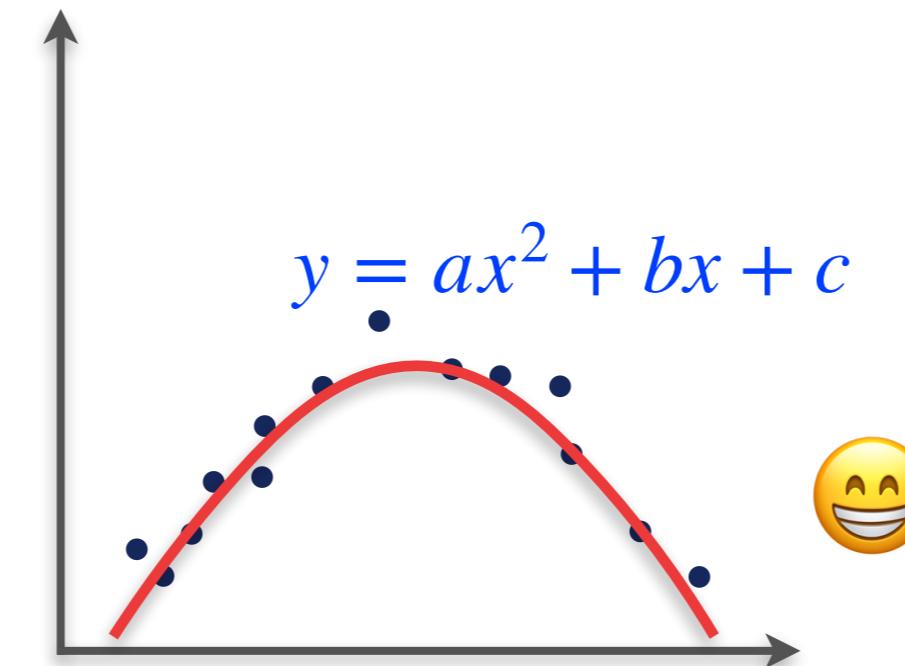
Conclusion: my **hypothesis** is supported by the **data**, so I'm now **more confident** in it



Conclusion:
The **data** doesn't support **H**



The no-free lunch theorem [1]
« there are no a priori distinctions between learning algorithms »



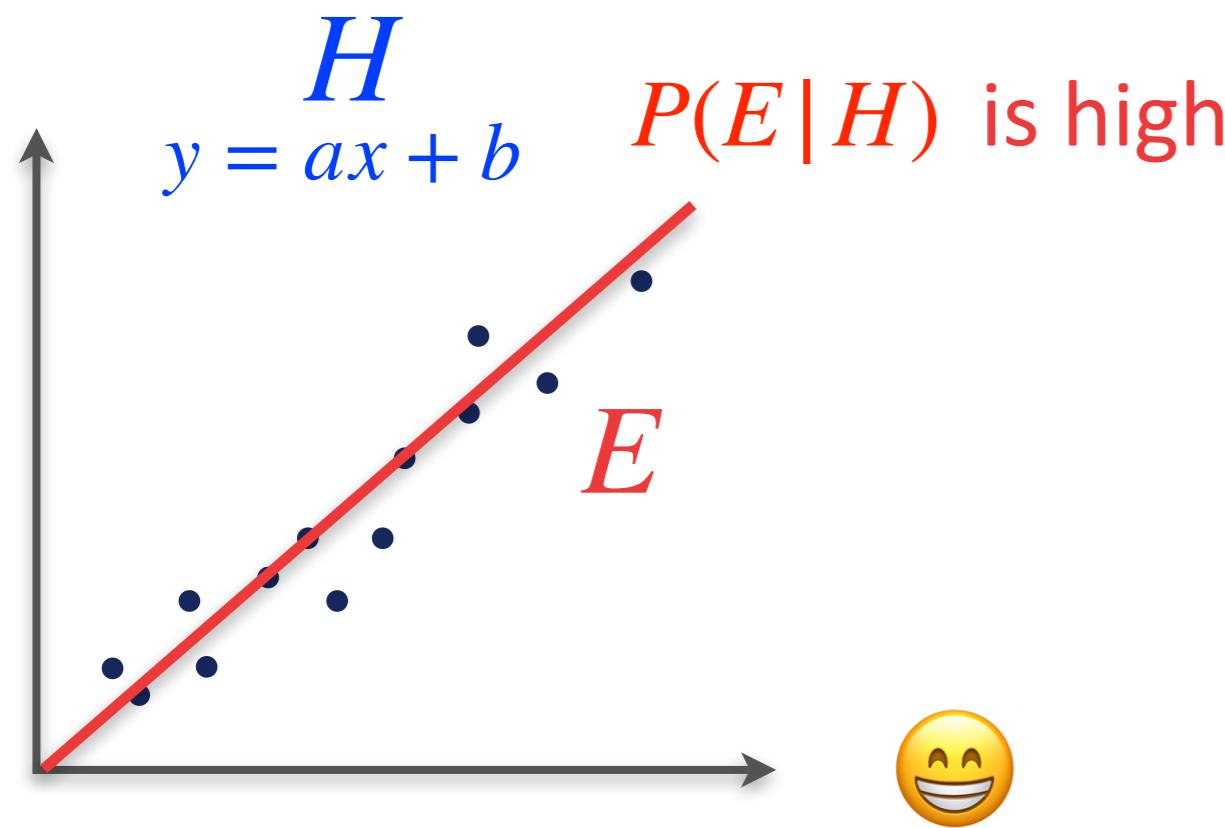
[1] Wolpert, David H. "The lack of a priori distinctions between learning algorithms." Neural computation 8.7 (1996): 1341-1390.

How about machine learning?

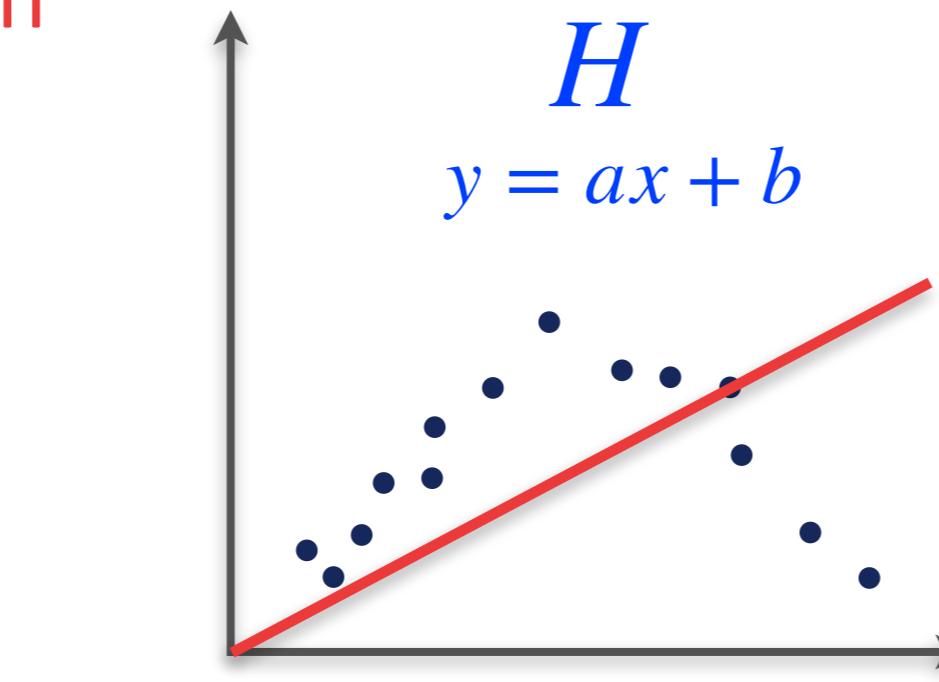
Often called « glorified curve-fitting »

Objective: find the prior beliefs (H) that lead to the best posterior

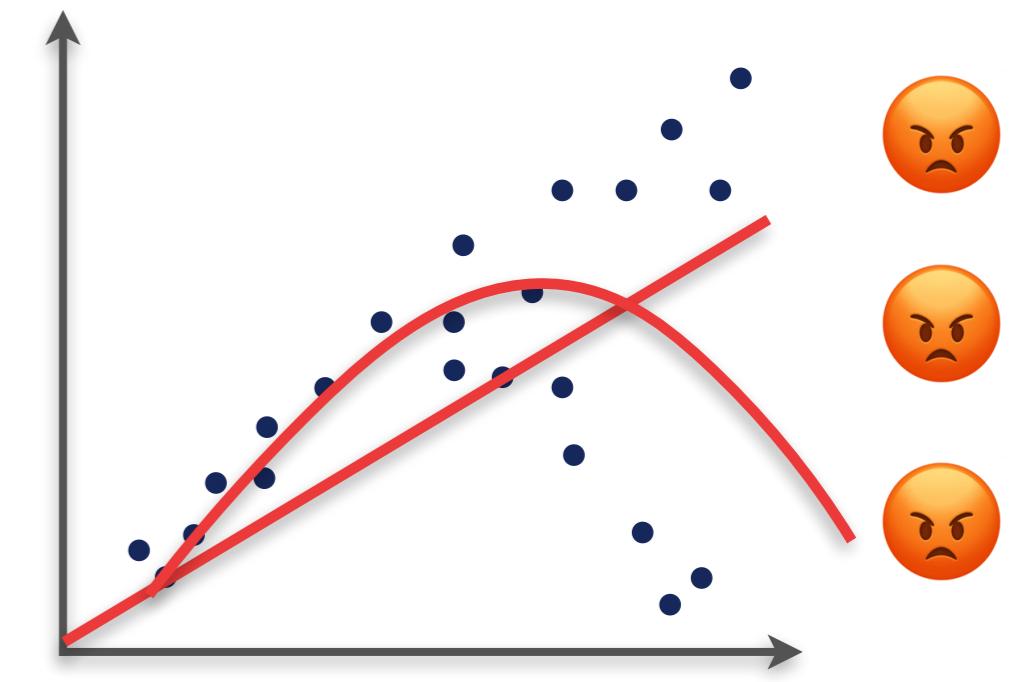
$$P(H|E)$$



Conclusion: my **hypothesis** is supported by the **data**, so I'm now **more confident** in it

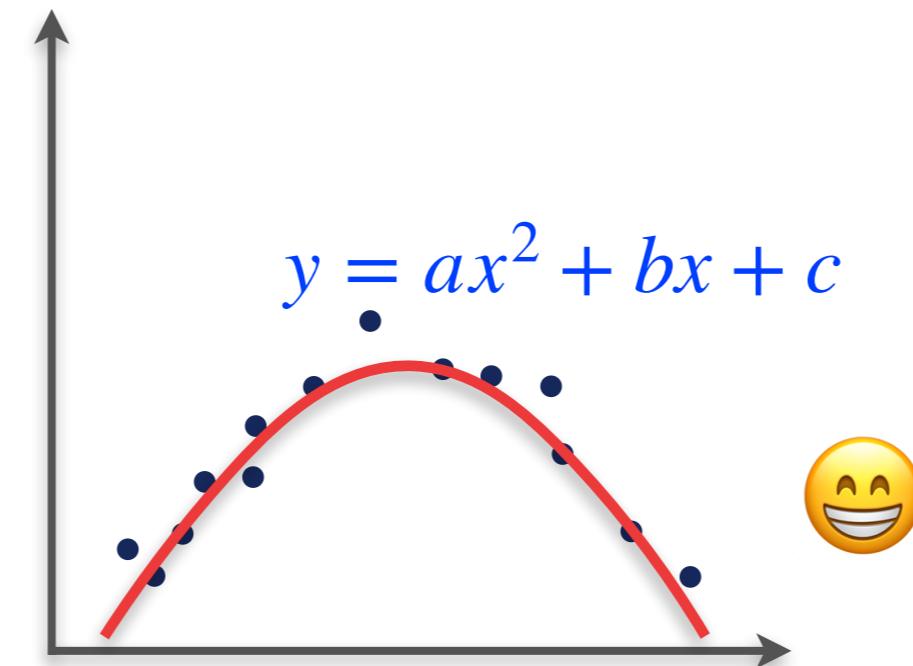


Conclusion:
The **data** doesn't support **H**



Conclusion:
Nothing works!

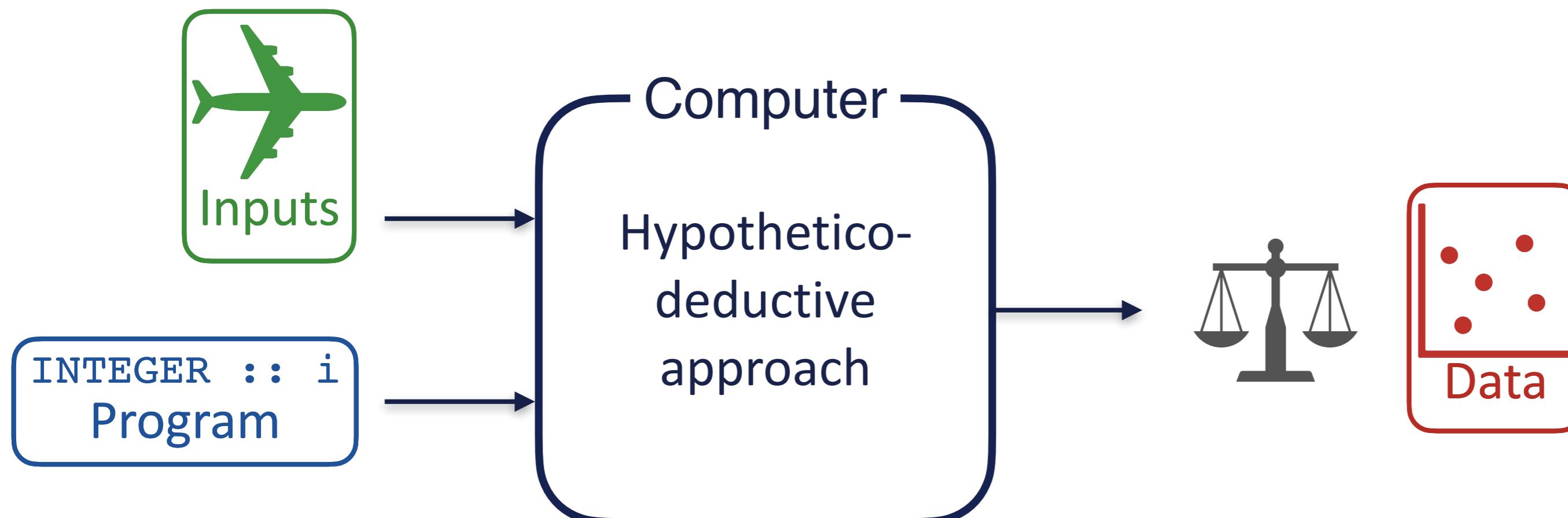
The no-free lunch theorem [1]
« there are no a priori distinctions between learning algorithms »



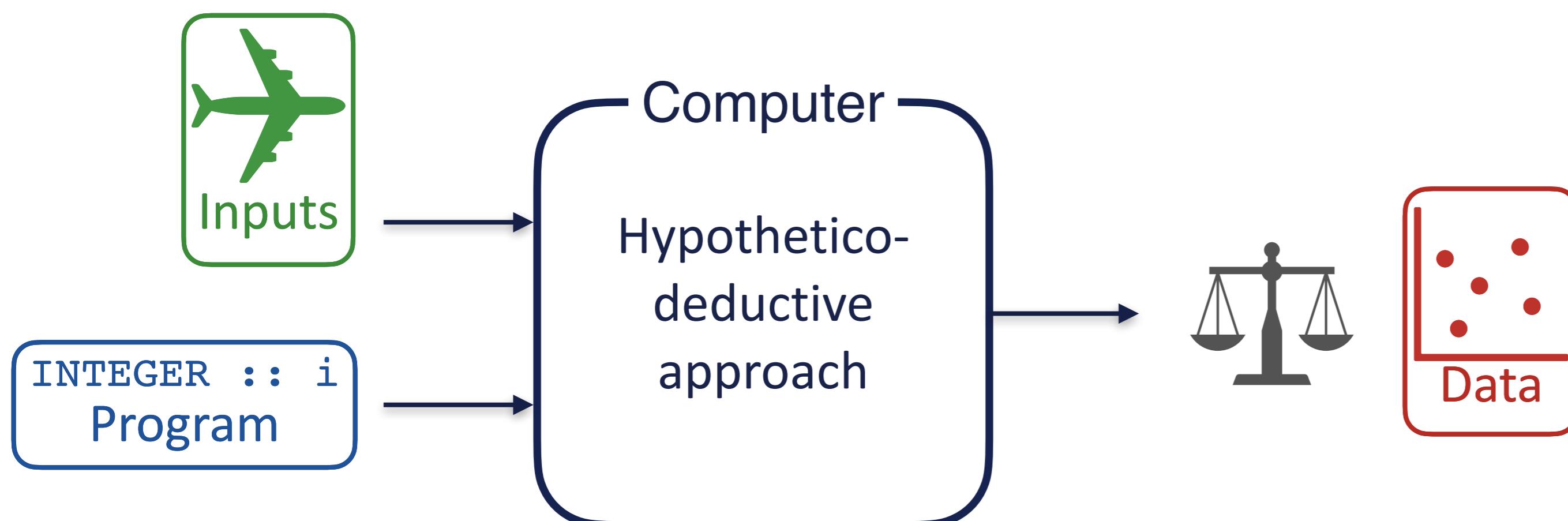
Some problems are ill-posed:
There is a fundamental ambiguity that cannot be resolved

[1] Wolpert, David H. "The lack of a priori distinctions between learning algorithms." Neural computation 8.7 (1996): 1341-1390.

Learning: a paradigm shift

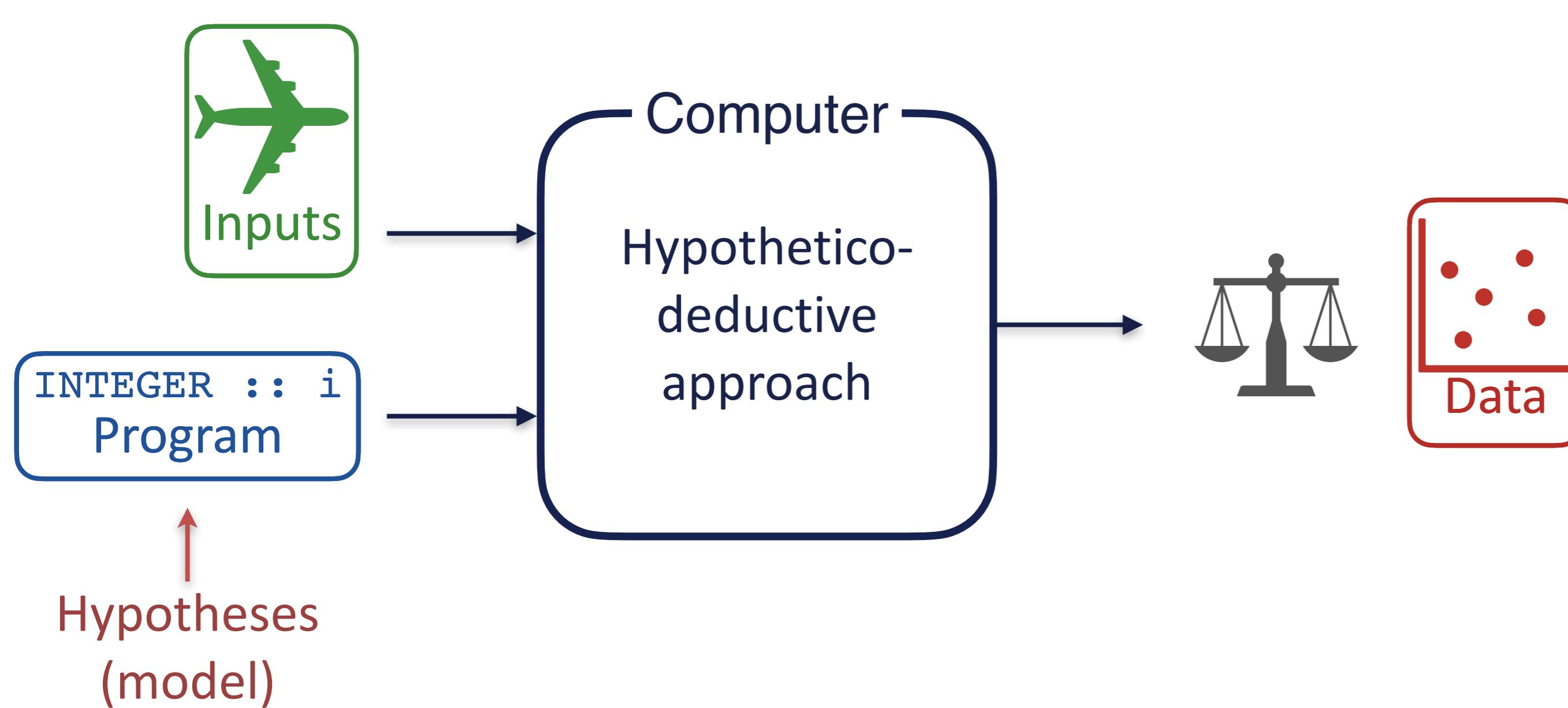


Learning: a paradigm shift



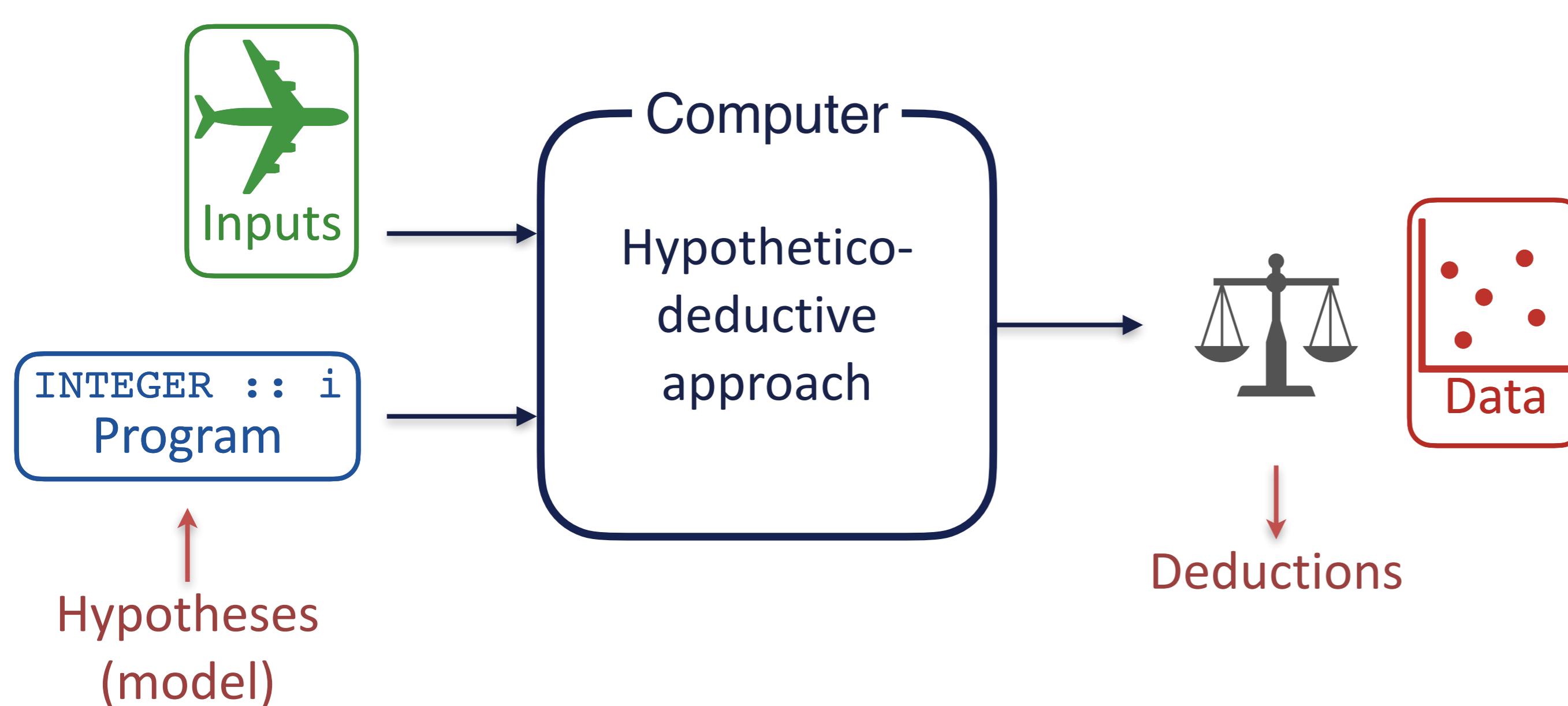
The scientific method is historically a deductive approach. **The data validates the model.**

Learning: a paradigm shift



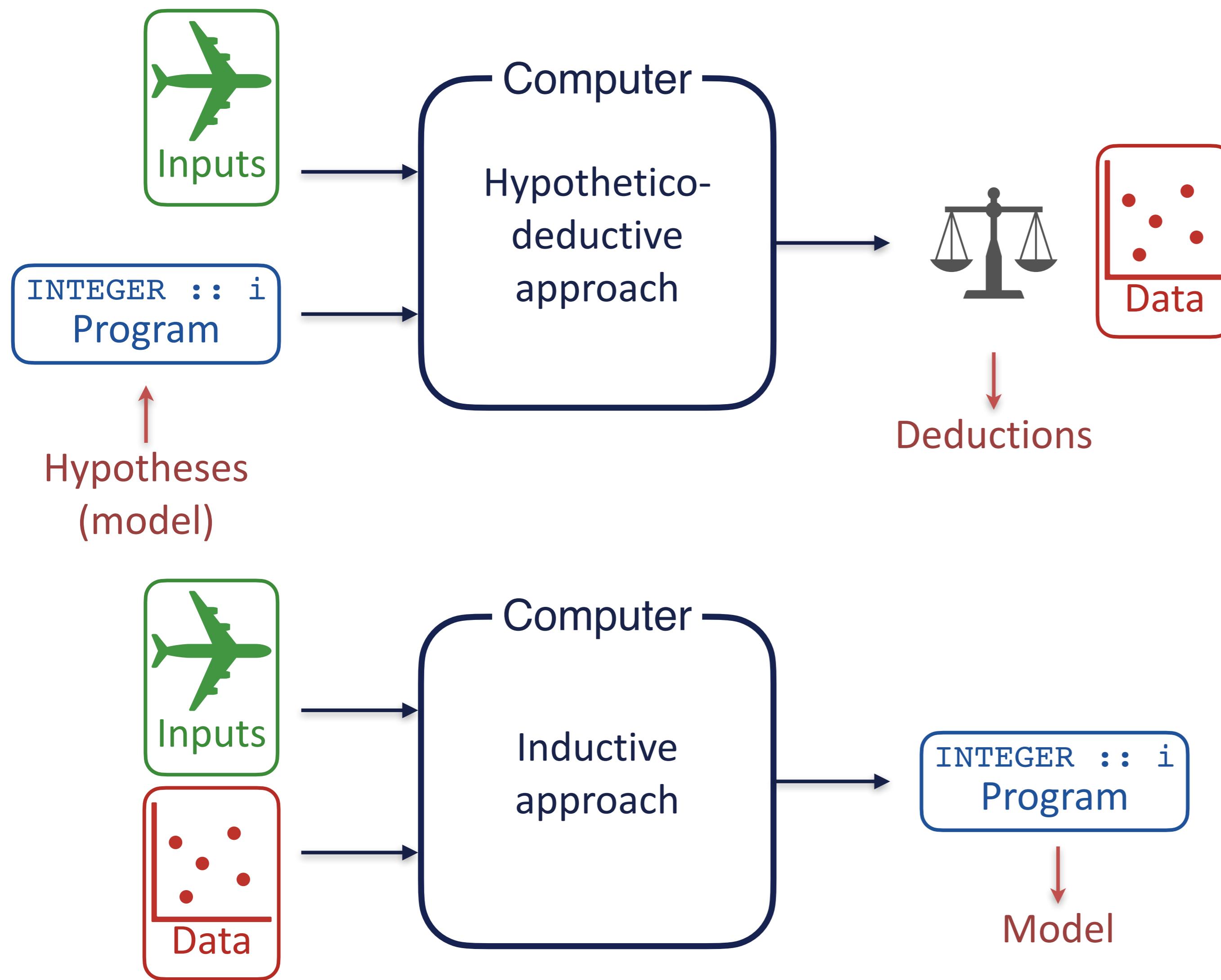
The scientific method is historically a deductive approach. **The data validates the model.**

Learning: a paradigm shift



The scientific method is historically a deductive approach. **The data validates the model.**

Learning: a paradigm shift



The scientific method is historically a deductive approach. **The data validates the model.**

Data-driven approaches are *inductive*. **The model is the output.**

Uses of AI



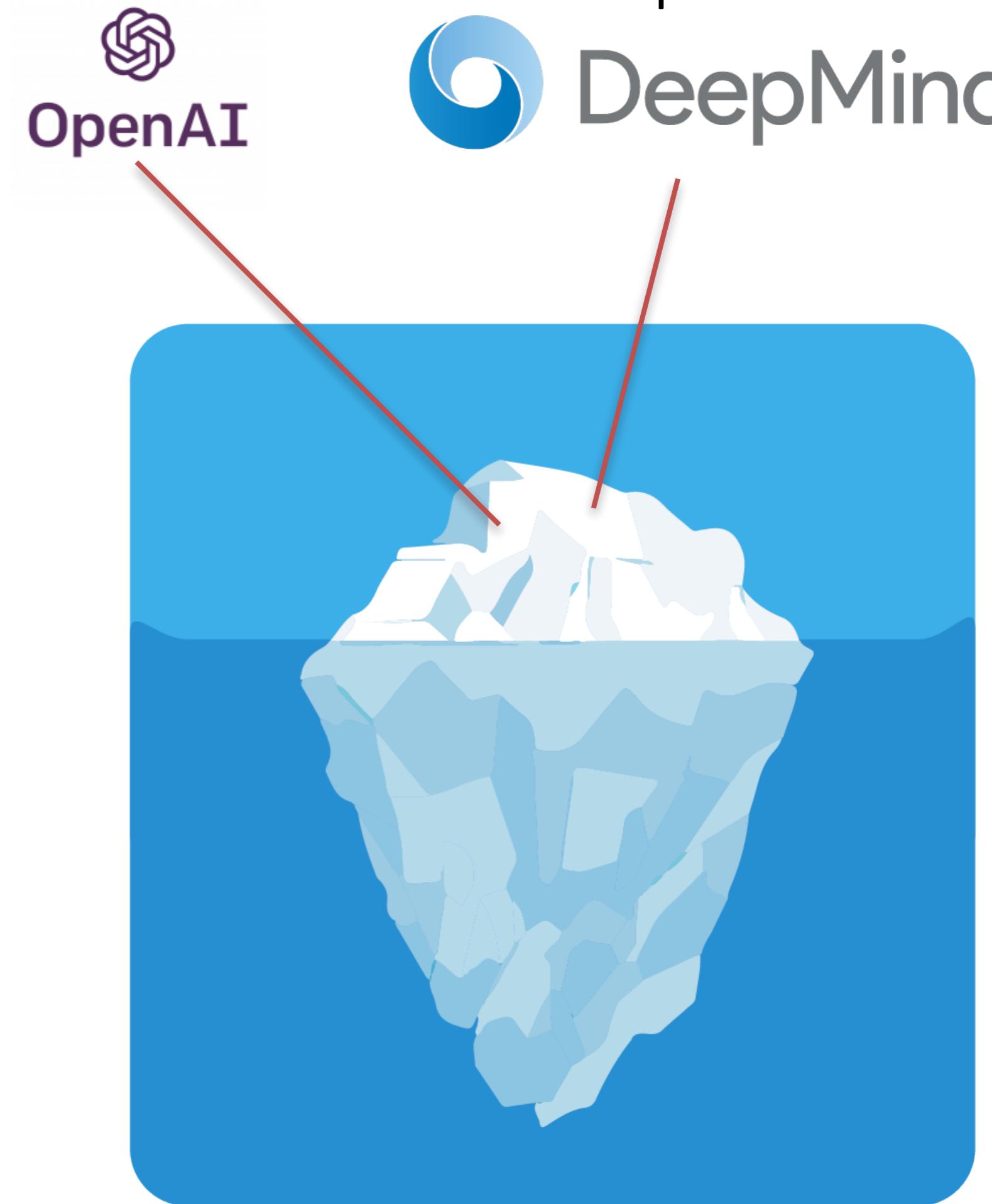
Uses of AI



- Shiny « superhuman » algorithms make headlines

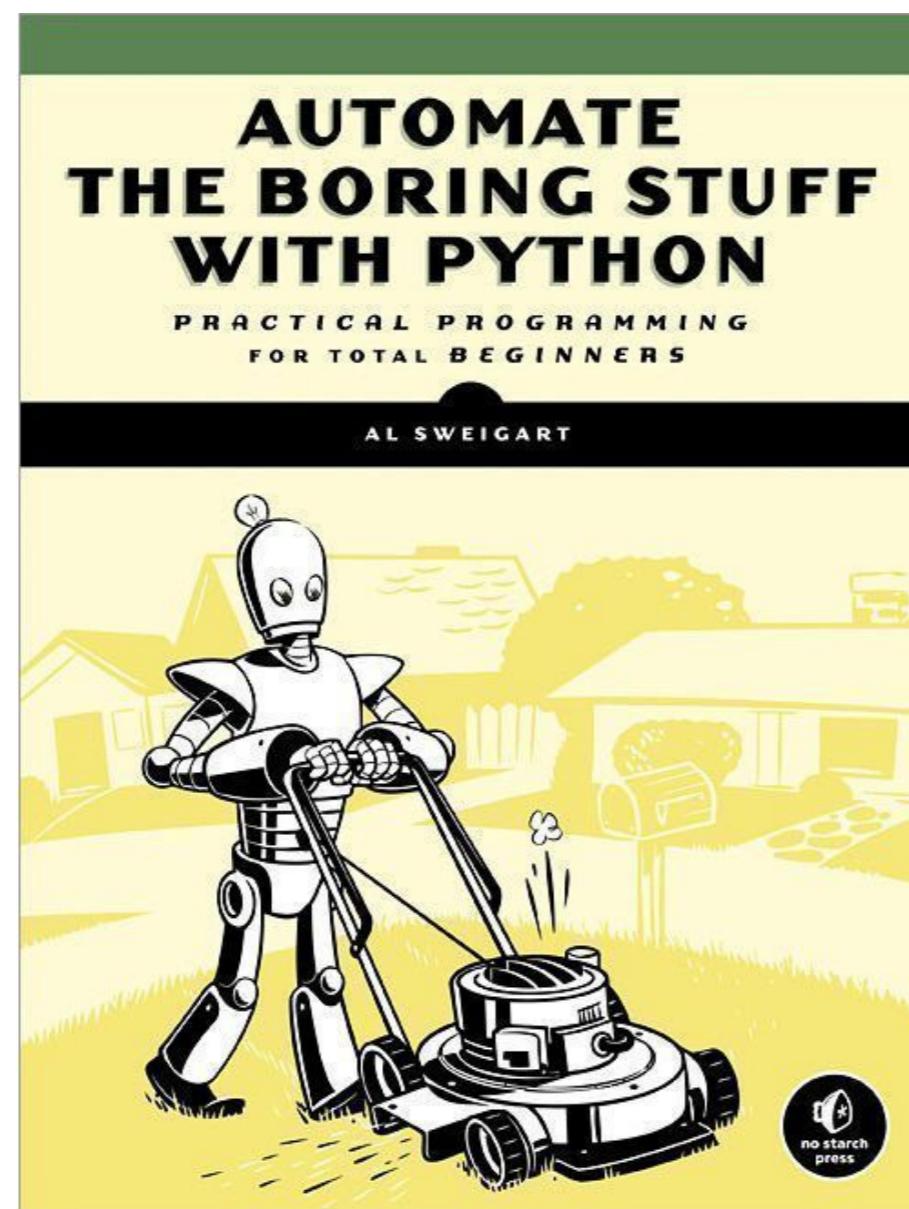
Uses of AI

- Shiny « superhuman » algorithms make headlines



Uses of AI

- Shiny « superhuman » algorithms make headlines
- But most applications « automate the boring stuff ».

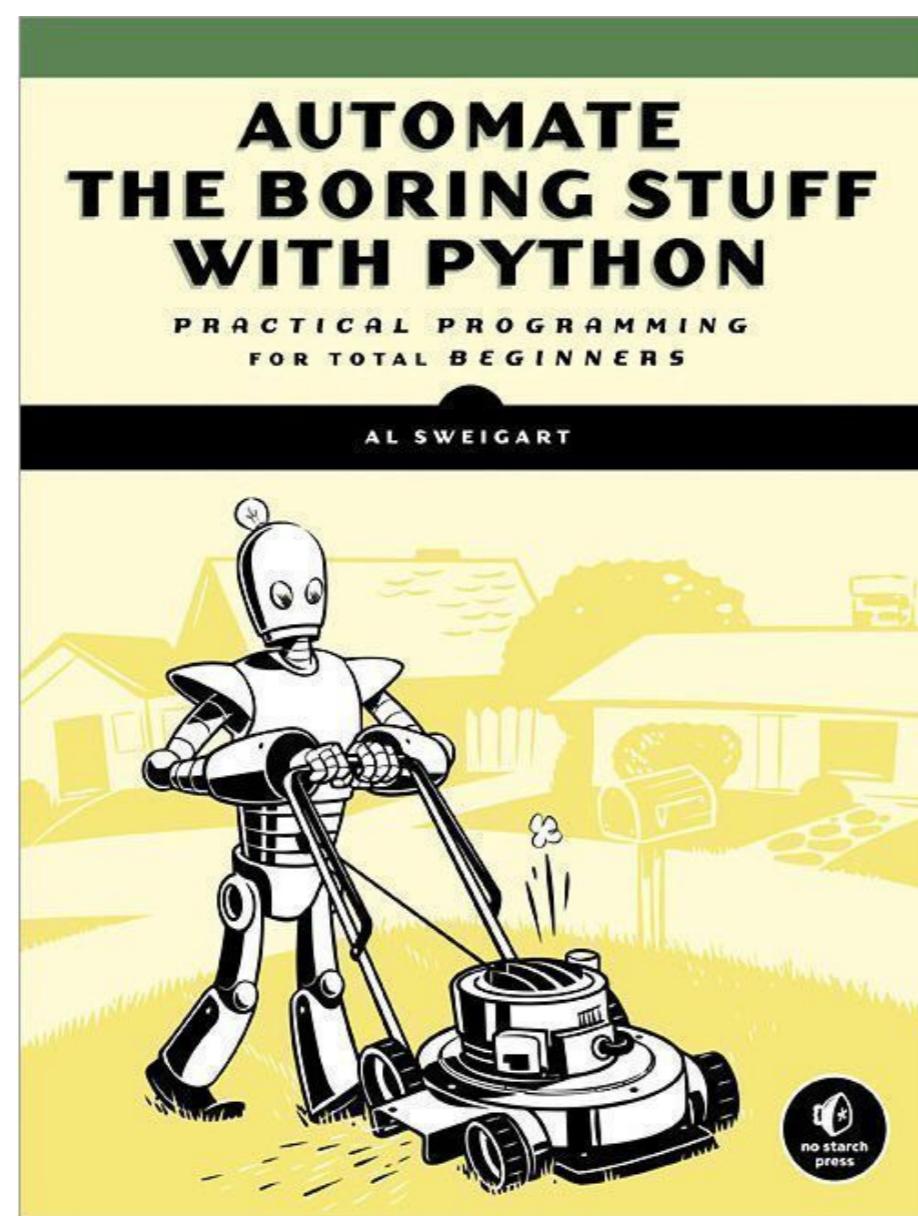


Just like
regular
programming
does!

Uses of AI

- Shiny « superhuman » algorithms make headlines
- But most applications « automate the boring stuff ».

Just like regular programming does!



DeepMind



300 Million
Images / Day
+ ...



100 Billion
Words / Day
+ ...



+ ...

Intelligence vs Experience

- One definition of intelligence:
(from F. Chollet)
$$\text{Intelligence} = \frac{\text{Skill}}{\text{Experience}}$$



¹: Silver, D., Hubert, T., Schrittwieser, J., Antonoglou, I., Lai, M., Guez, A., ... & Lillicrap, T. (2017). Mastering chess and shogi by self-play with a general reinforcement learning algorithm.

Intelligence vs Experience

- One definition of intelligence: (from F. Chollet)
$$\text{Intelligence} = \frac{\text{Skill}}{\text{Experience}}$$



¹: Silver, D., Hubert, T., Schrittwieser, J., Antonoglou, I., Lai, M., Guez, A., ... & Lillicrap, T. (2017). Mastering chess and shogi by self-play with a general reinforcement learning algorithm.

Intelligence vs Experience

- One definition of intelligence:
(from F. Chollet)
$$\text{Intelligence} = \frac{\text{Skill}}{\text{Experience}}$$

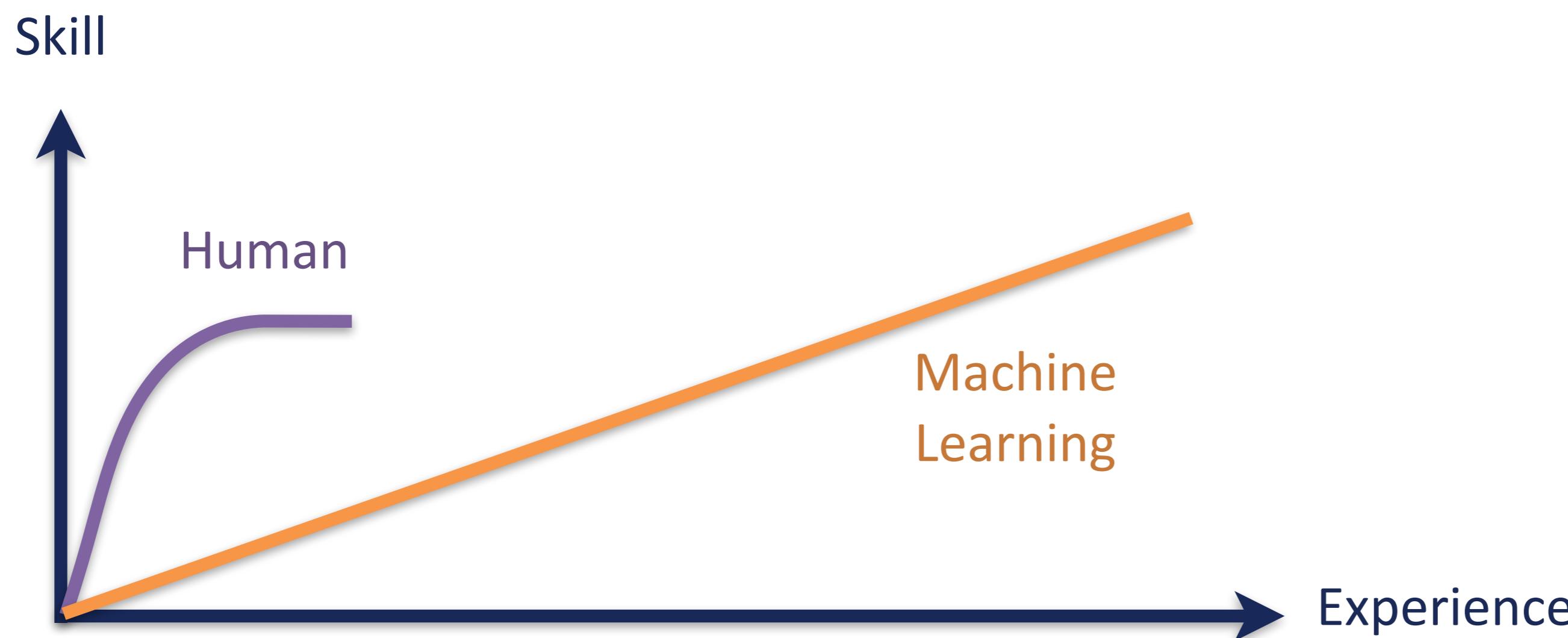


¹: Silver, D., Hubert, T., Schrittwieser, J., Antonoglou, I., Lai, M., Guez, A., ... & Lillicrap, T. (2017). Mastering chess and shogi by self-play with a general reinforcement learning algorithm.

Intelligence vs Experience

- One definition of intelligence:
(from F. Chollet)

$$\text{Intelligence} = \frac{\text{Skill}}{\text{Experience}}$$



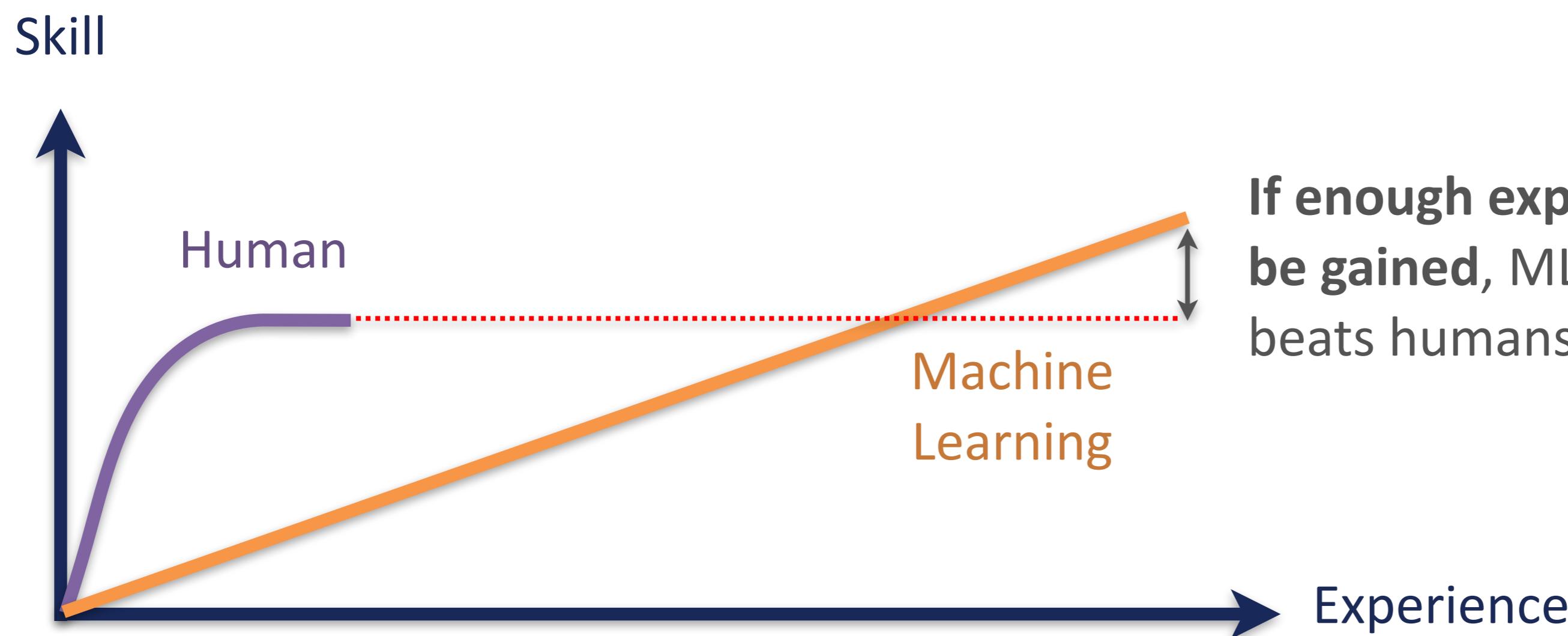
Alpha Zero¹ needs 21 Million
games of Go during training
but
training takes ≈24h

¹: Silver, D., Hubert, T., Schrittwieser, J., Antonoglou, I., Lai, M., Guez, A., ... & Lillicrap, T. (2017). Mastering chess and shogi by self-play with a general reinforcement learning algorithm.

Intelligence vs Experience

- One definition of intelligence:
(from F. Chollet)

$$\text{Intelligence} = \frac{\text{Skill}}{\text{Experience}}$$



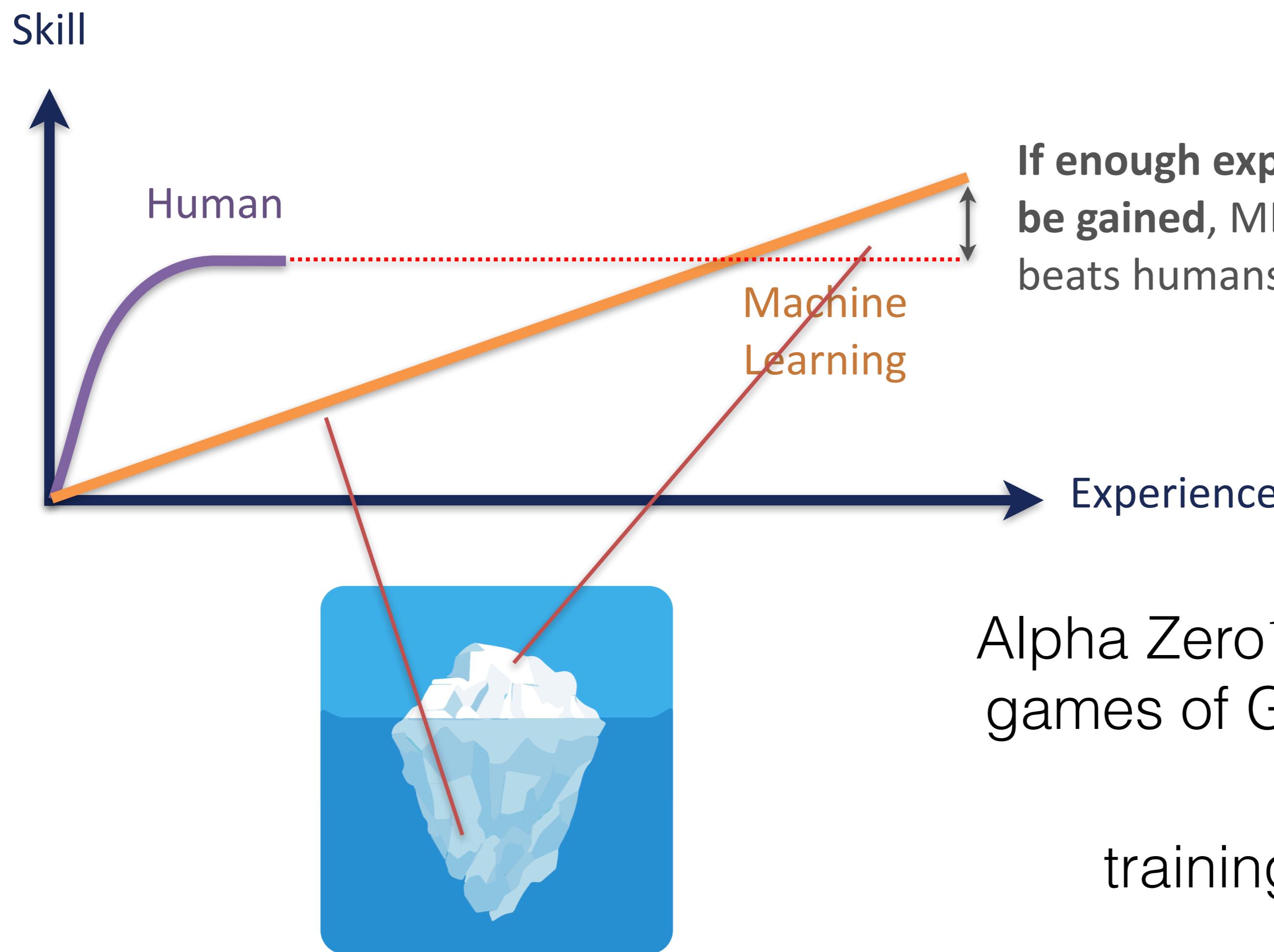
Alpha Zero¹ needs 21 Million
games of Go during training
but
training takes ≈24h

¹: Silver, D., Hubert, T., Schrittwieser, J., Antonoglou, I., Lai, M., Guez, A., ... & Lillicrap, T. (2017). Mastering chess and shogi by self-play with a general reinforcement learning algorithm.

Intelligence vs Experience

- One definition of intelligence:
(from F. Chollet)

$$\text{Intelligence} = \frac{\text{Skill}}{\text{Experience}}$$



¹: Silver, D., Hubert, T., Schrittwieser, J., Antonoglou, I., Lai, M., Guez, A., ... & Lillicrap, T. (2017). Mastering chess and shogi by self-play with a general reinforcement learning algorithm.

Finding a good ML problem

Focus on problems that
would be difficult to solve
with traditional
programming

Finding a good ML problem

Focus on problems that would be difficult to solve with traditional programming



Neural networks ≈ « intuition machines ». If you can do it but you don't know how, you can't code it. Example:

Finding a good ML problem

Focus on problems that would be difficult to solve with traditional programming



Neural networks ≈ « intuition machines ». If you can do it but you don't know how, you can't code it. Example:



Where's the cat?

Finding a good ML problem

Focus on problems that would be difficult to solve with traditional programming



Neural networks ≈ « intuition machines ». If you can do it but you don't know how, you can't code it. Example:



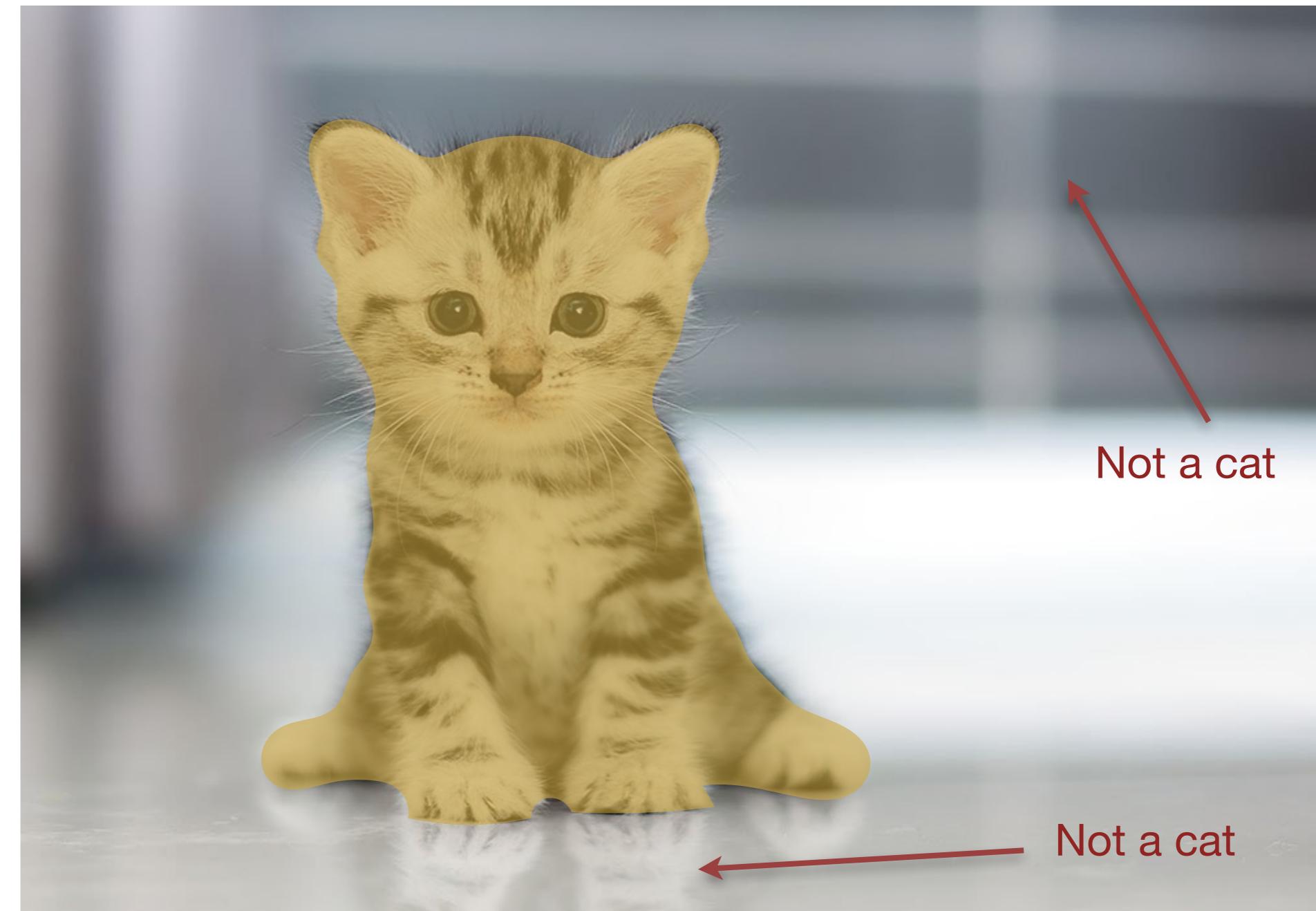
Where's the cat?

Finding a good ML problem

Focus on problems that would be difficult to solve with traditional programming



Neural networks ≈ « intuition machines ». If you can do it but you don't know how, you can't code it. Example:



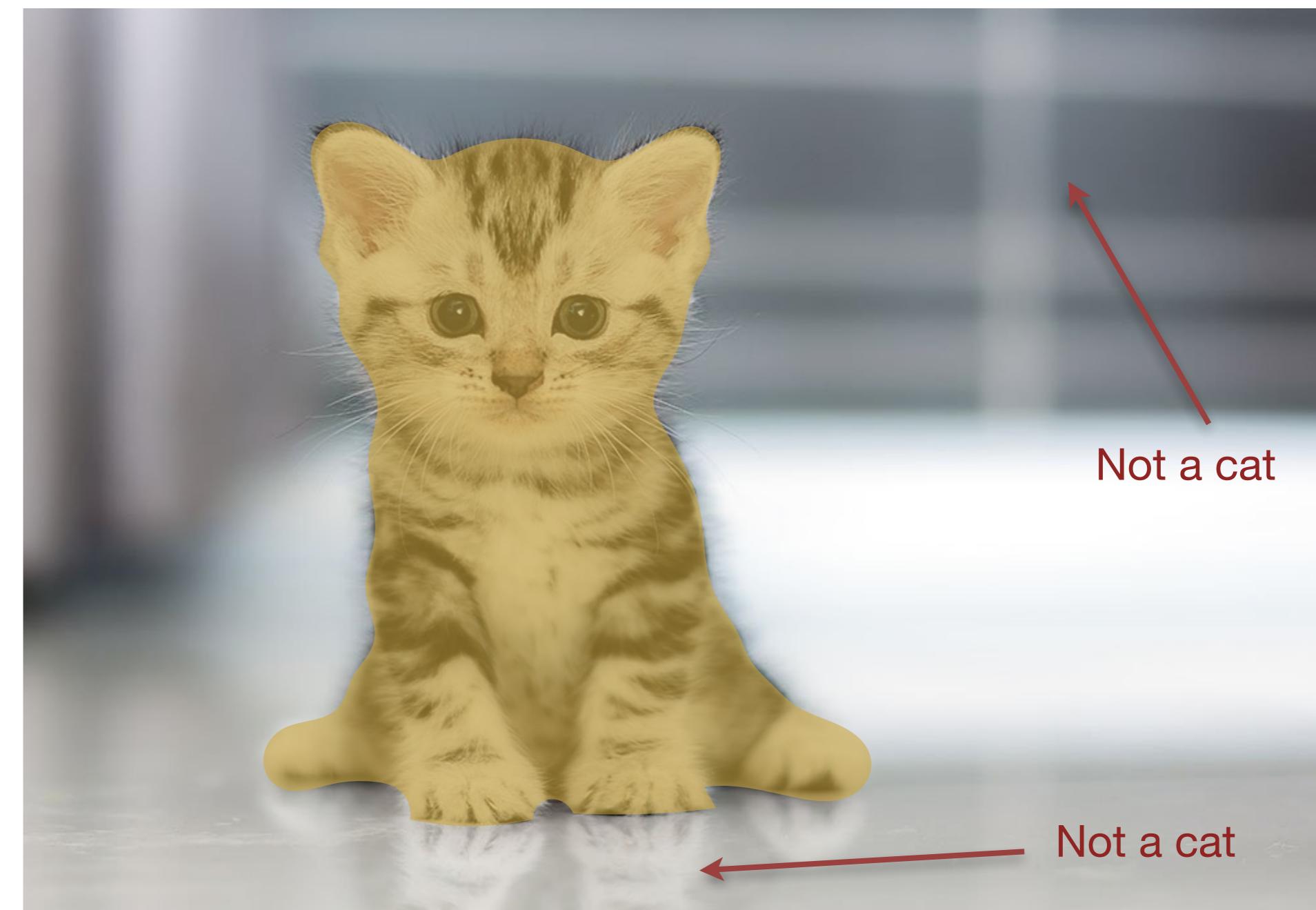
Finding a good ML problem

Focus on problems that would be difficult to solve with traditional programming

Know the problem before focusing on the data



Neural networks ≈ « intuition machines ». If you can do it but you don't know how, you can't code it. Example:



Where's the cat?

Finding a good ML problem

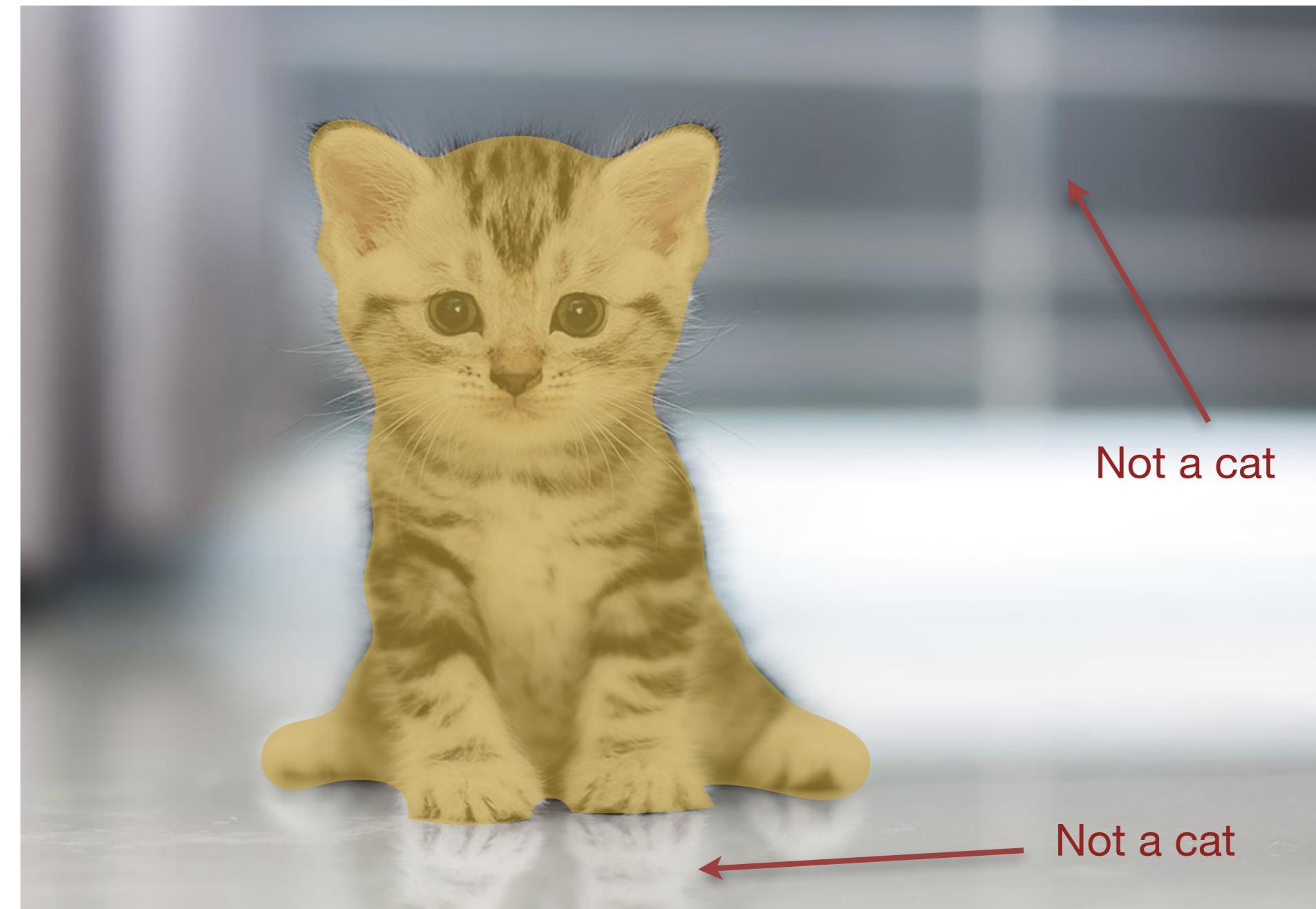
Focus on problems that would be difficult to solve with traditional programming

Know the problem before focusing on the data

Get lots of data



Neural networks \approx « intuition machines ». If you can do it but you don't know how, you can't code it. Example:



Finding a good ML problem

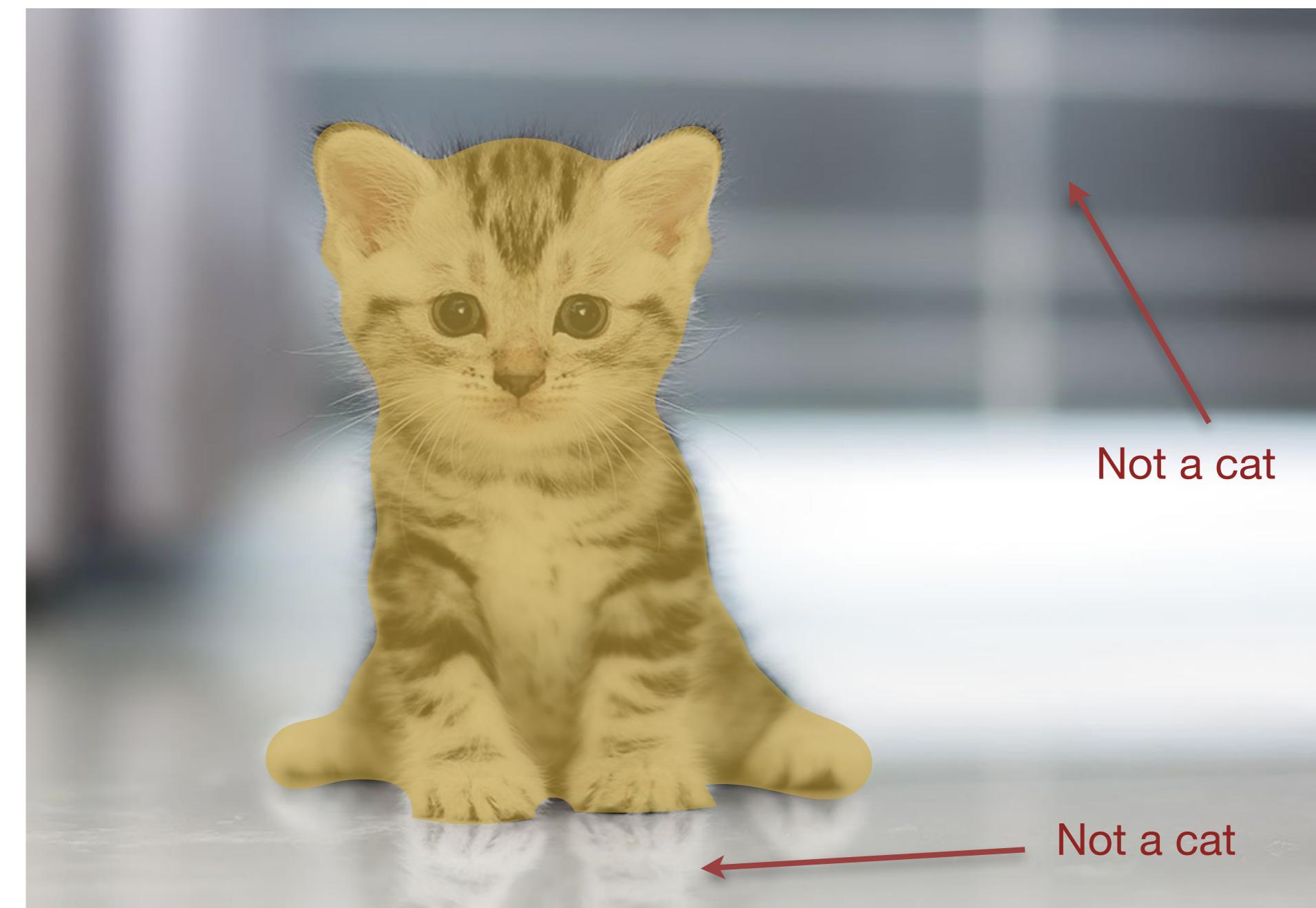
Focus on problems that would be difficult to solve with traditional programming

Know the problem before focusing on the data

Get lots of data



Neural networks ≈ « intuition machines ». If you can do it but you don't know how, you can't code it. Example:



Where's the cat?

Ok, but what is a lot?

Finding a good ML problem

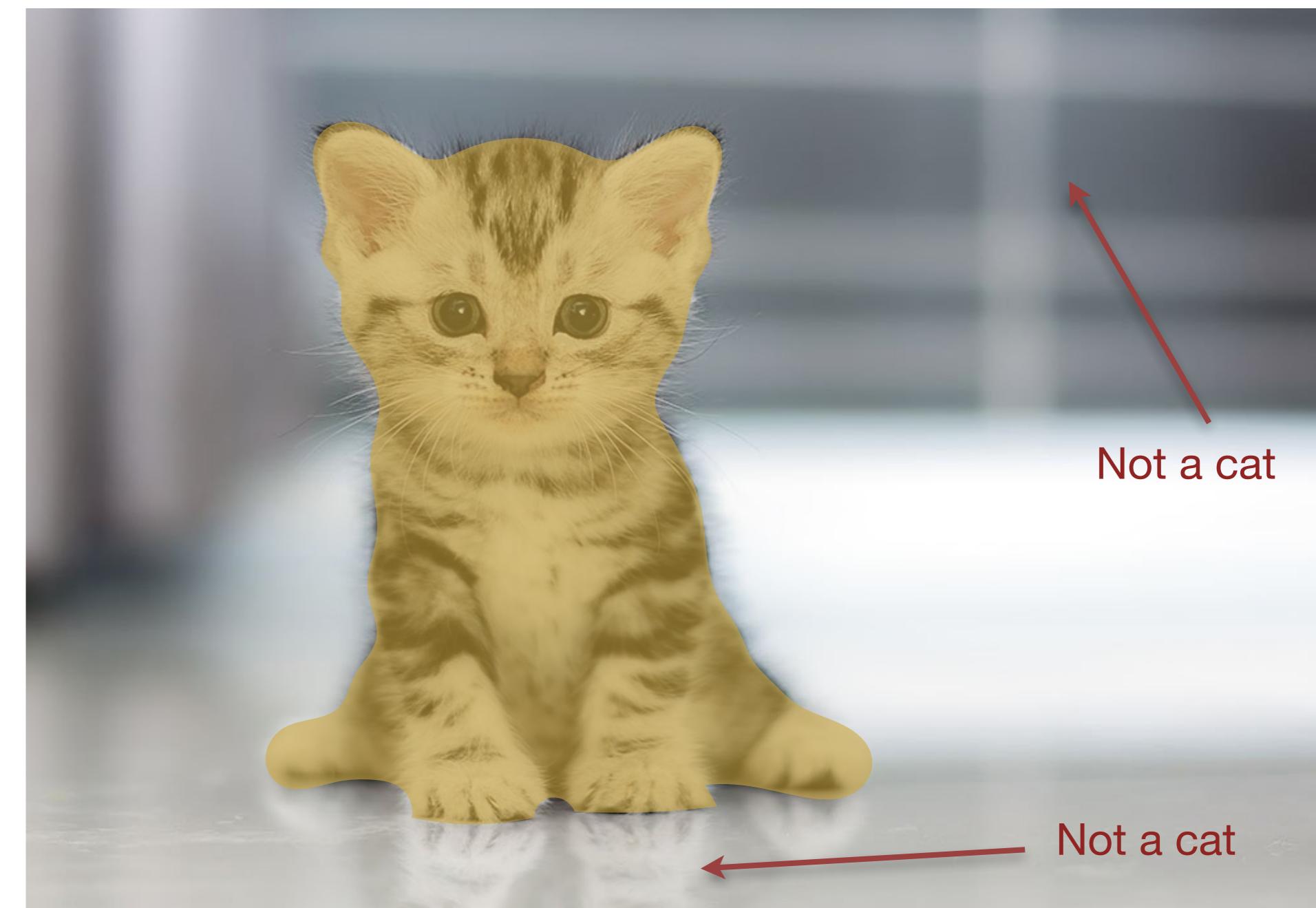
Focus on problems that would be difficult to solve with traditional programming

Know the problem before focusing on the data

Get lots of data

Don't let ML do the hard work of choosing features

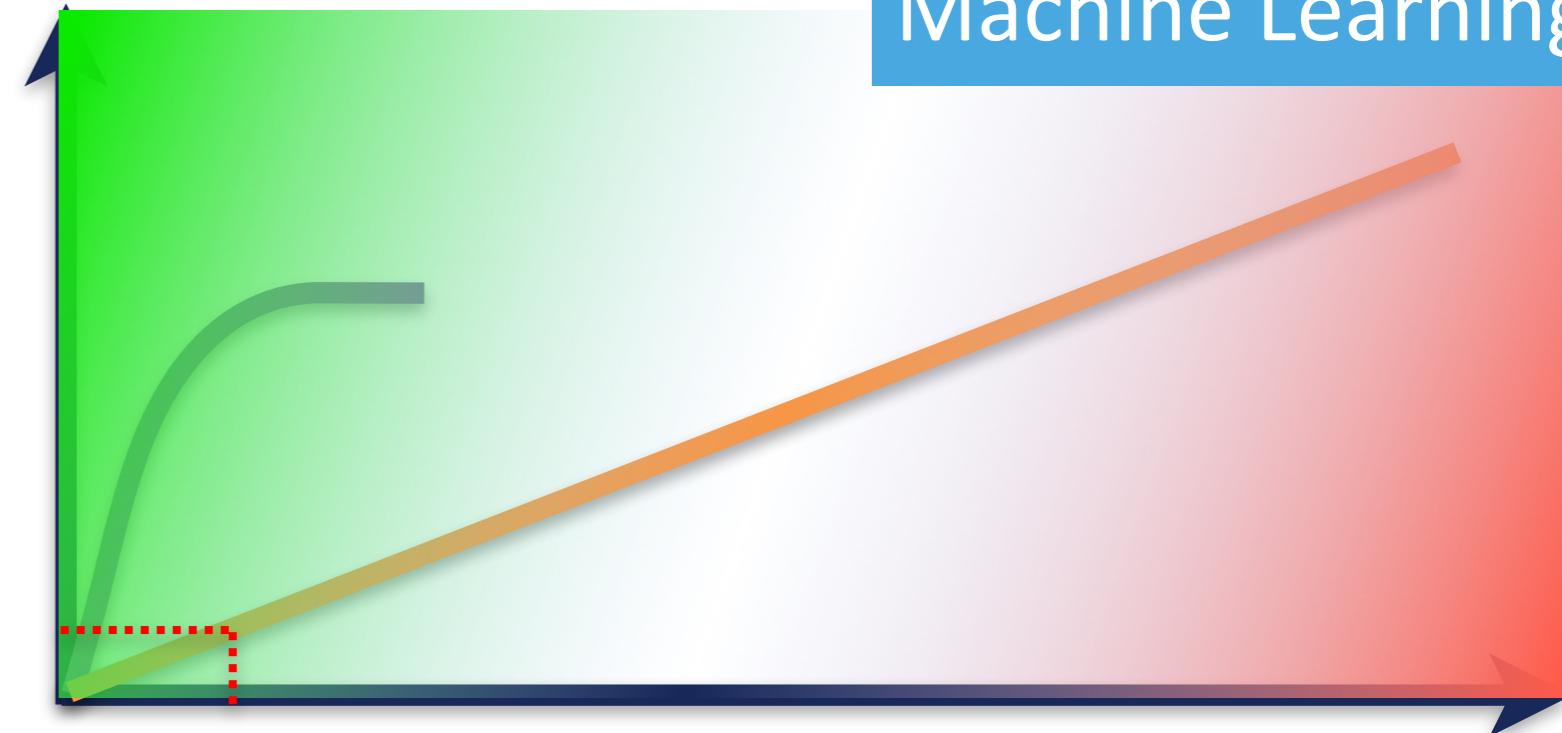
Neural networks ≈ « intuition machines ». If you can do it but you don't know how, you can't code it. Example:



Where's the cat?

Ok, but what is a lot?

How much data?

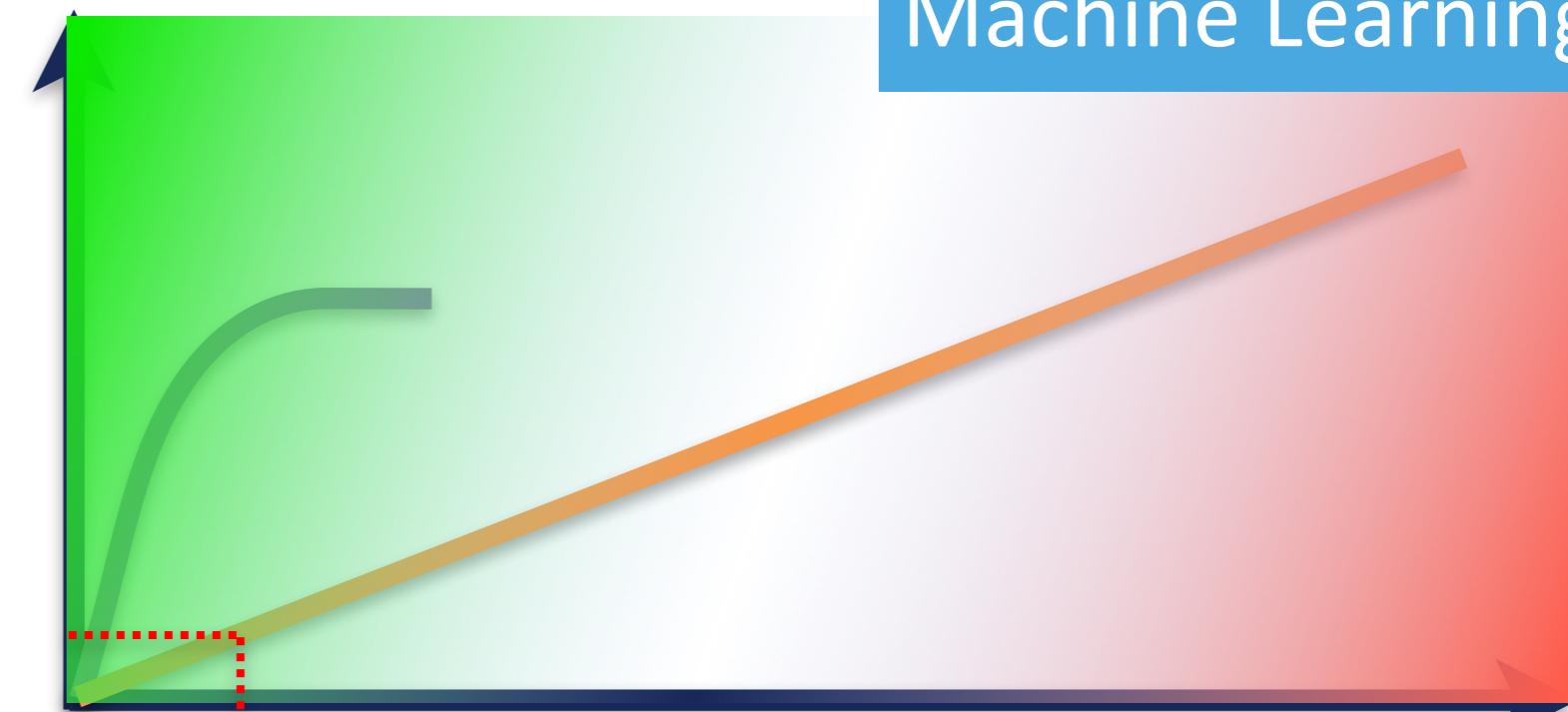


Low intelligence + low experience
= low skill

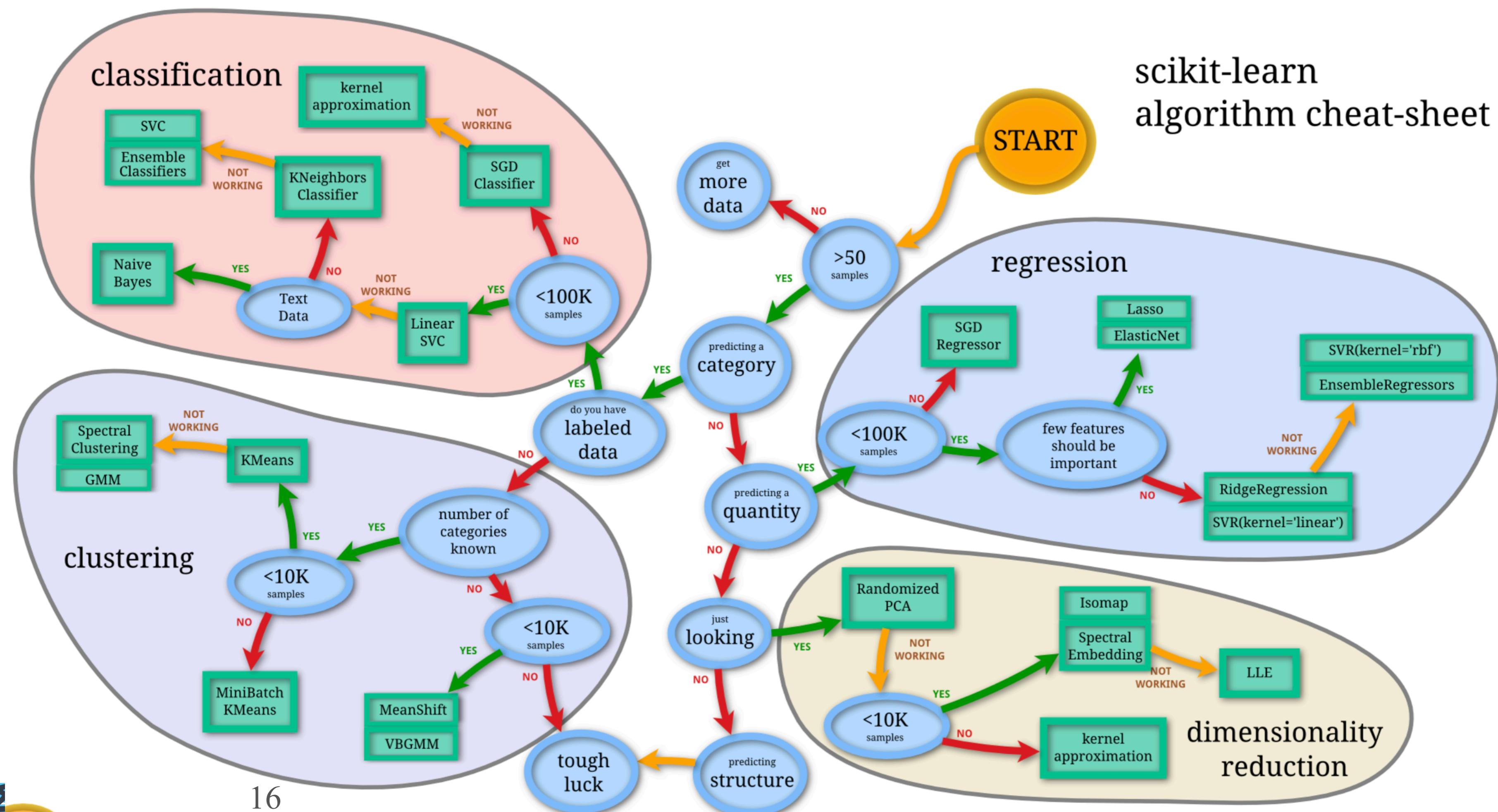
How much data?



<https://scikit-learn.org/>



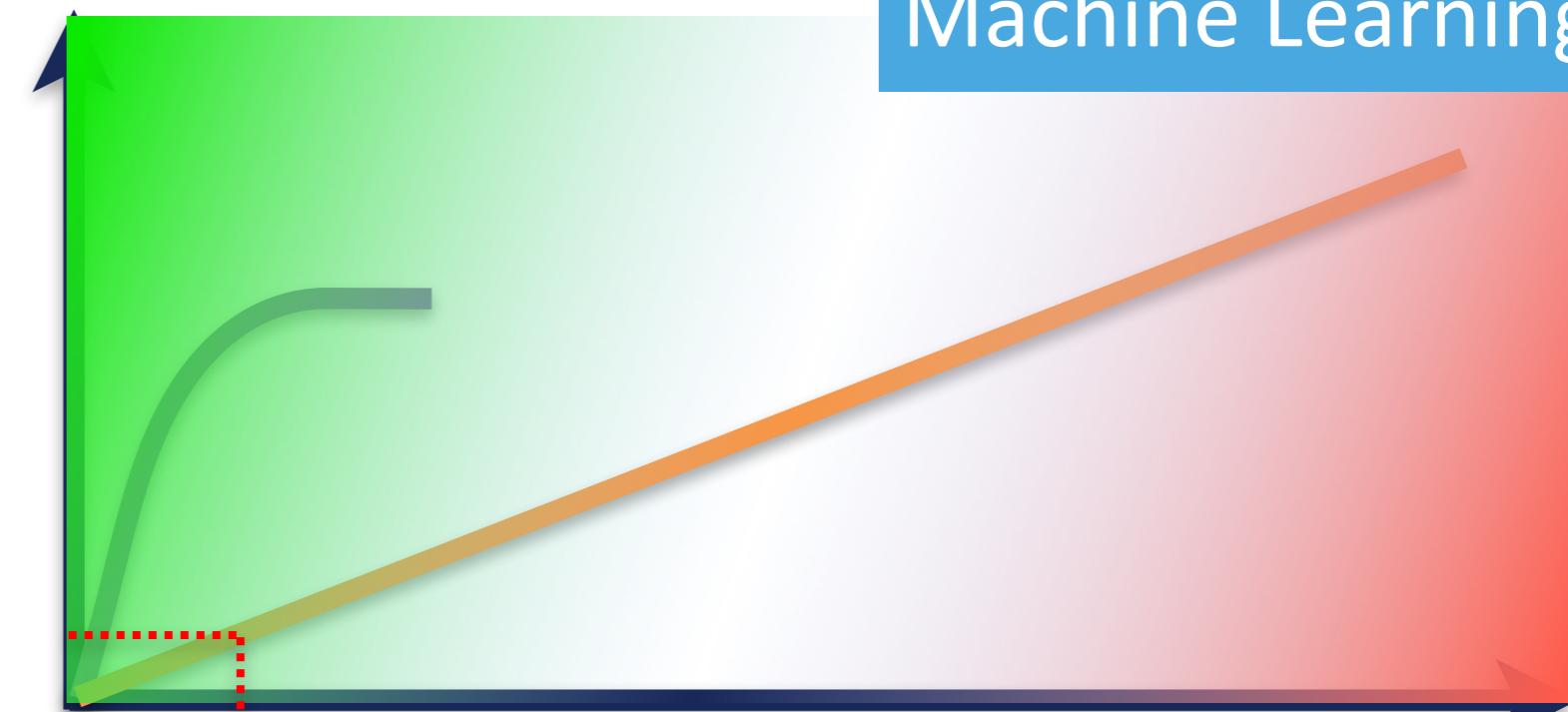
Low intelligence + low experience
= low skill



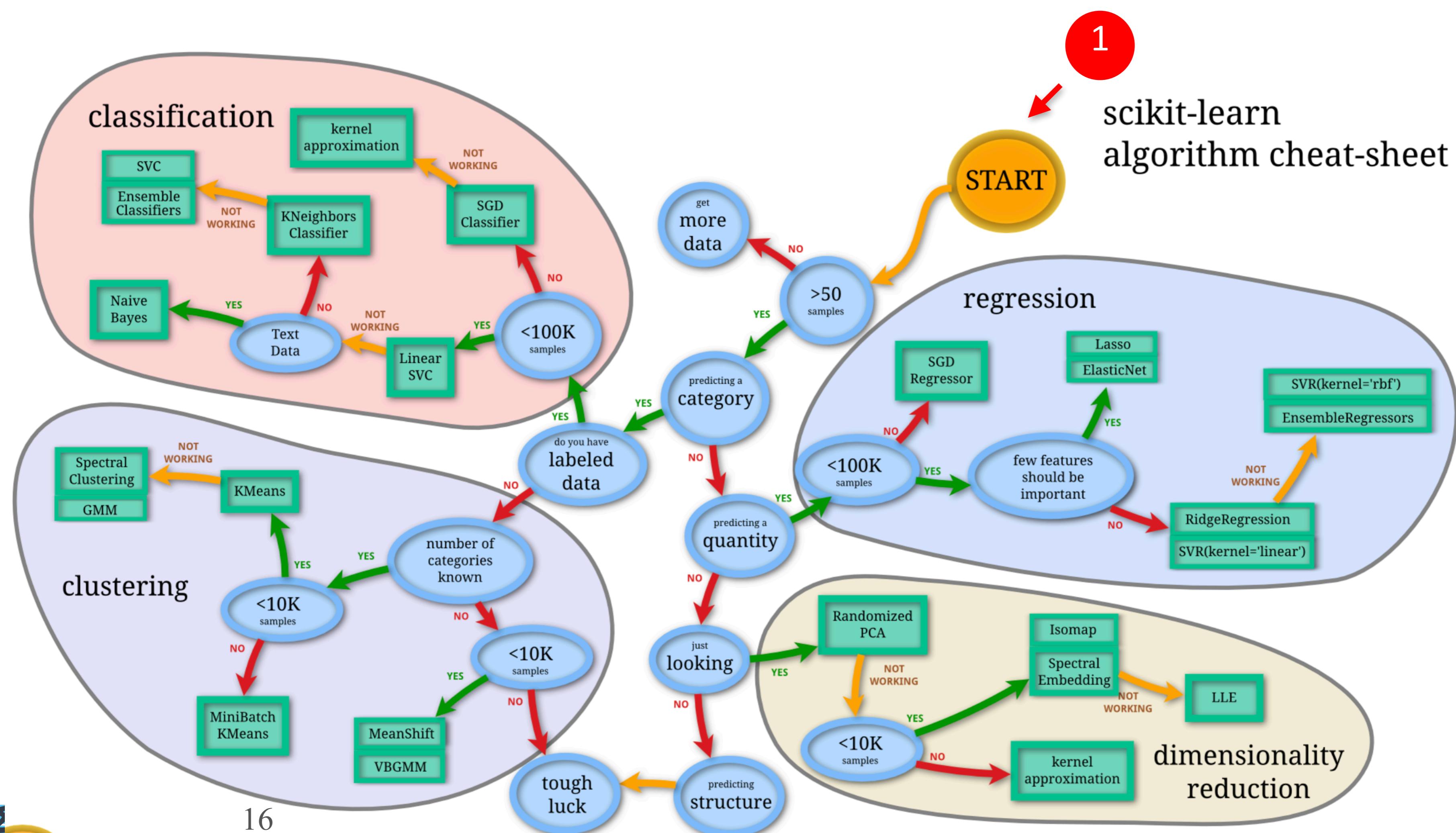
How much data?



<https://scikit-learn.org/>



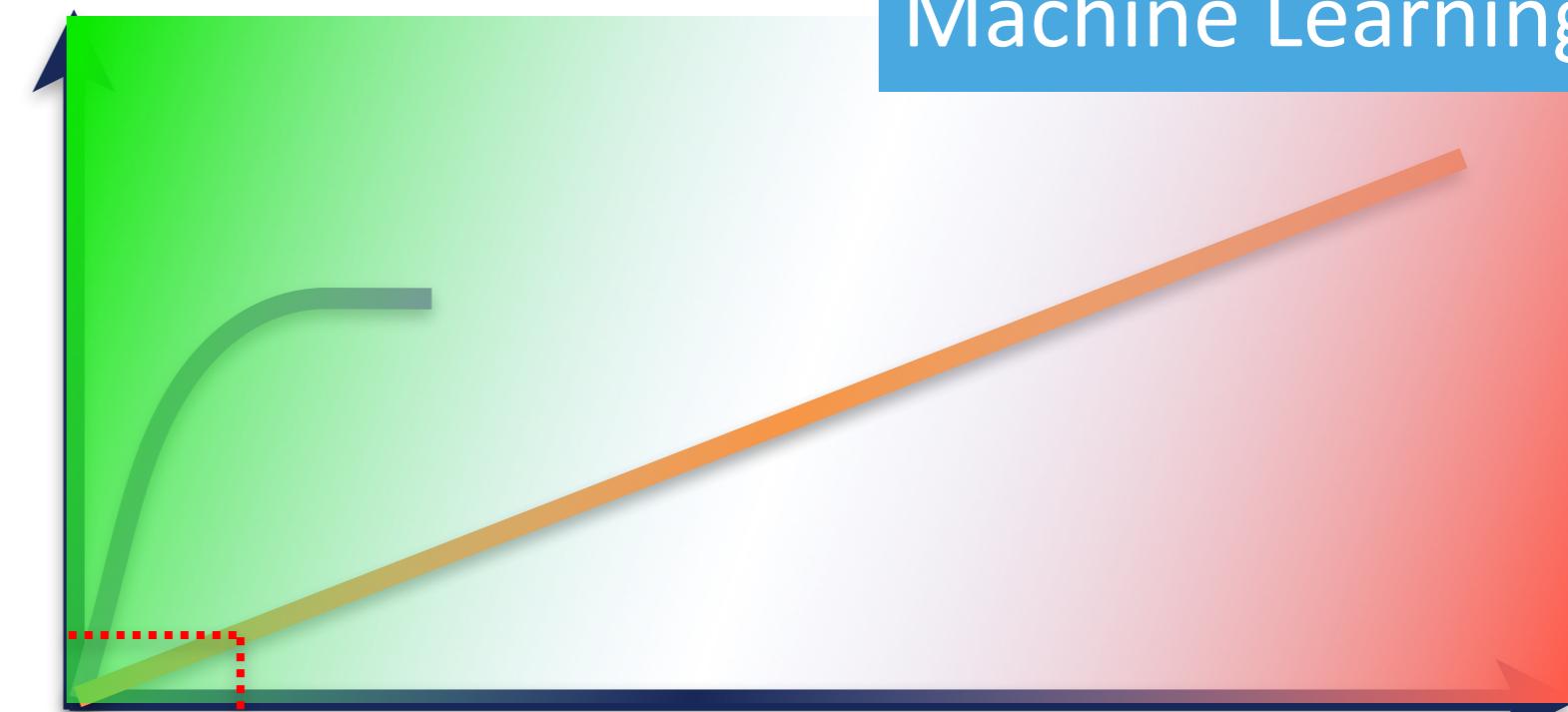
Low intelligence + low experience
= low skill



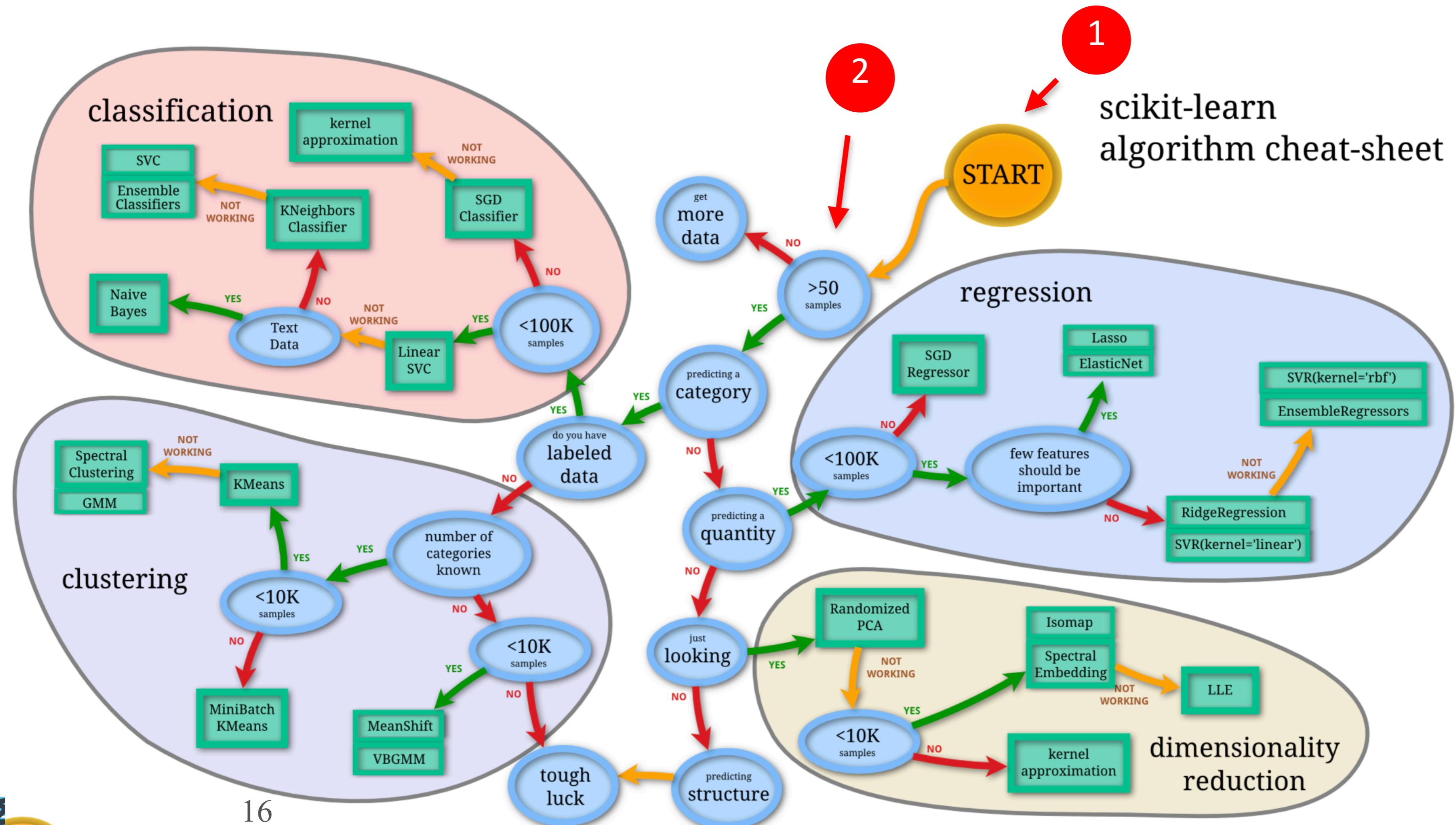
How much data?



<https://scikit-learn.org/>



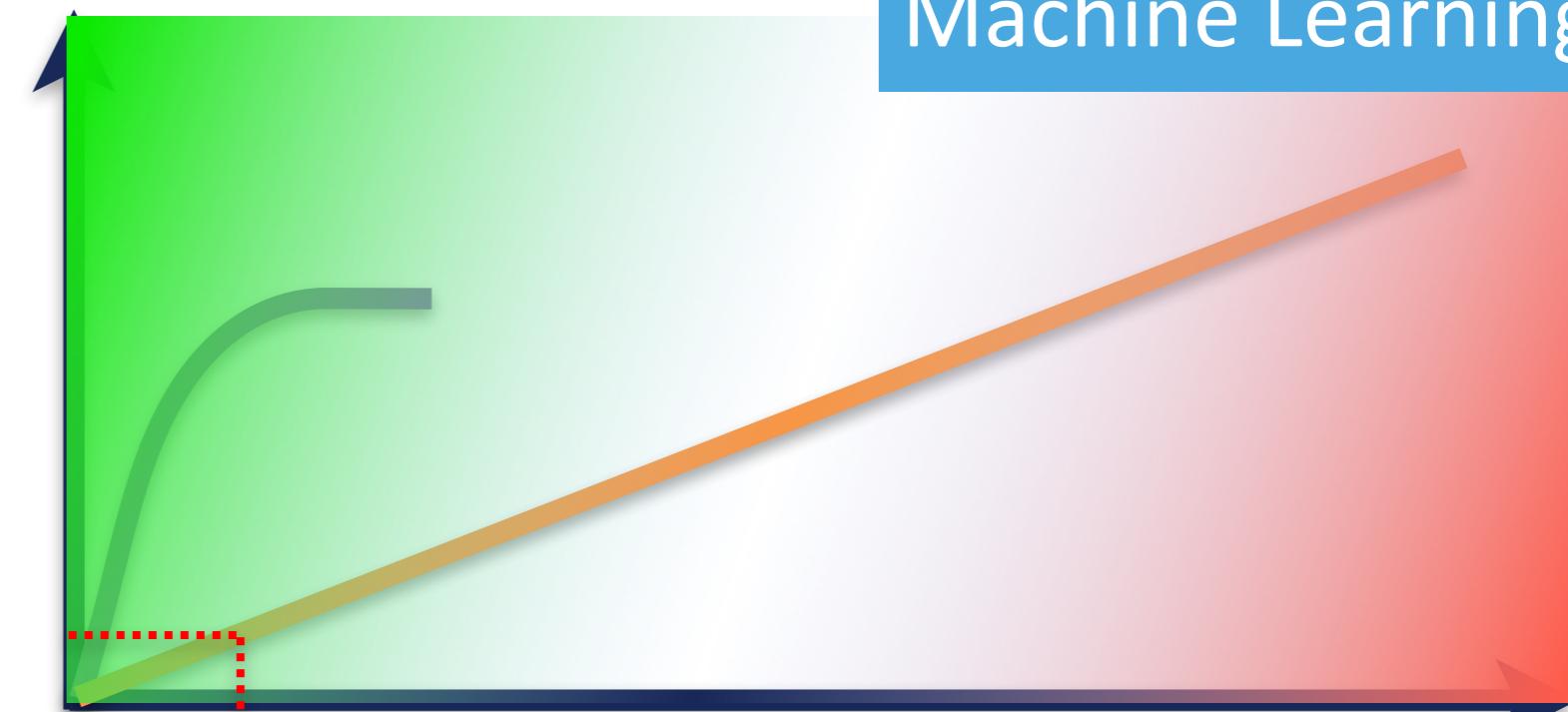
Low intelligence + low experience
= low skill



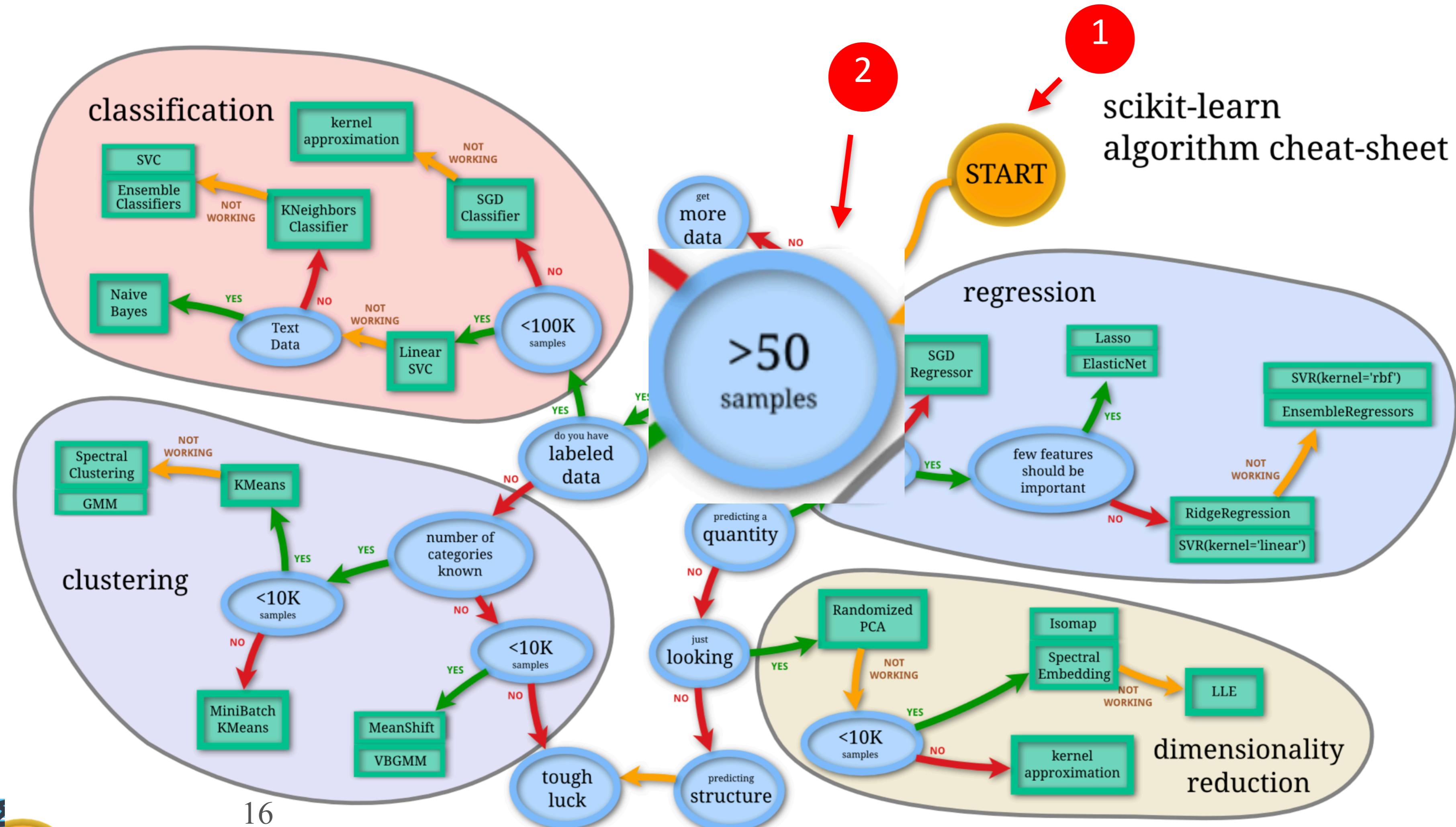
How much data?



<https://scikit-learn.org/>



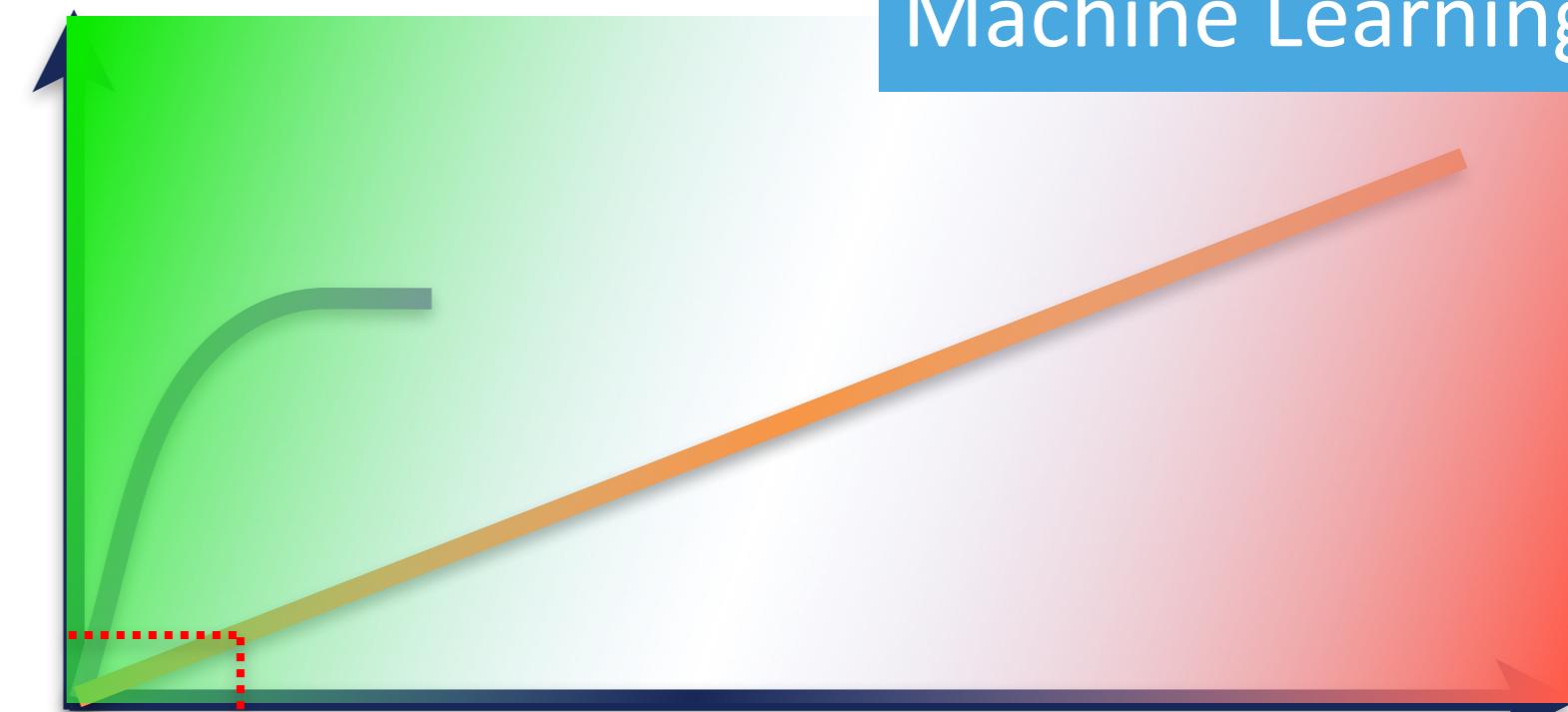
Low intelligence + low experience
= low skill



How much data?



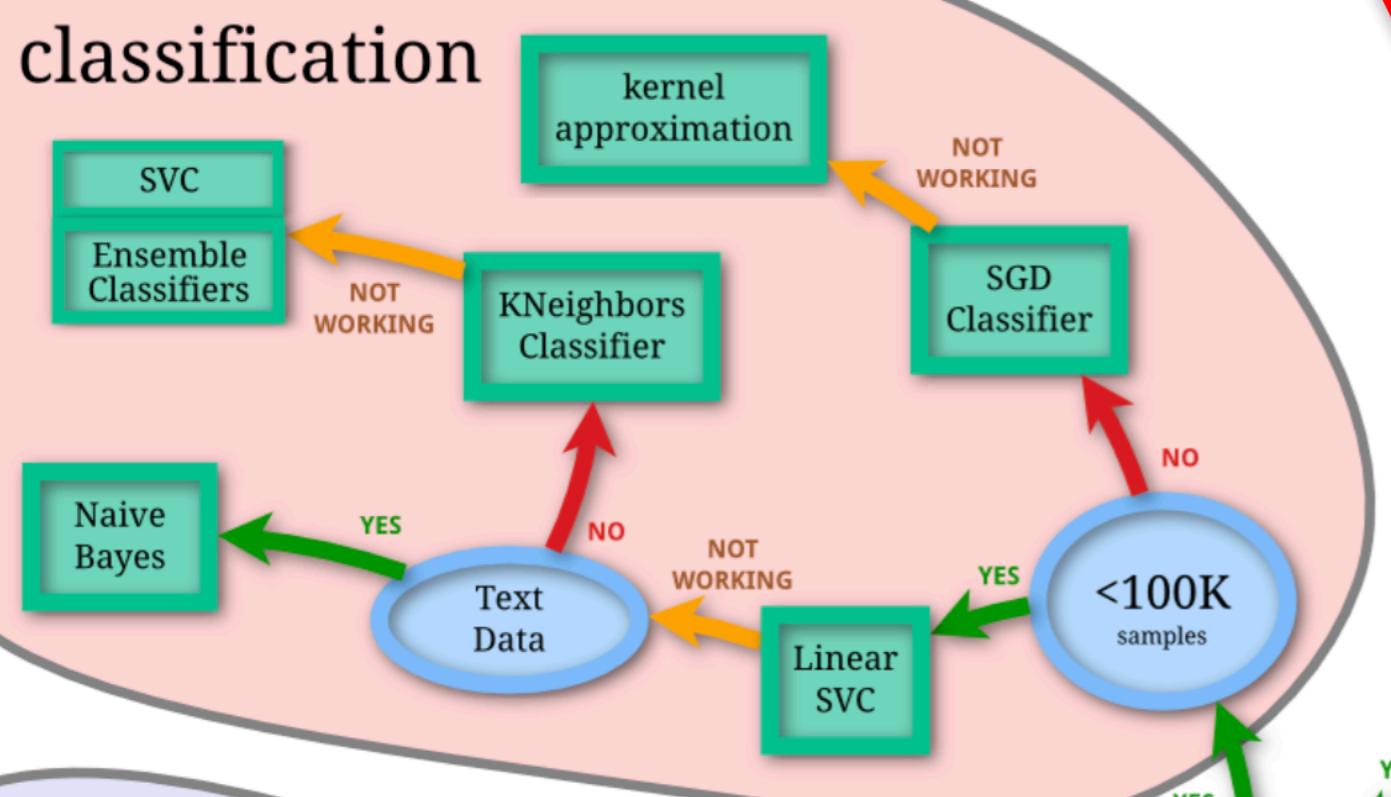
<https://scikit-learn.org/>



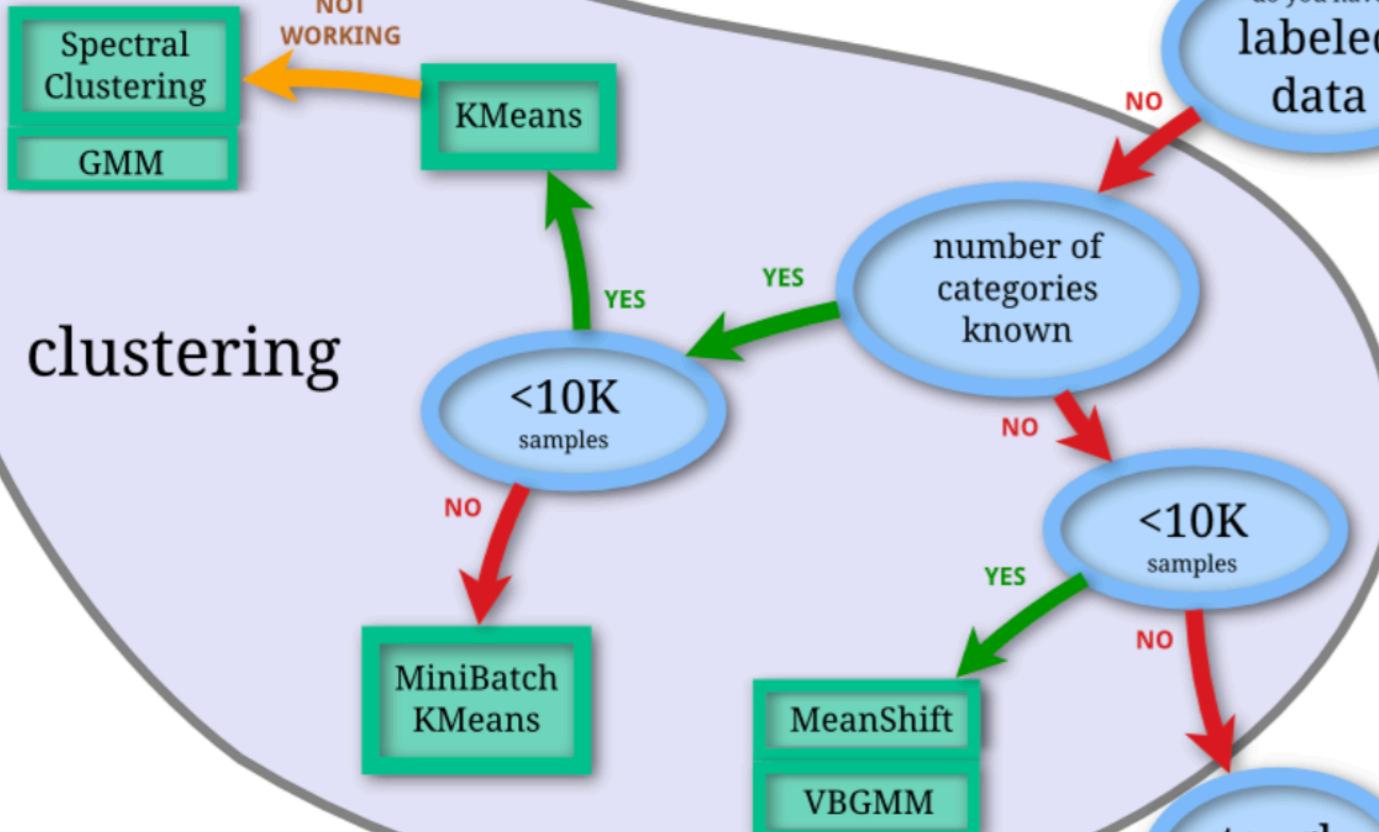
ML can't help you

Low intelligence + low experience
= low skill

classification



clustering



3

1

get more data

NO

2

>50 samples

YES

do you have labeled data

NO

predicting a category

NO

predicting a quantity

NO

just looking

NO

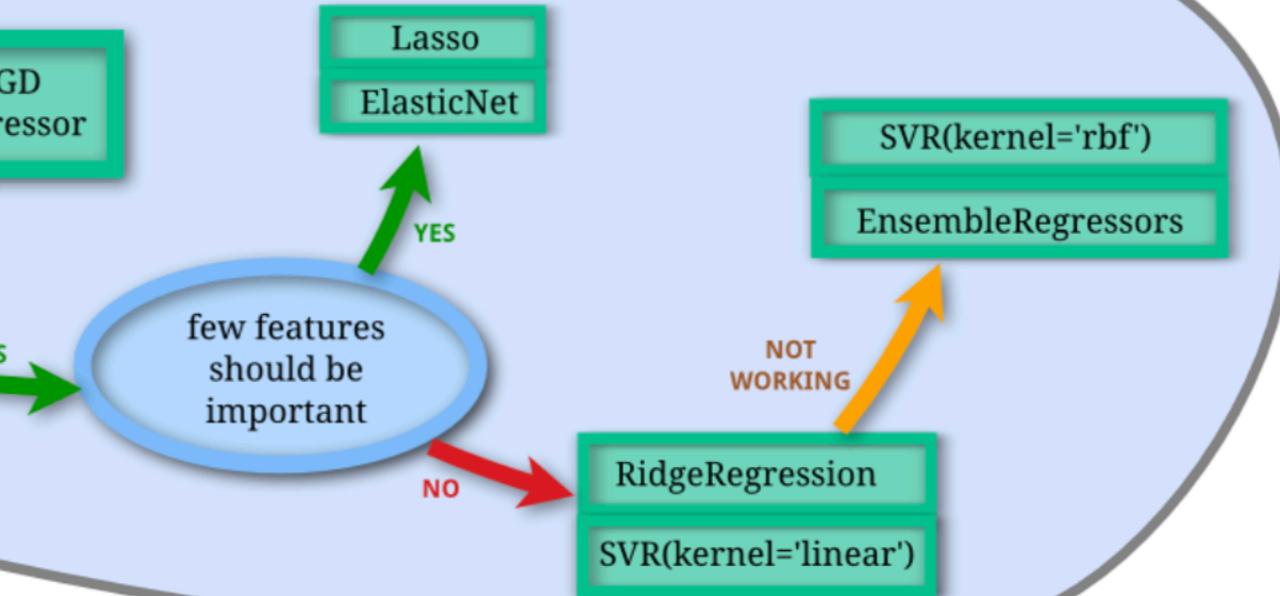
predicting structure

NO

tough luck

START

regression



scikit-learn algorithm cheat-sheet

3

2

1

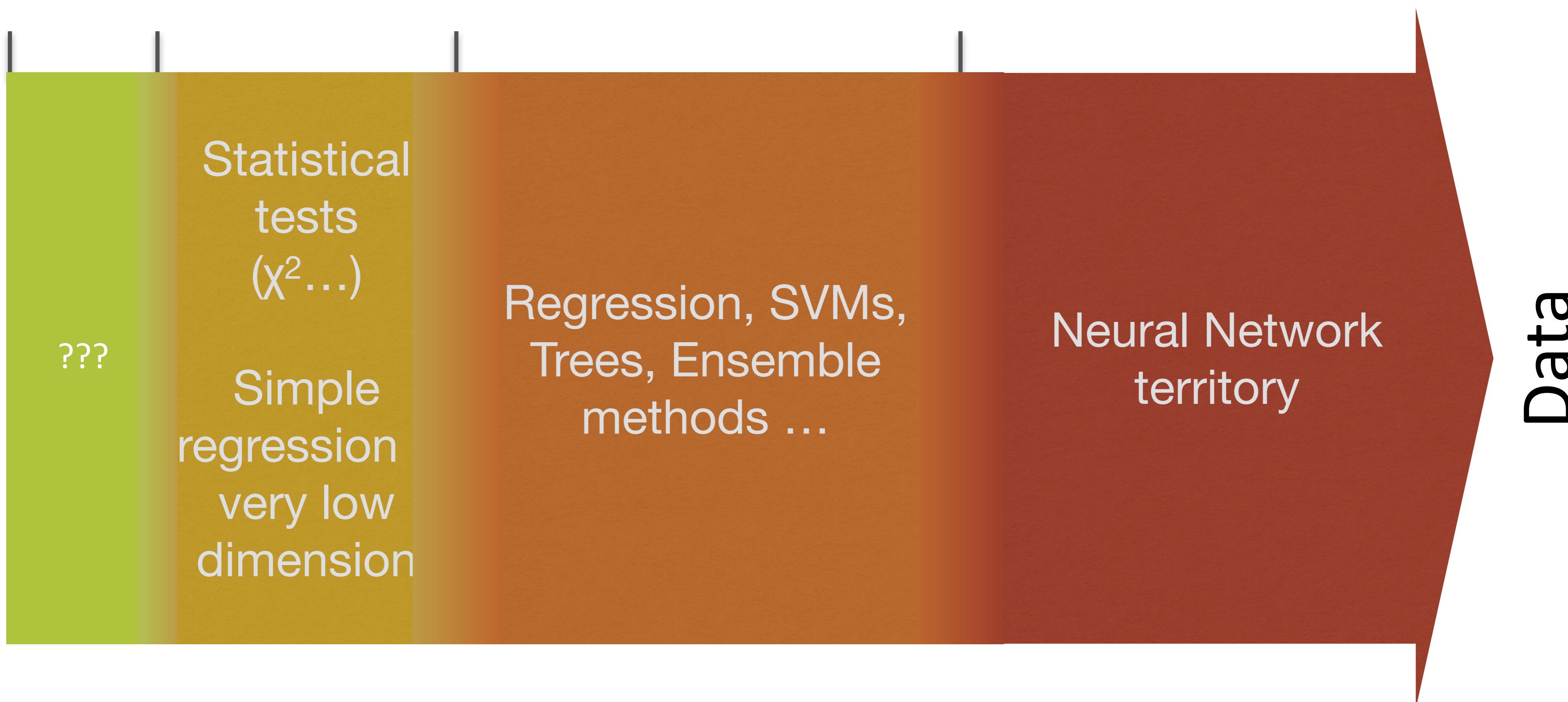
NO

YES

NO

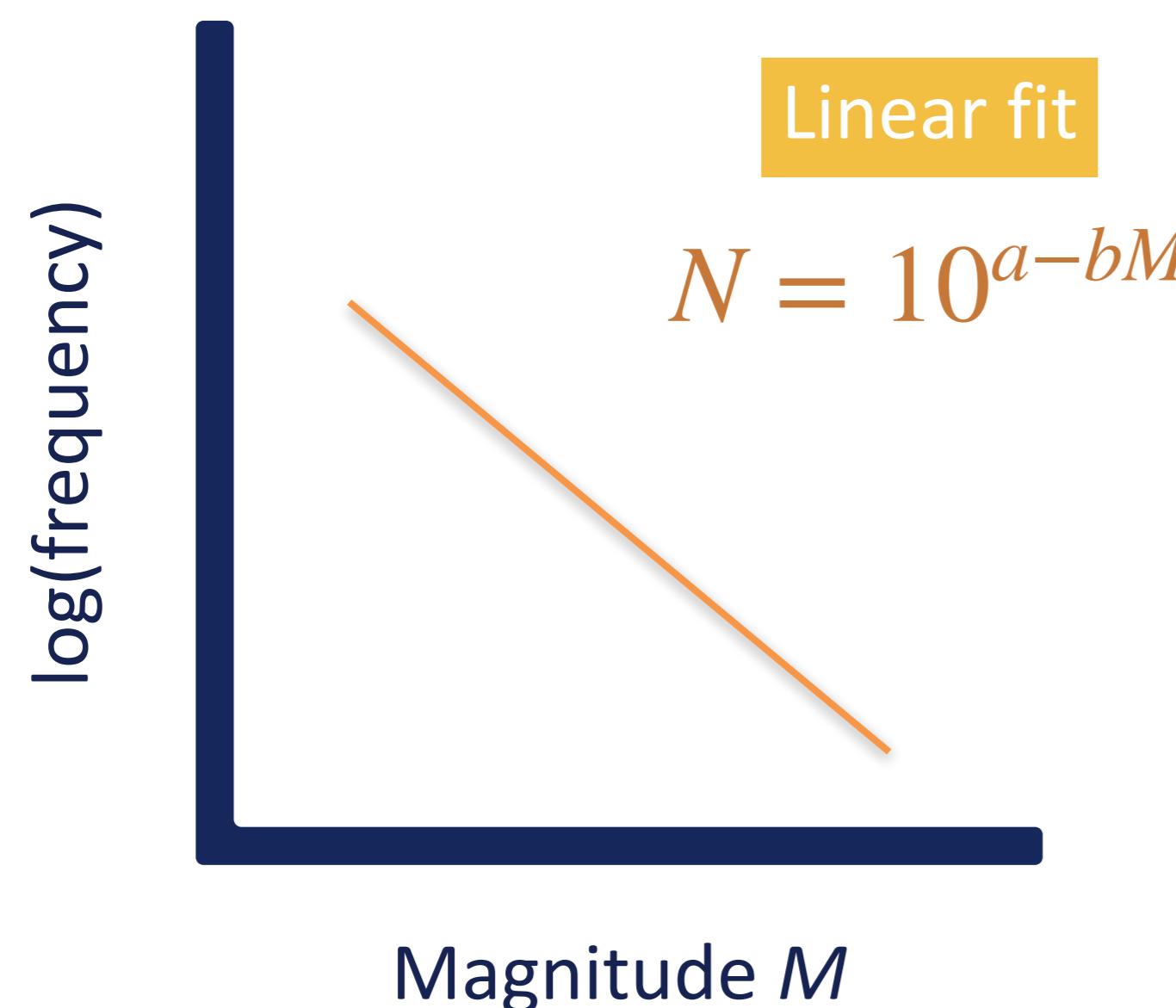
How much data?

0 ≈ 30 100-1000 100,000



Not enough data ... ?

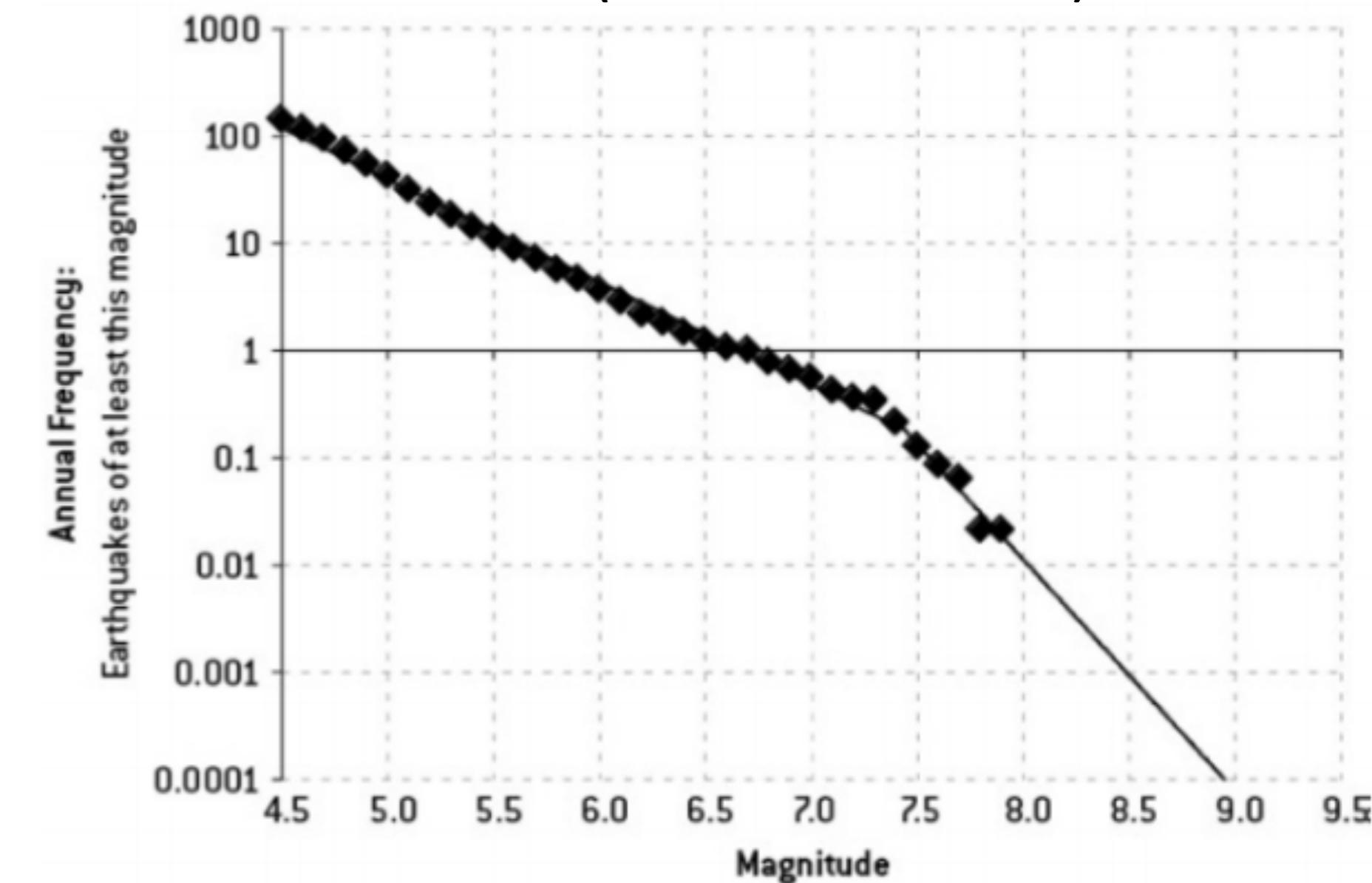
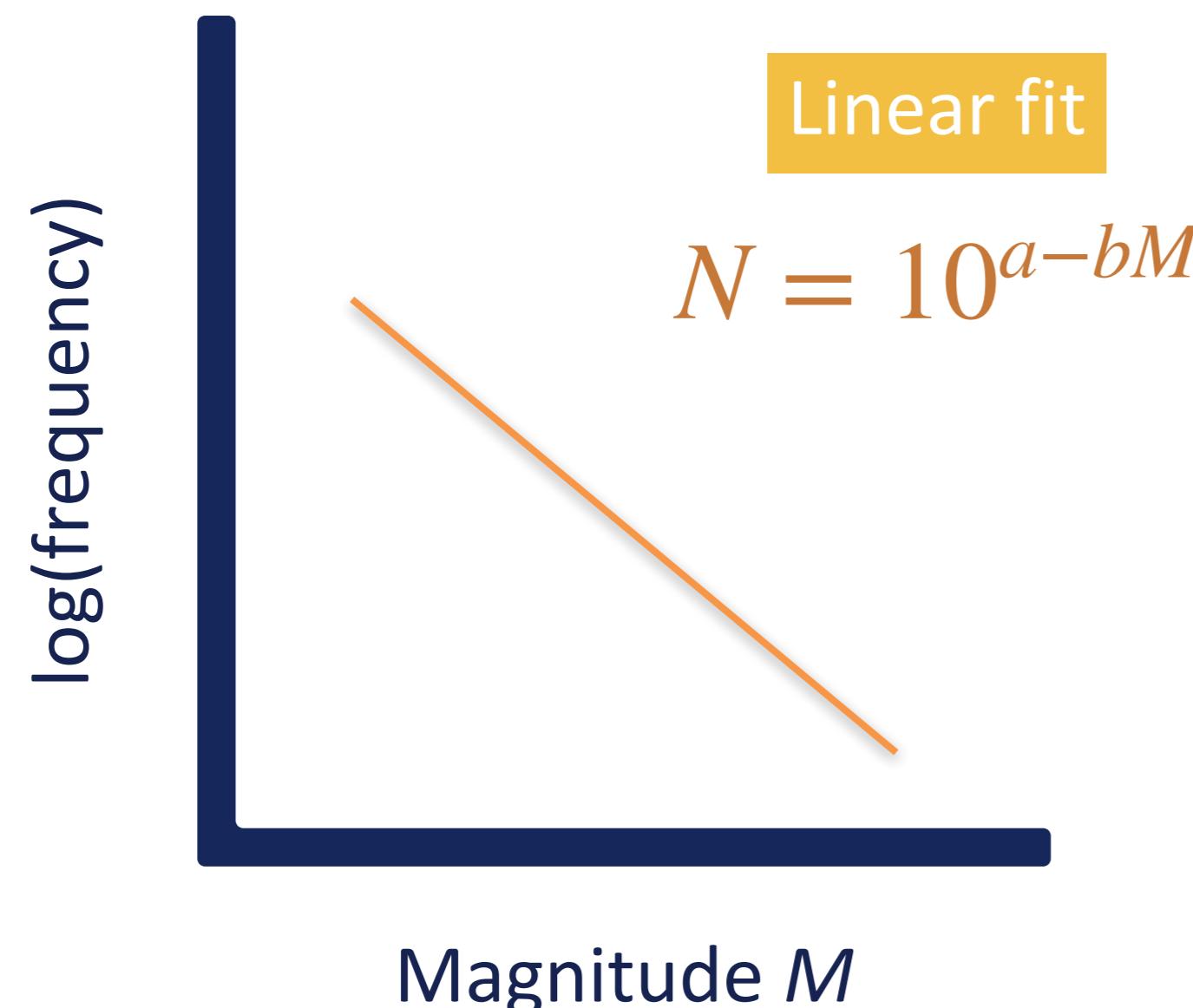
Earthquake frequency:
The Gutenberg-Richter Law



Not enough data ... ?

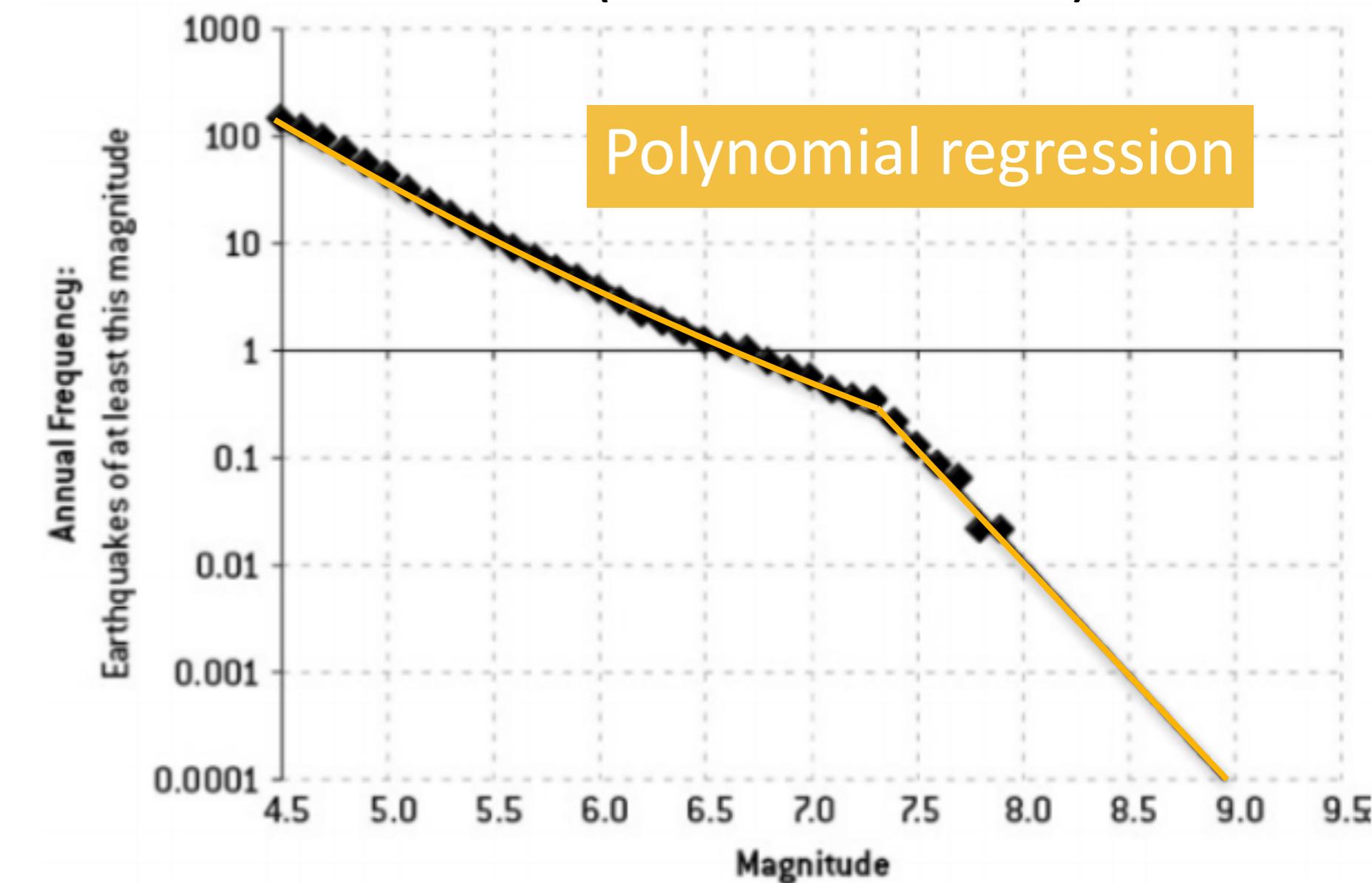
Tōhoku area
(near Fukushima)

Earthquake frequency:
The Gutenberg-Richter Law

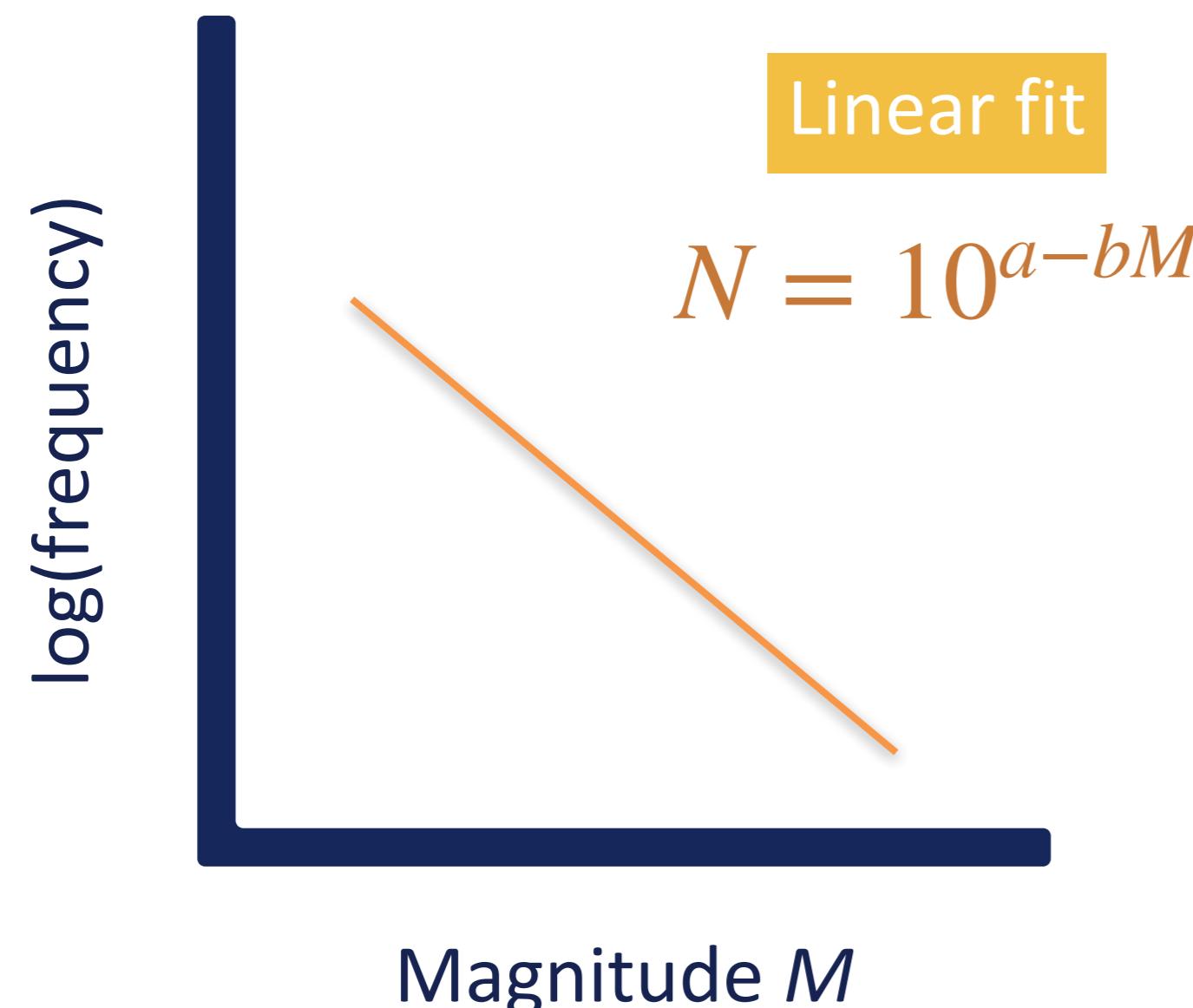


Not enough data ... ?

Tōhoku area
(near Fukushima)



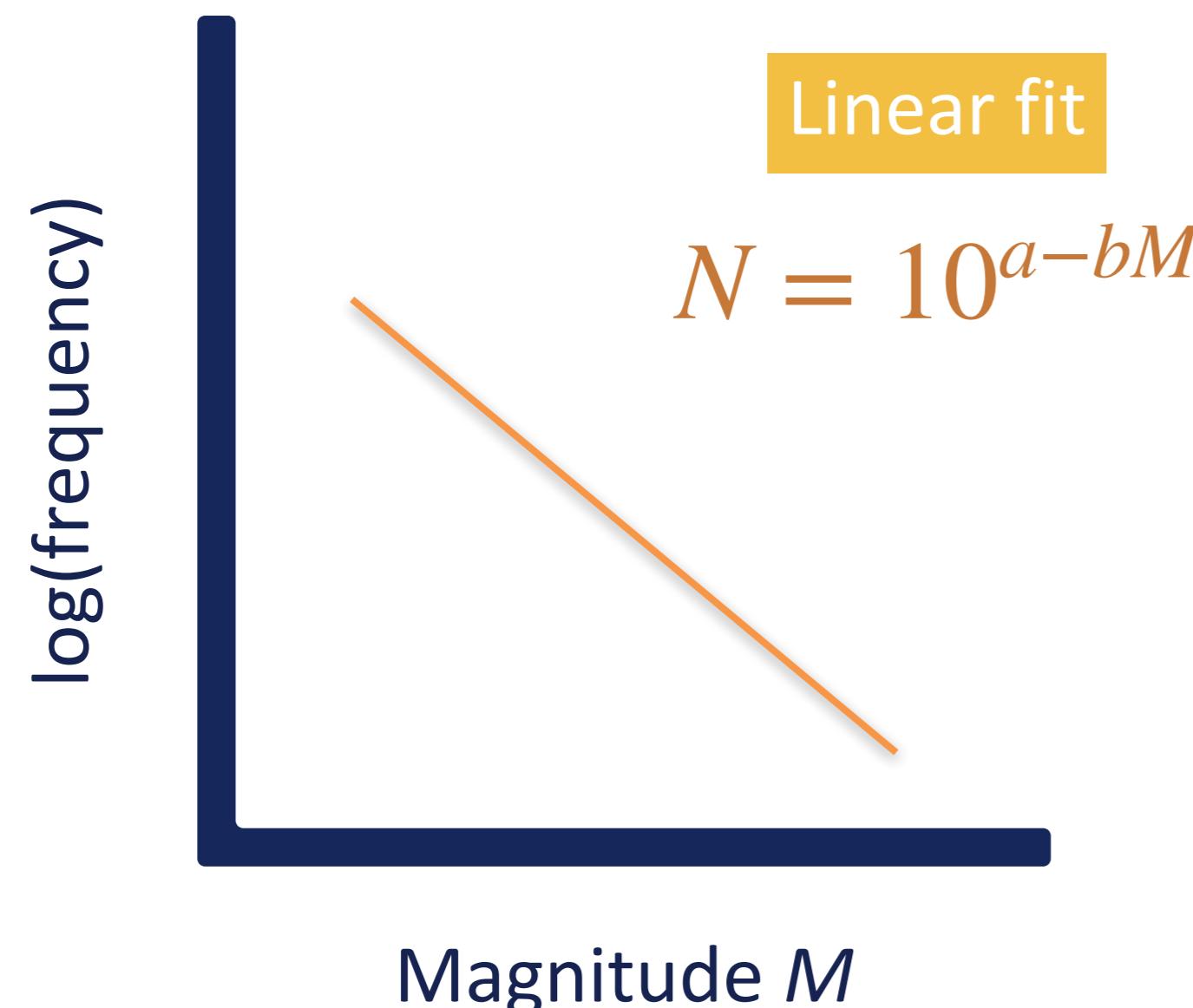
Earthquake frequency:
The Gutenberg-Richter Law



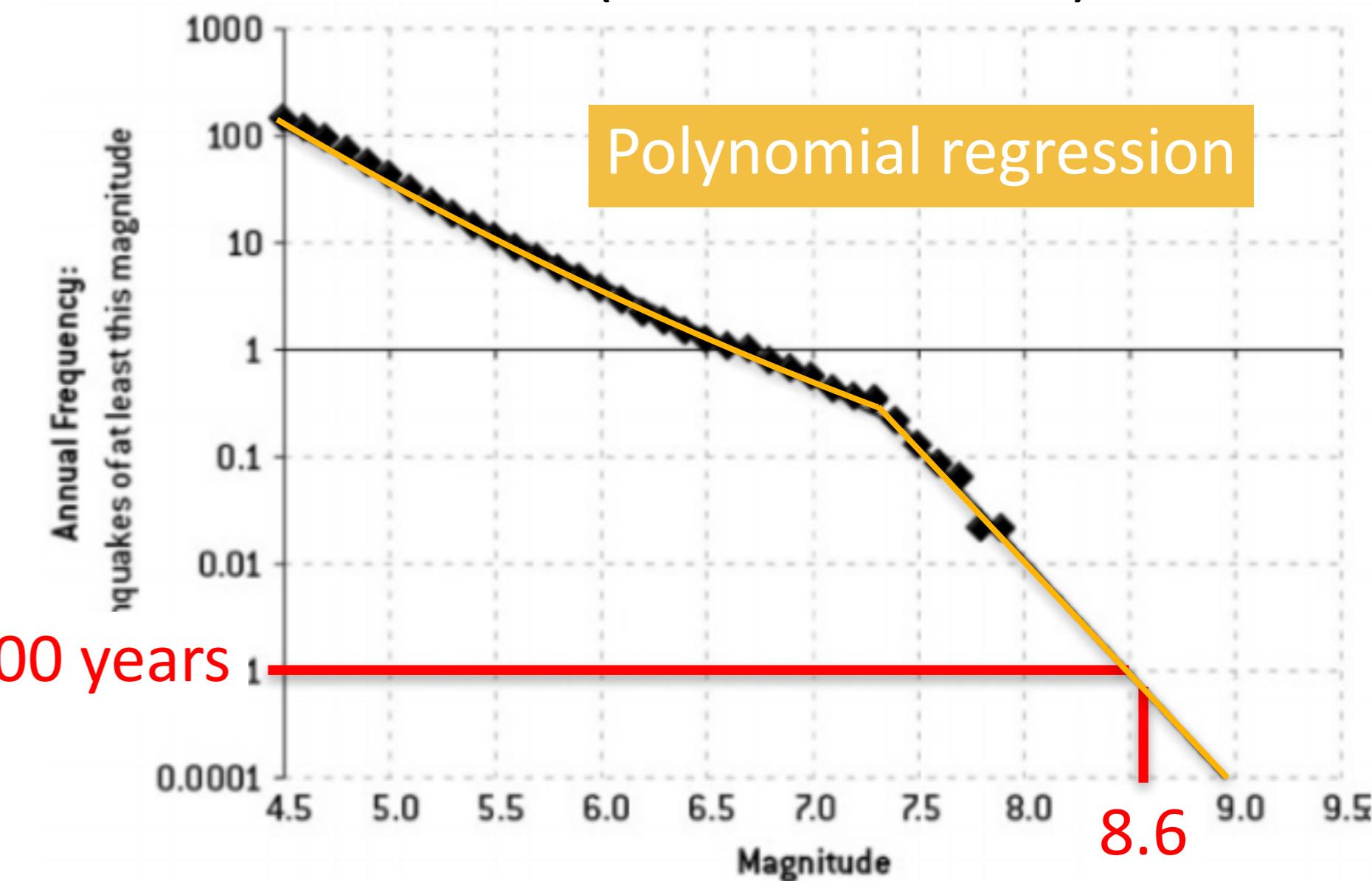
Not enough data ... ?

Tōhoku area
(near Fukushima)

Earthquake frequency:
The Gutenberg-Richter Law

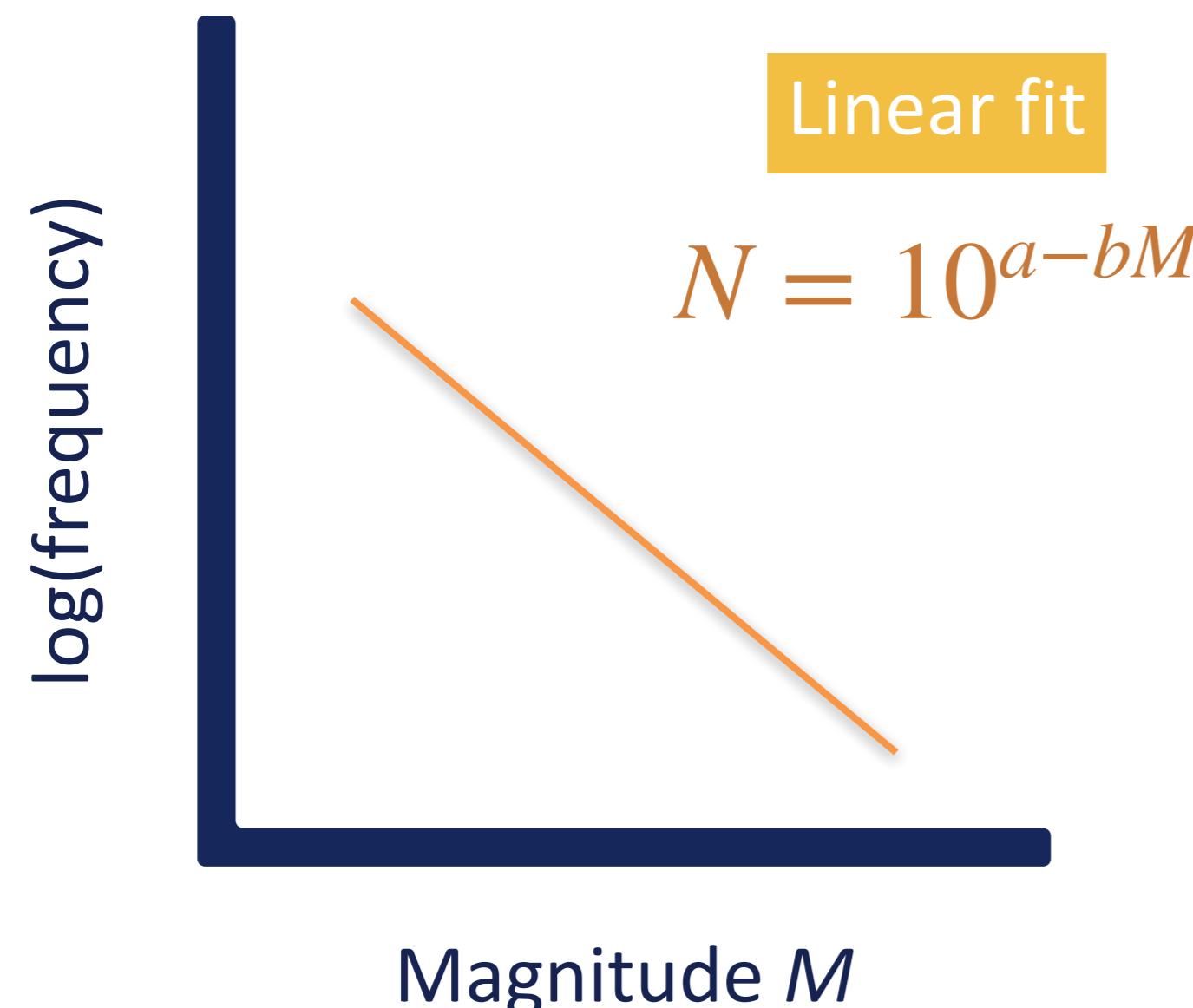


1 every 1000 years

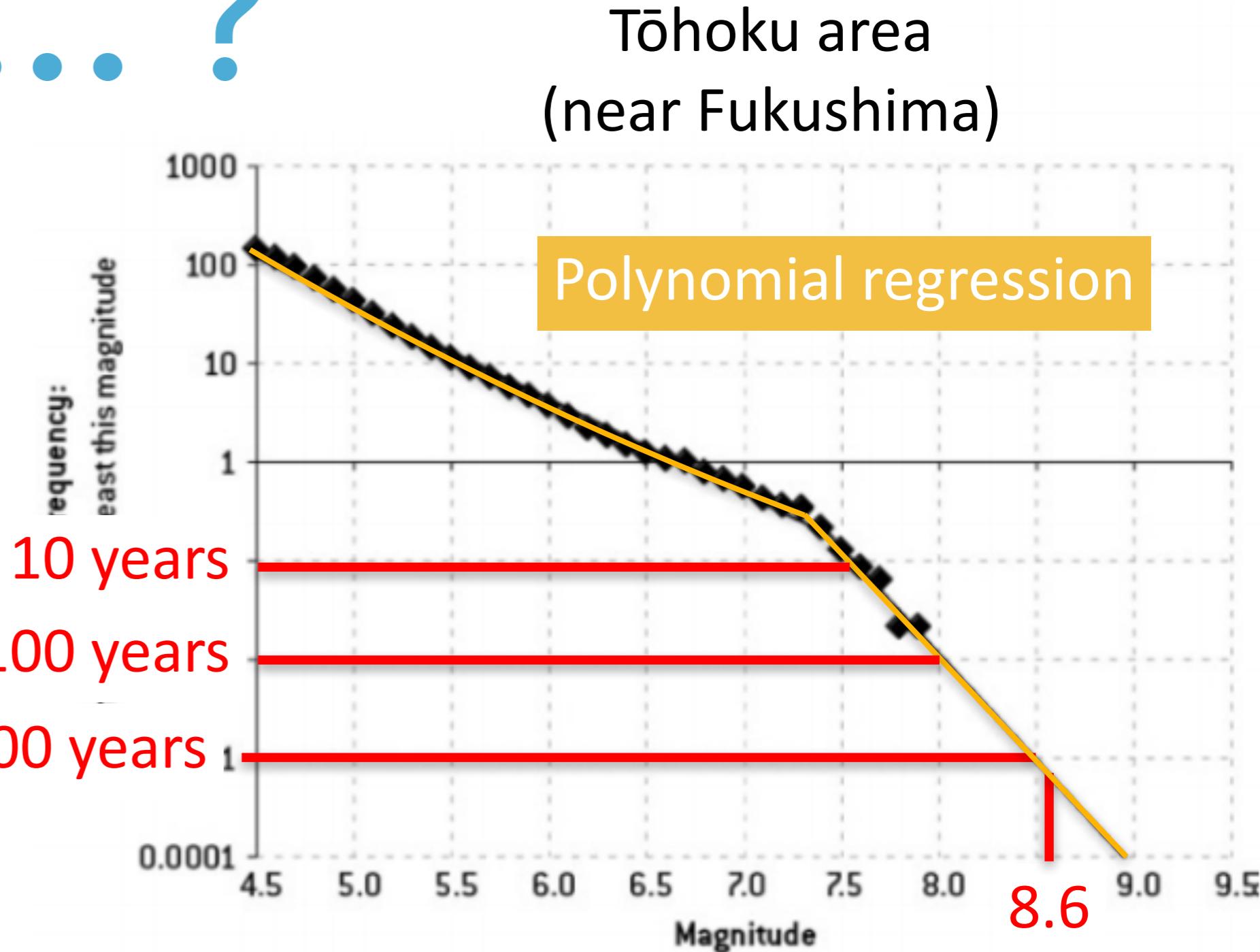


Not enough data ... ?

Earthquake frequency:
The Gutenberg-Richter Law

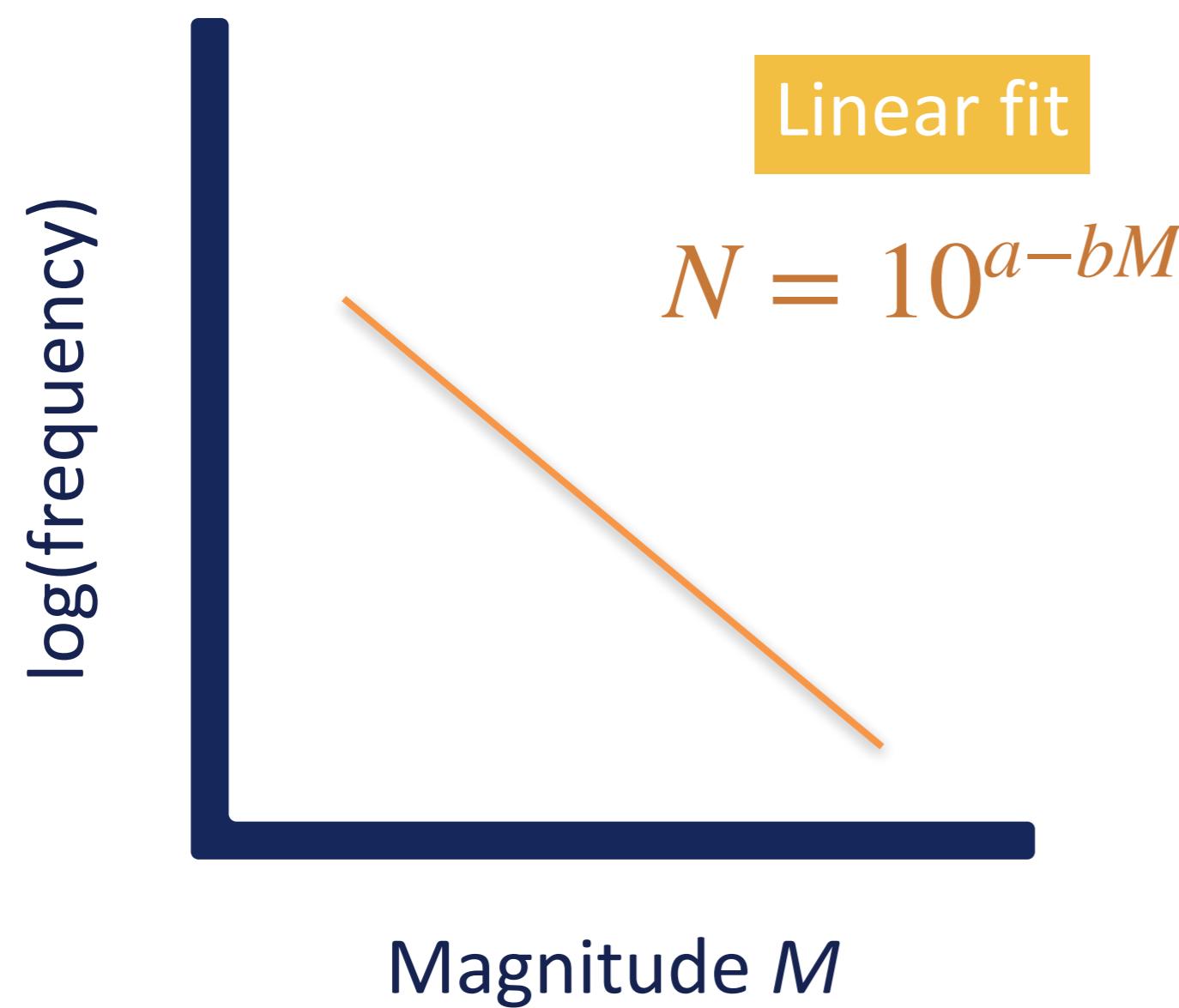


1 every 10 years
1 every 100 years
1 every 1000 years

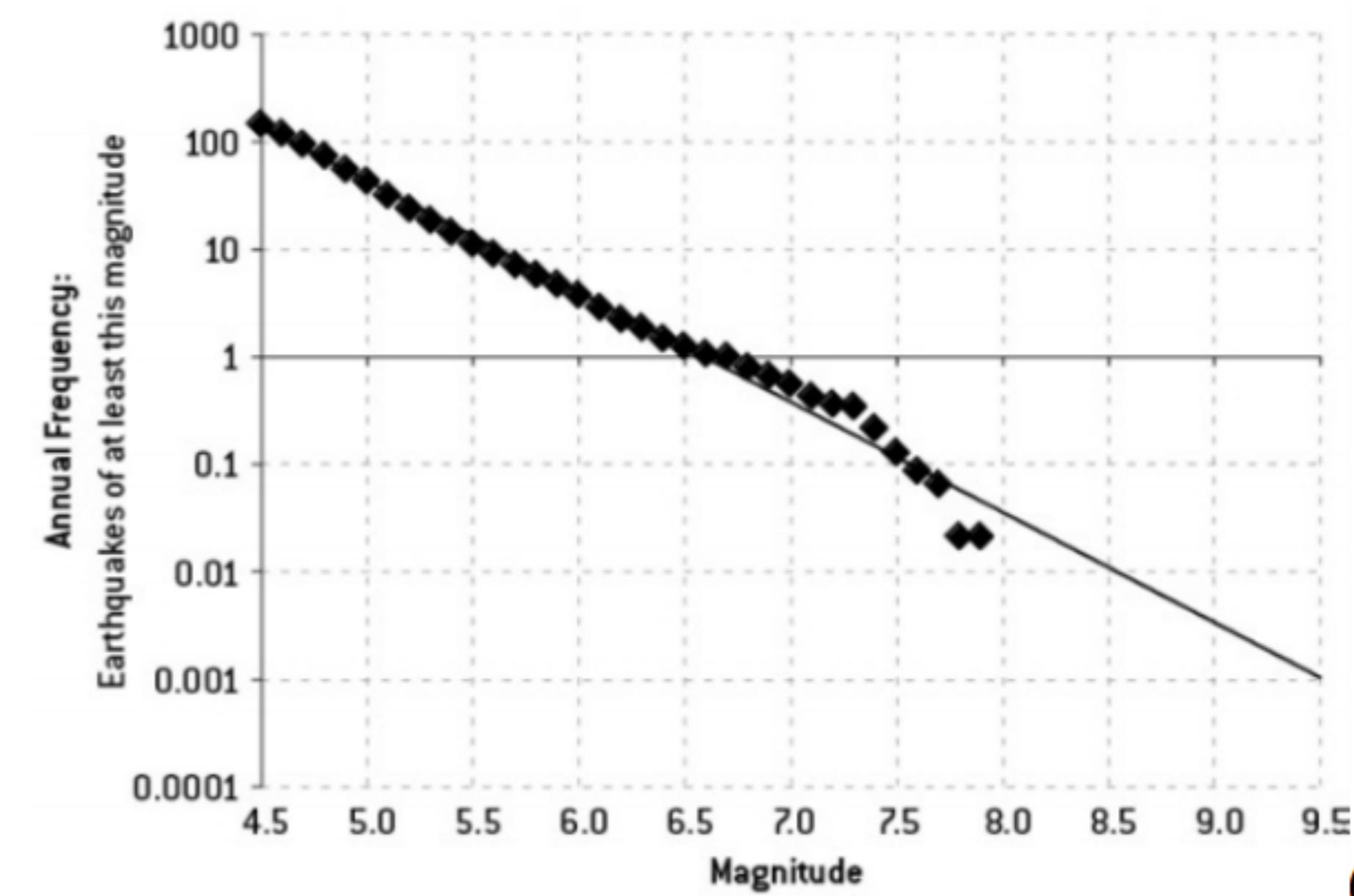
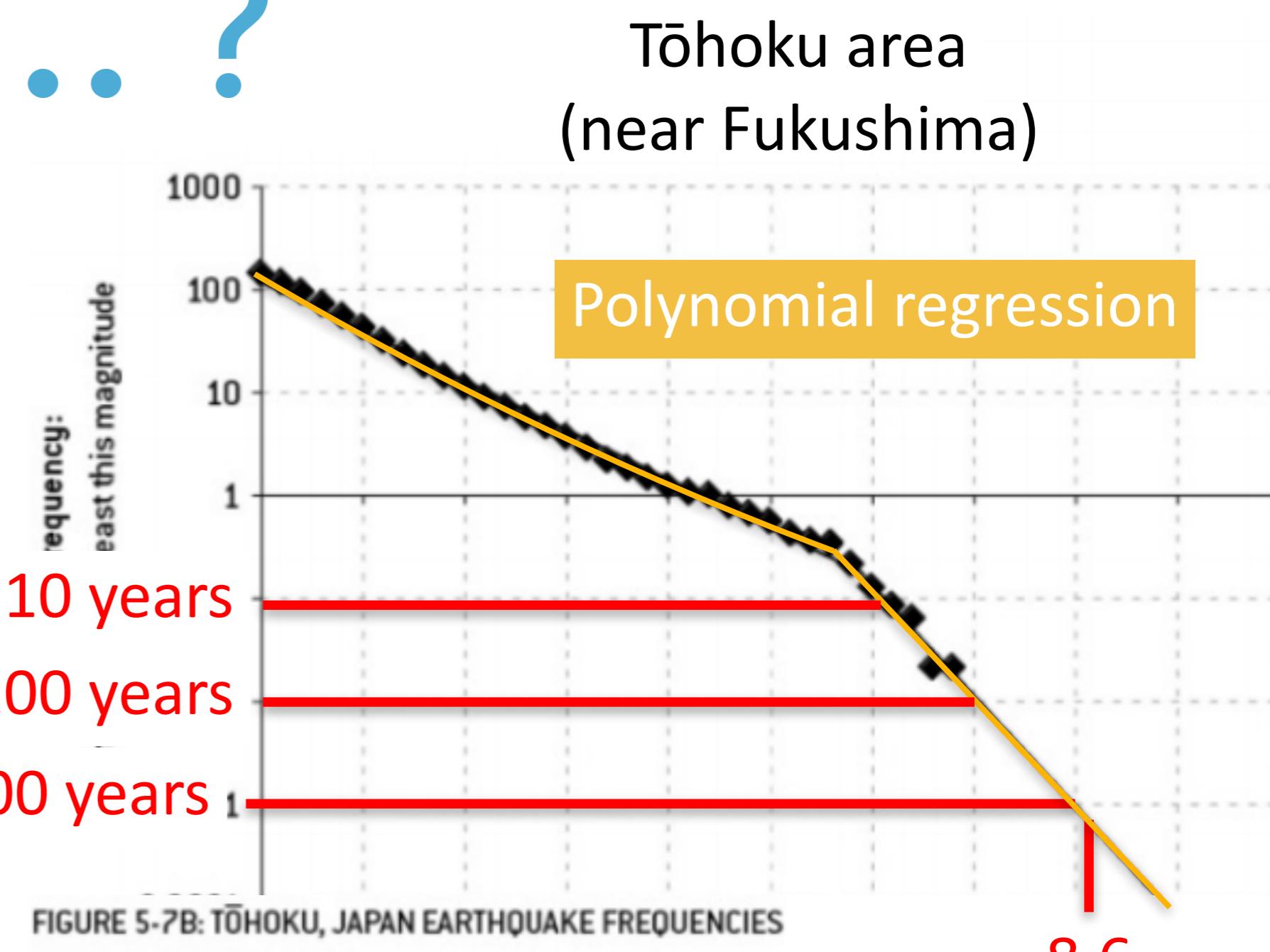


Not enough data ... ?

Earthquake frequency:
The Gutenberg-Richter Law

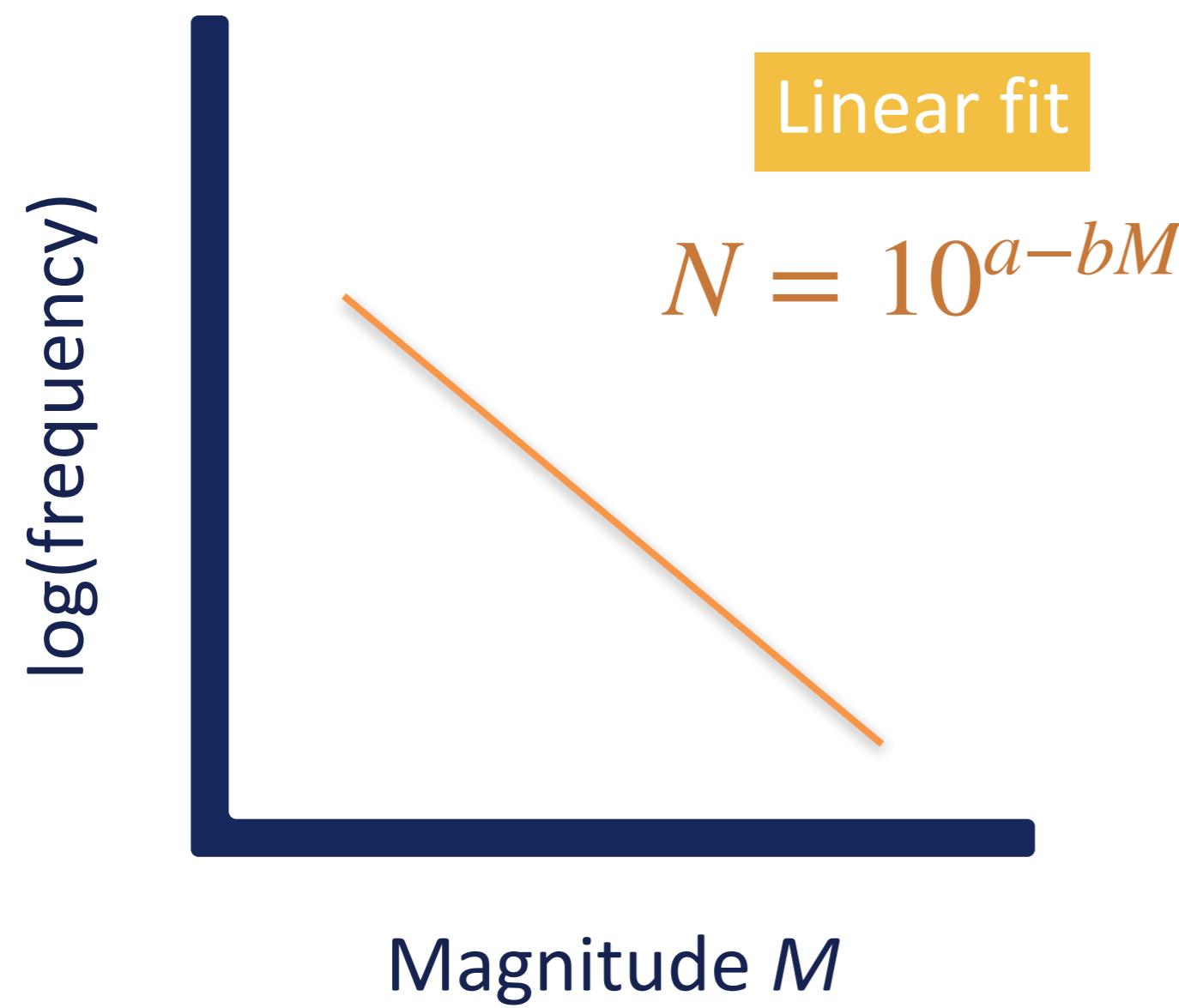


1 every 10 years
1 every 100 years
1 every 1000 years



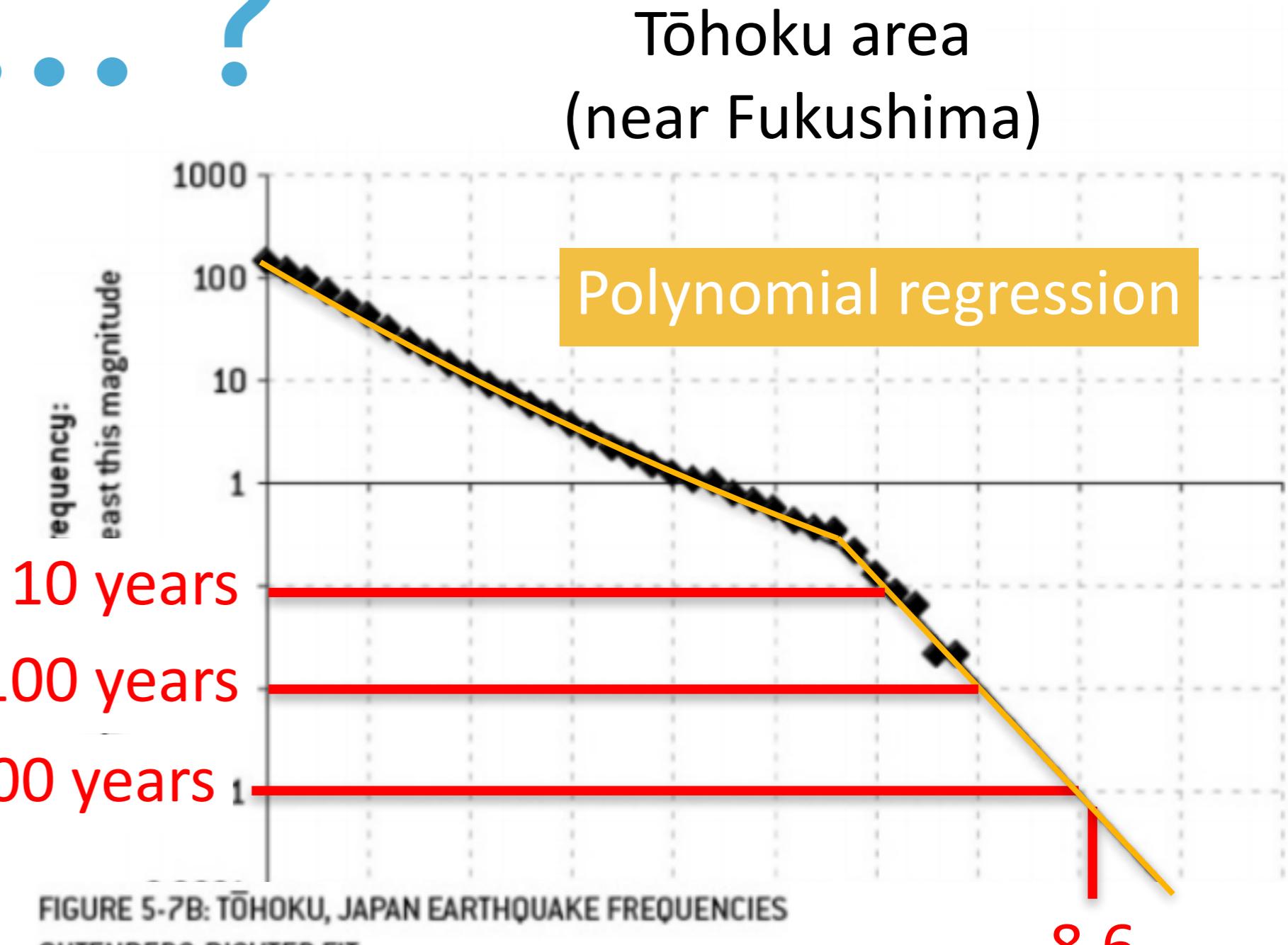
Not enough data ... ?

Earthquake frequency:
The Gutenberg-Richter Law

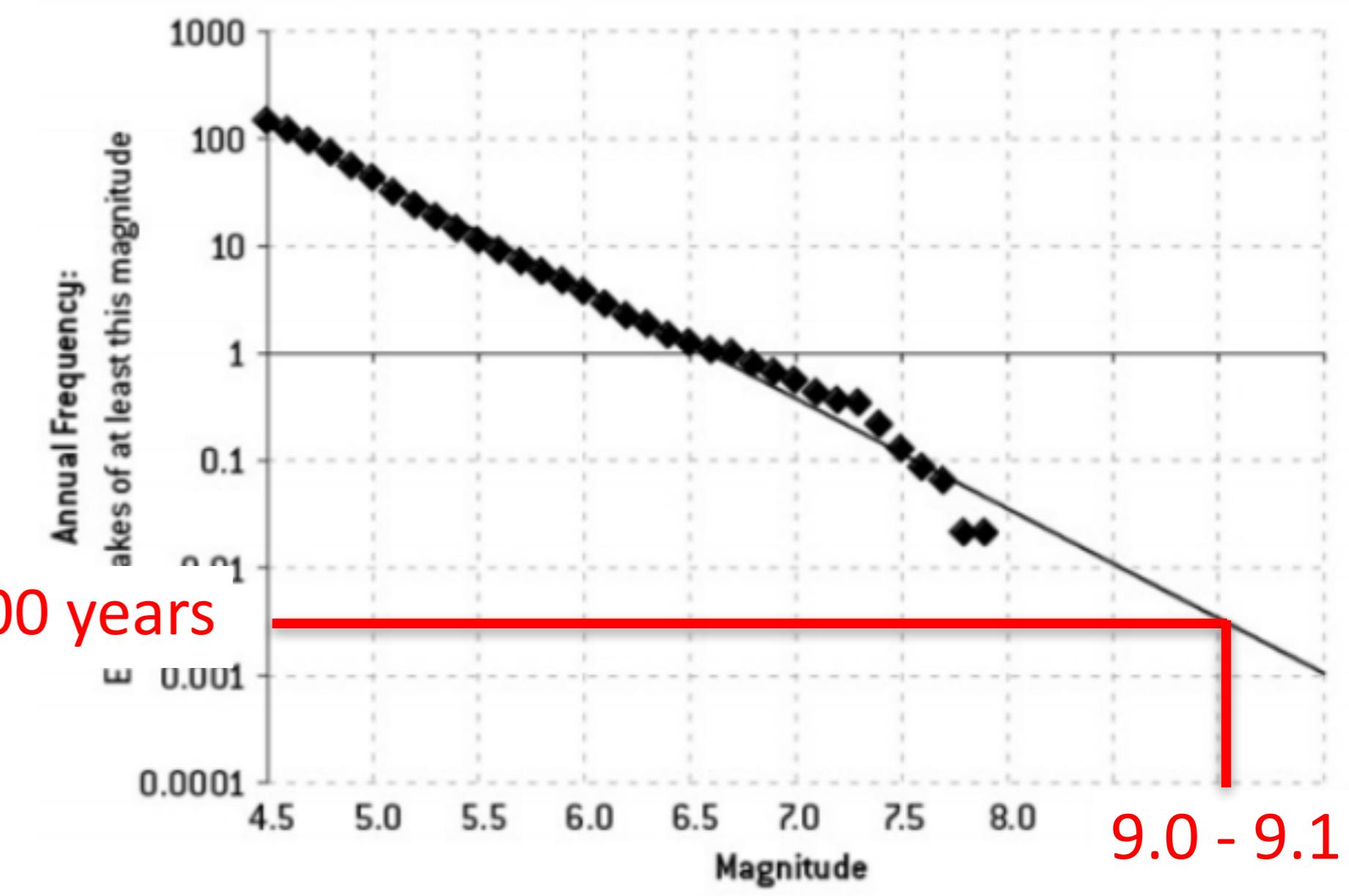


1 every 10 years
1 every 100 years
1 every 1000 years

FIGURE 5-7B: TŌHOKU, JAPAN EARTHQUAKE FREQUENCIES
GUTENBERG-RICHTER FIT

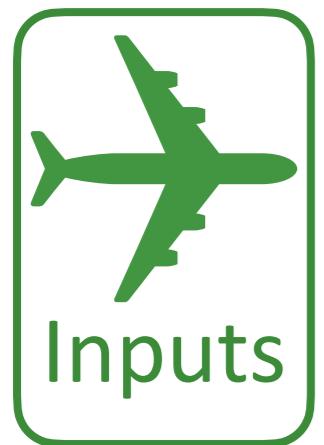


1 every ~ 300 years

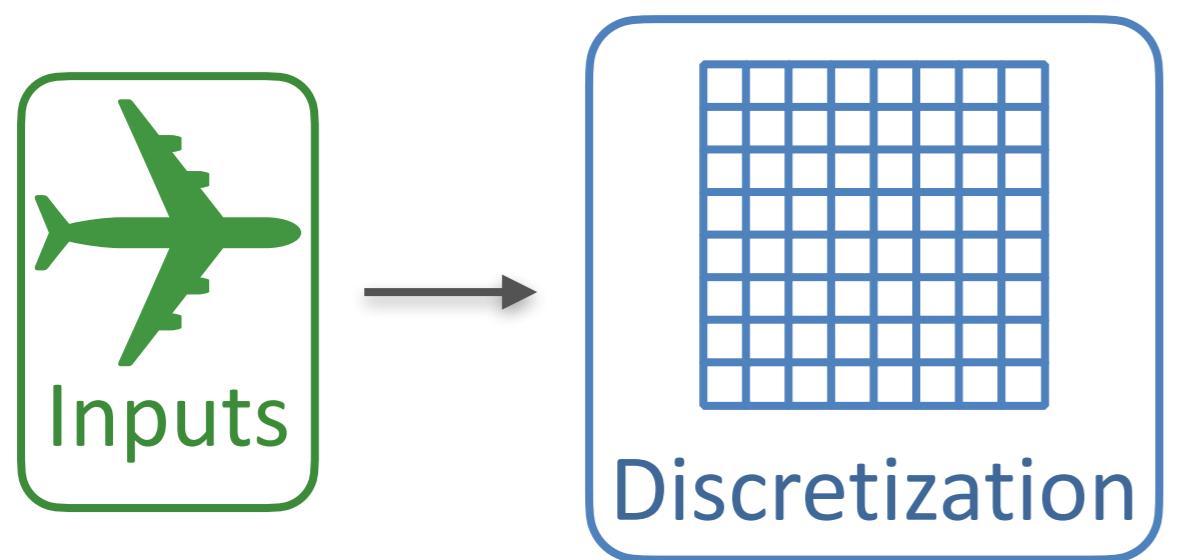


Case Studies of AI in CFD

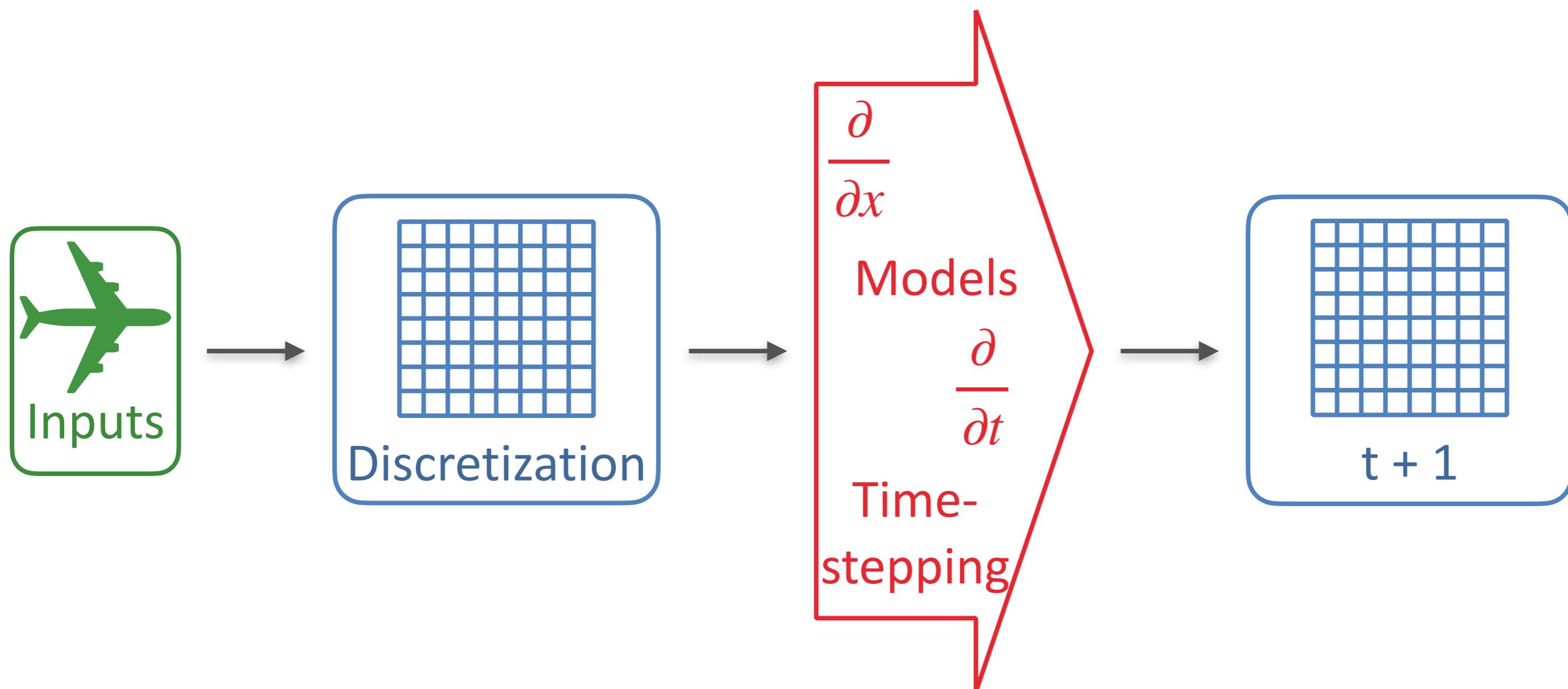
AI for « better » CFD...?



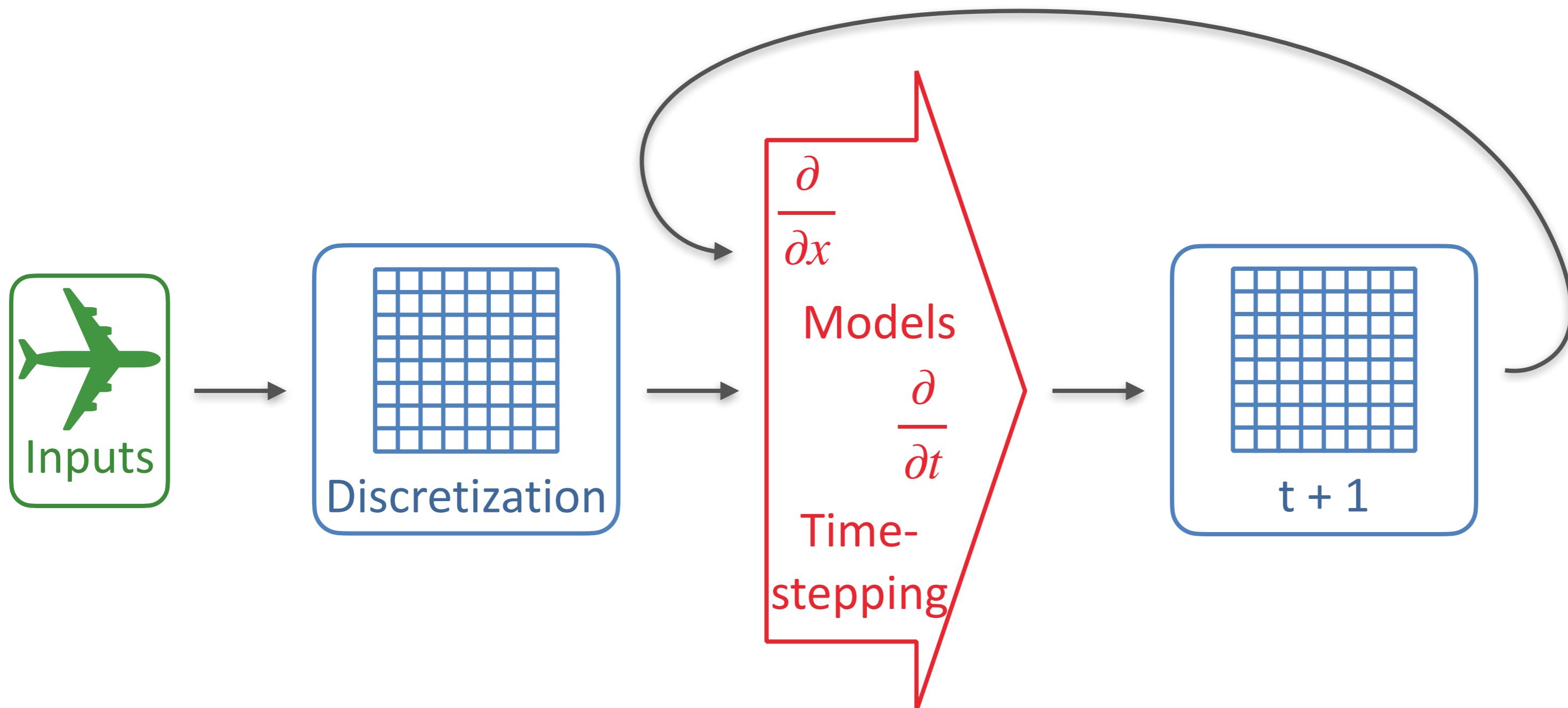
AI for « better » CFD...?



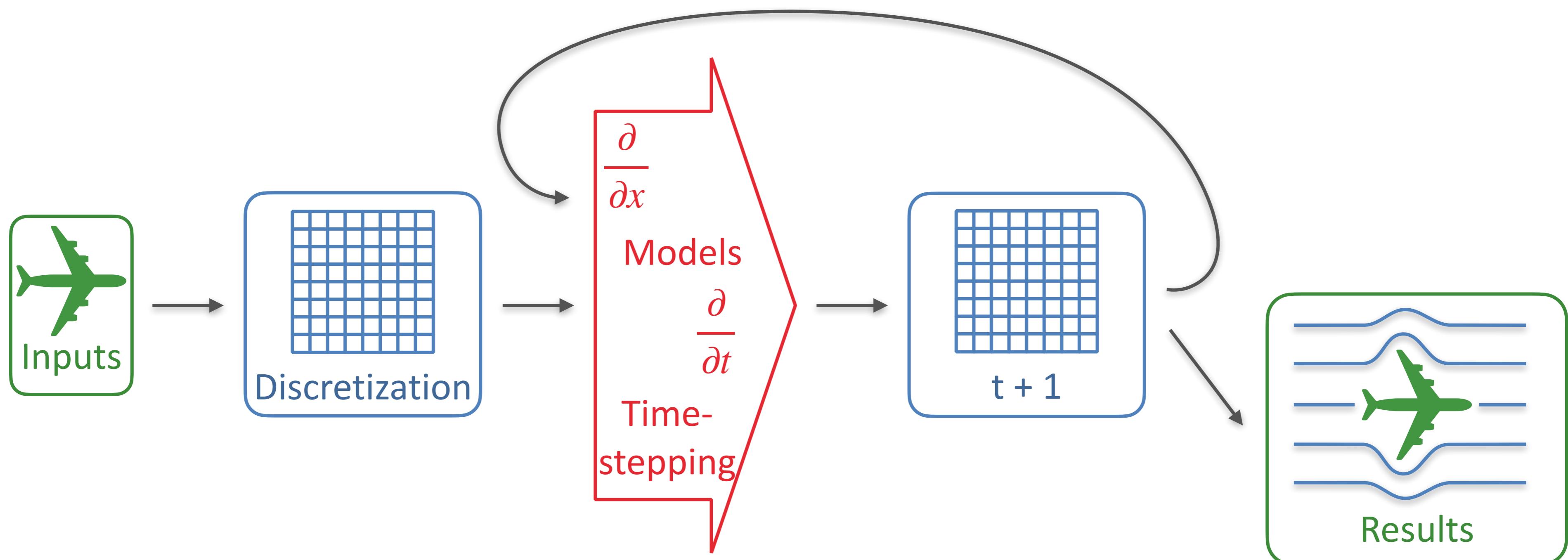
AI for « better » CFD...?



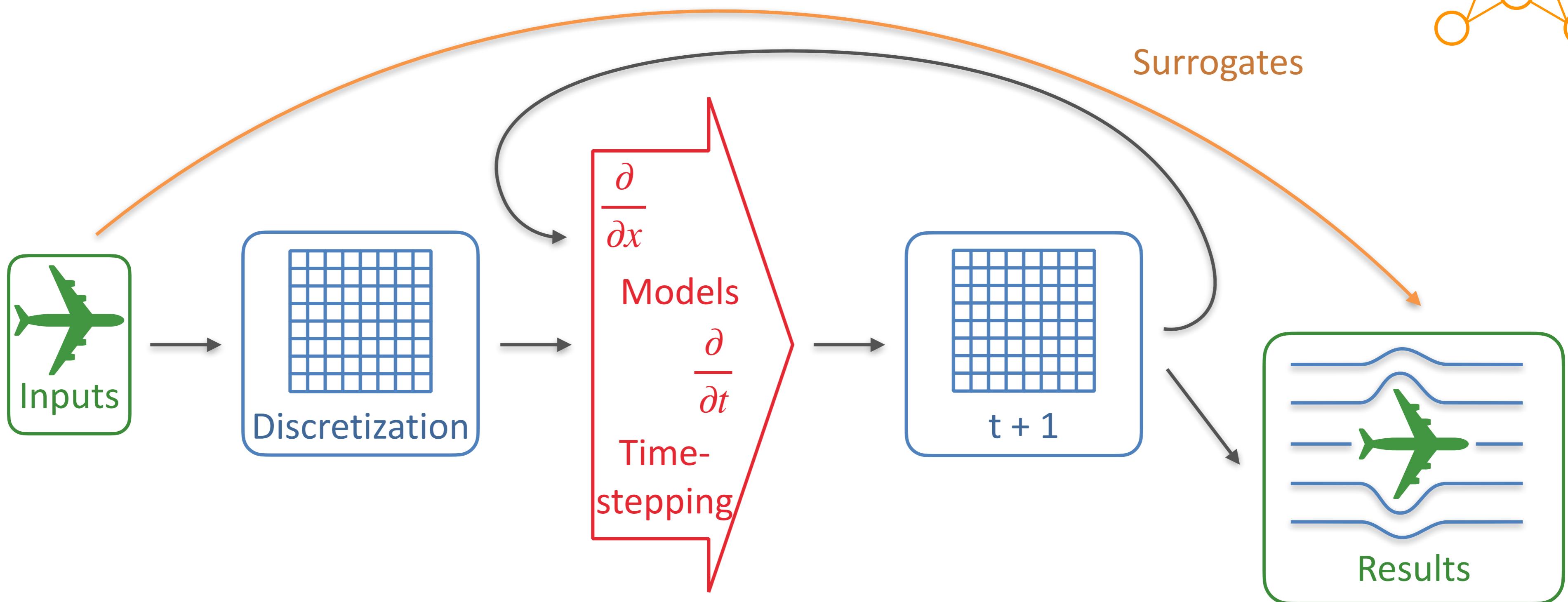
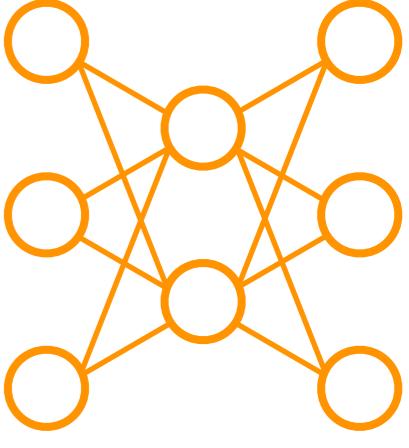
AI for « better » CFD...?



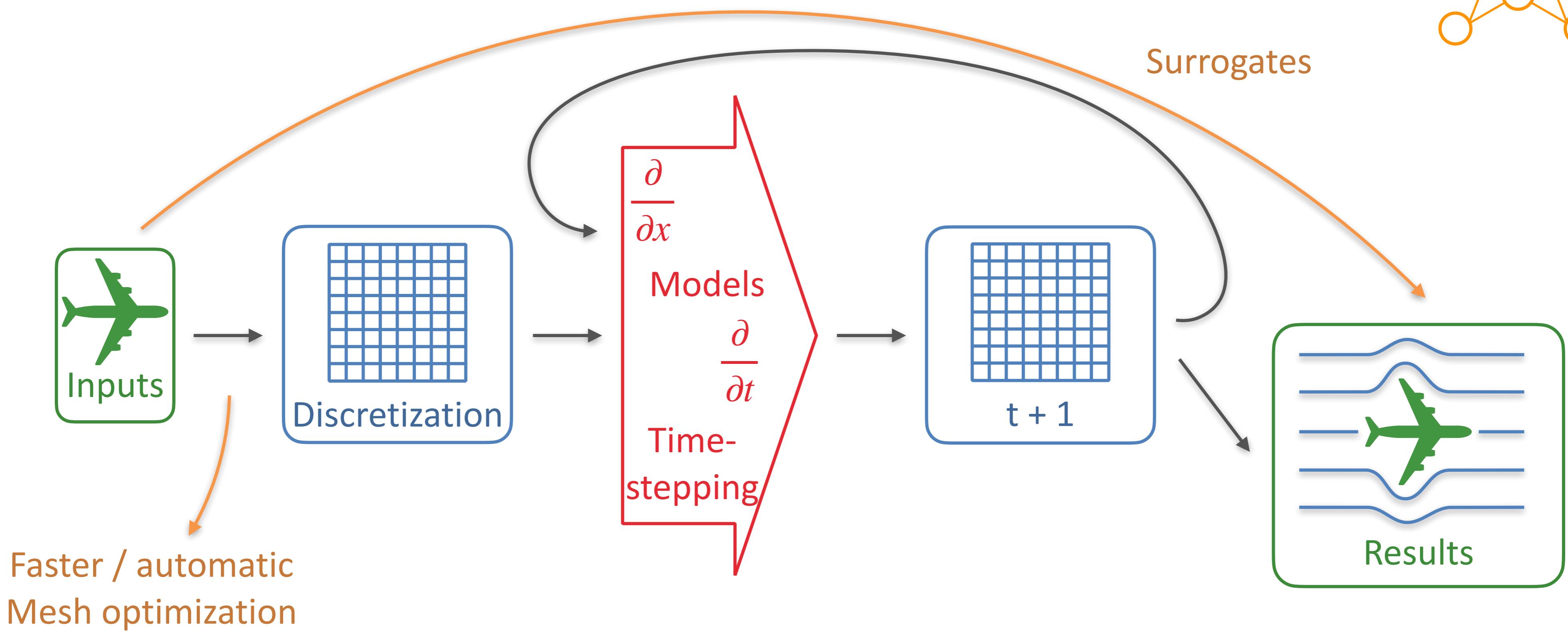
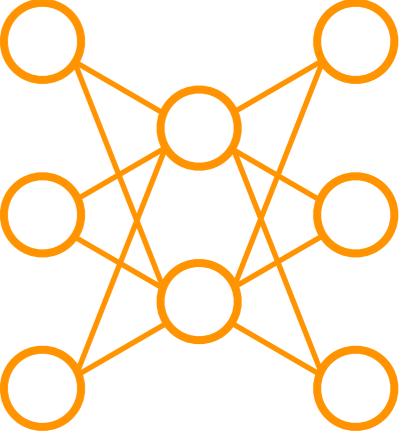
AI for « better » CFD...?



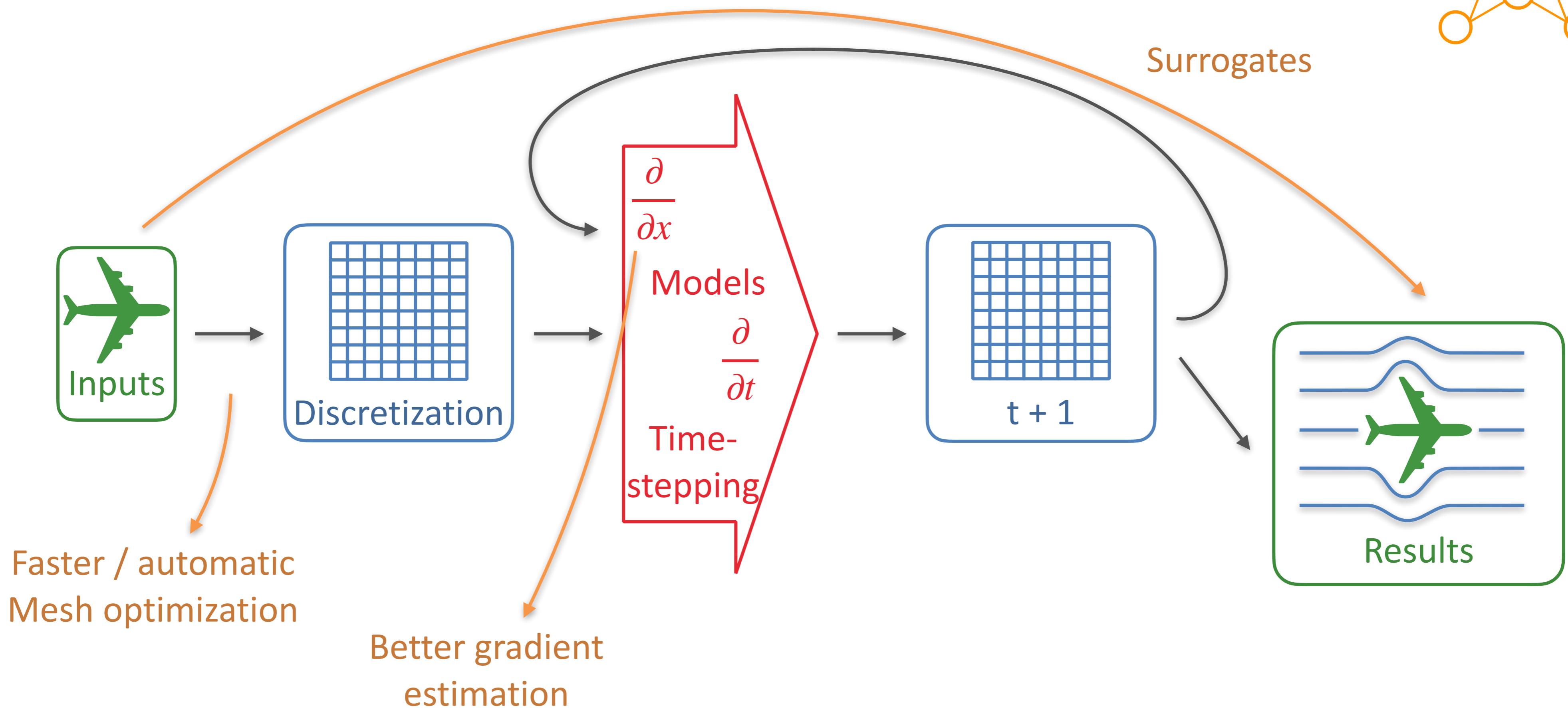
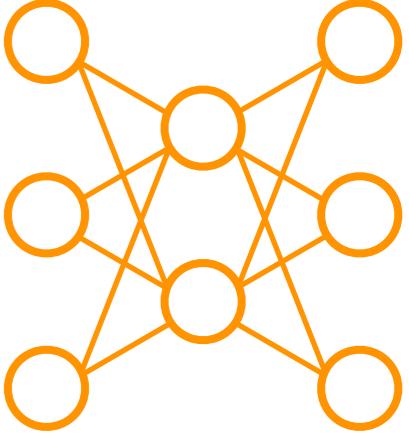
AI for « better » CFD...?



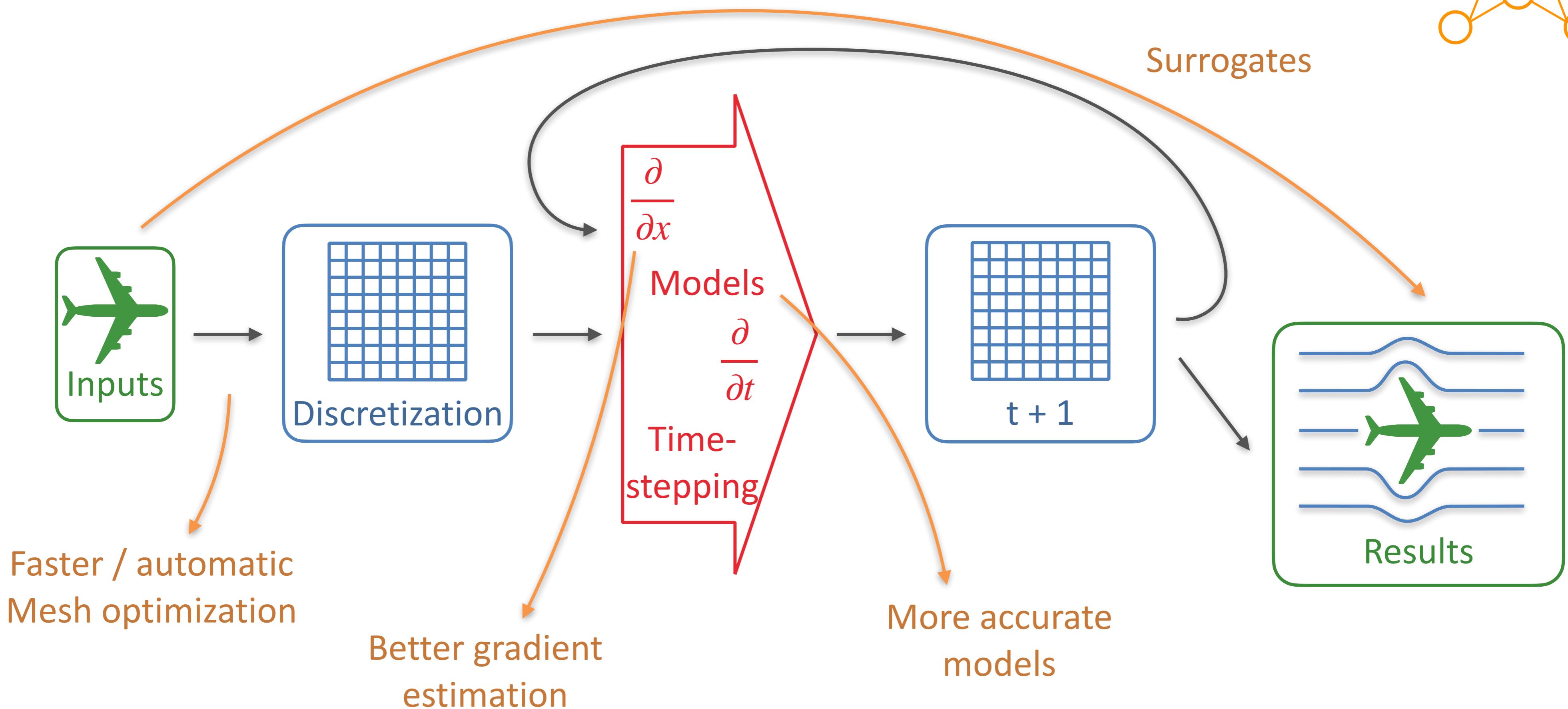
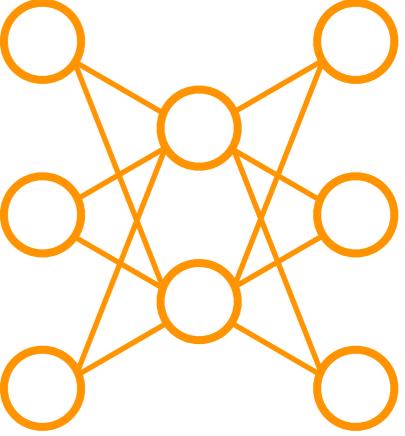
AI for « better » CFD...?



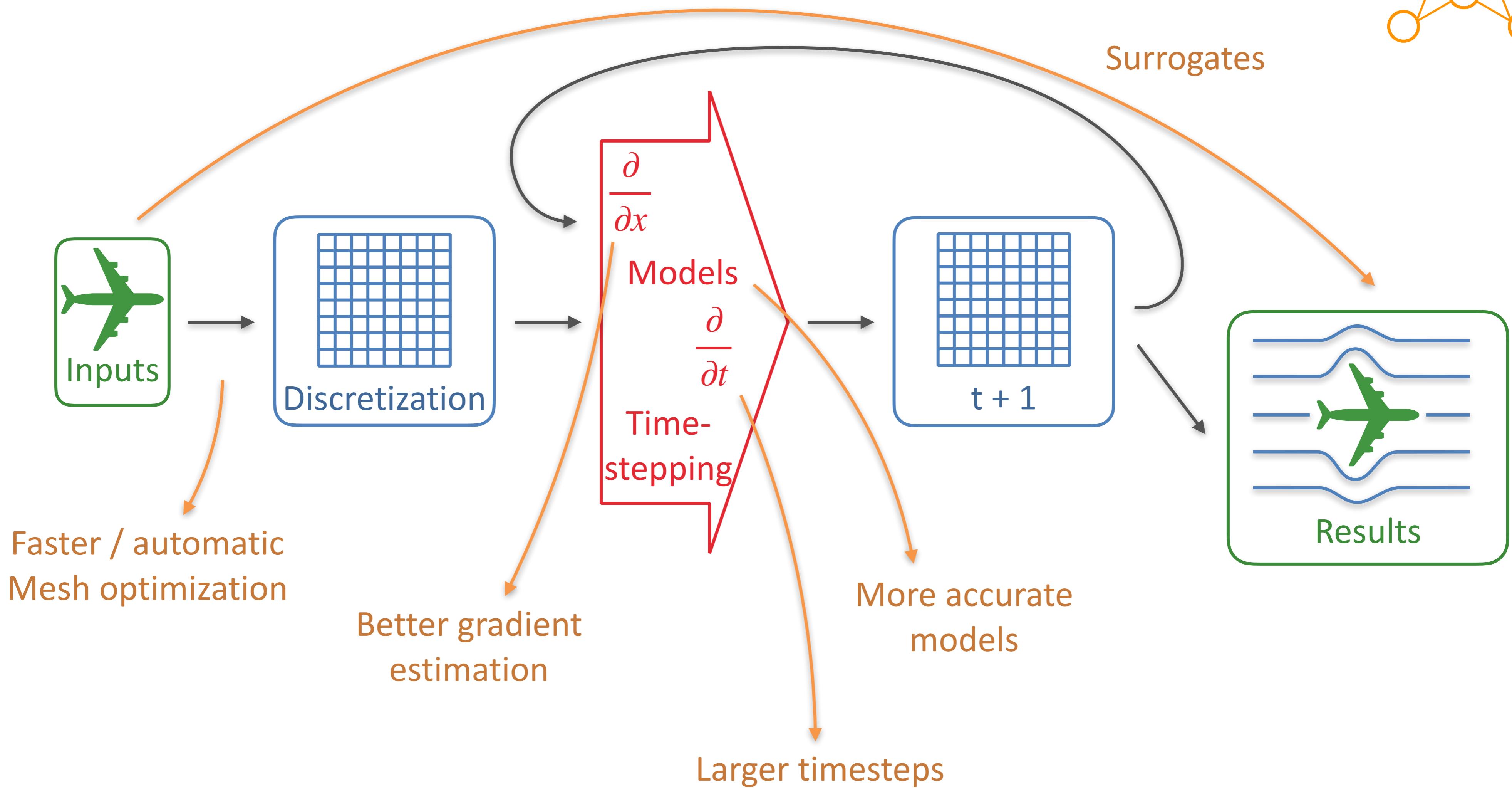
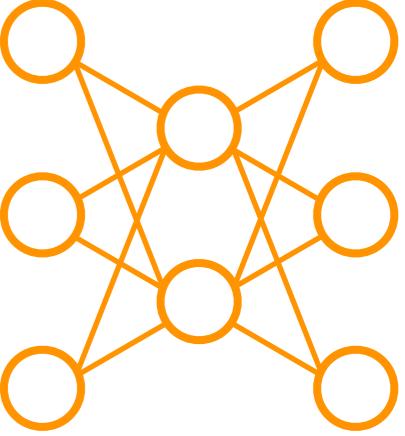
AI for « better » CFD...?



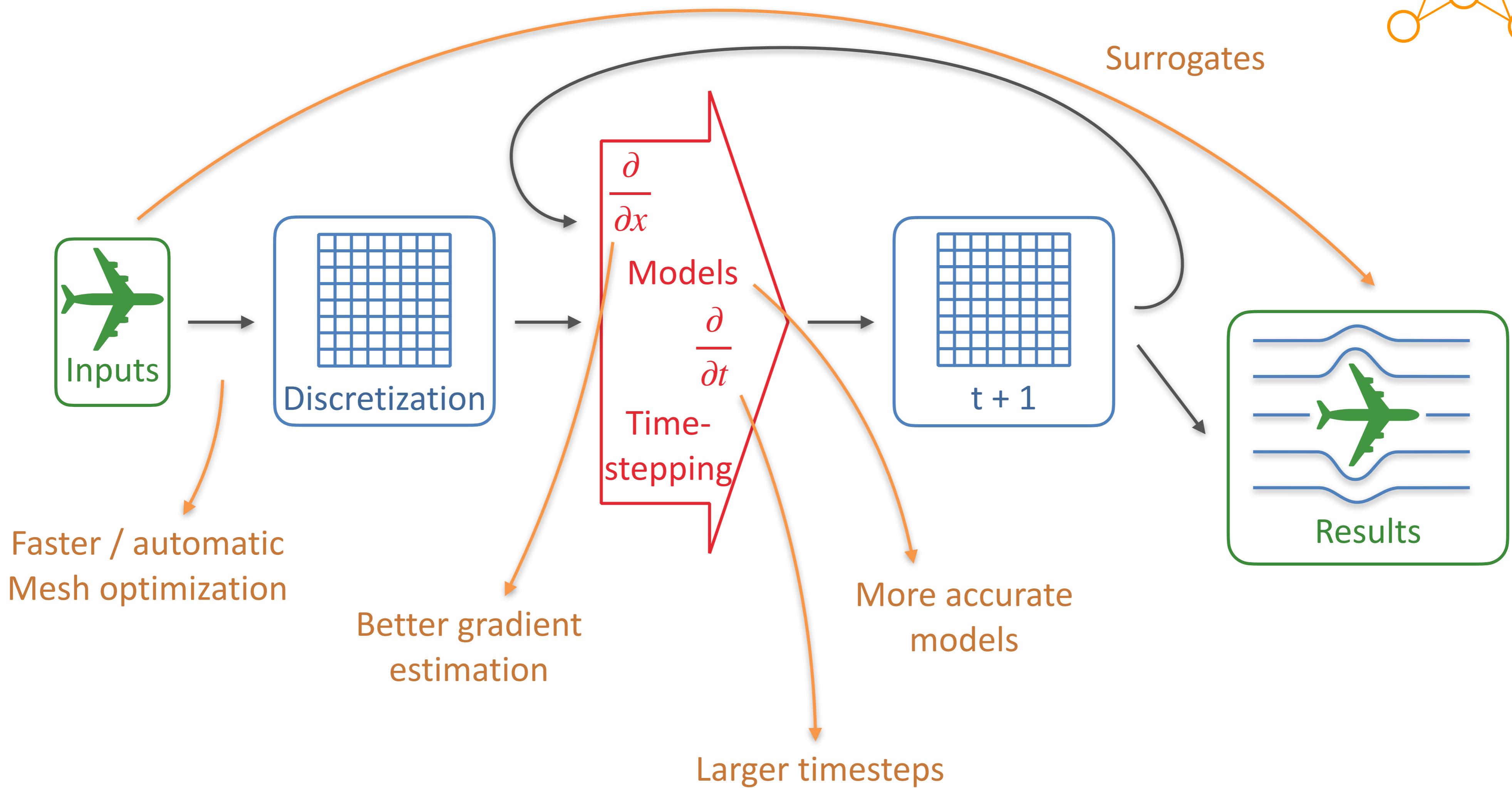
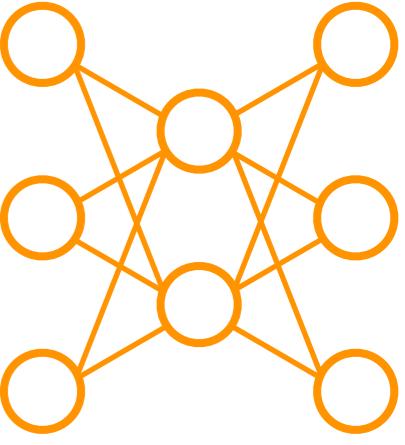
AI for « better » CFD...?



AI for « better » CFD...?

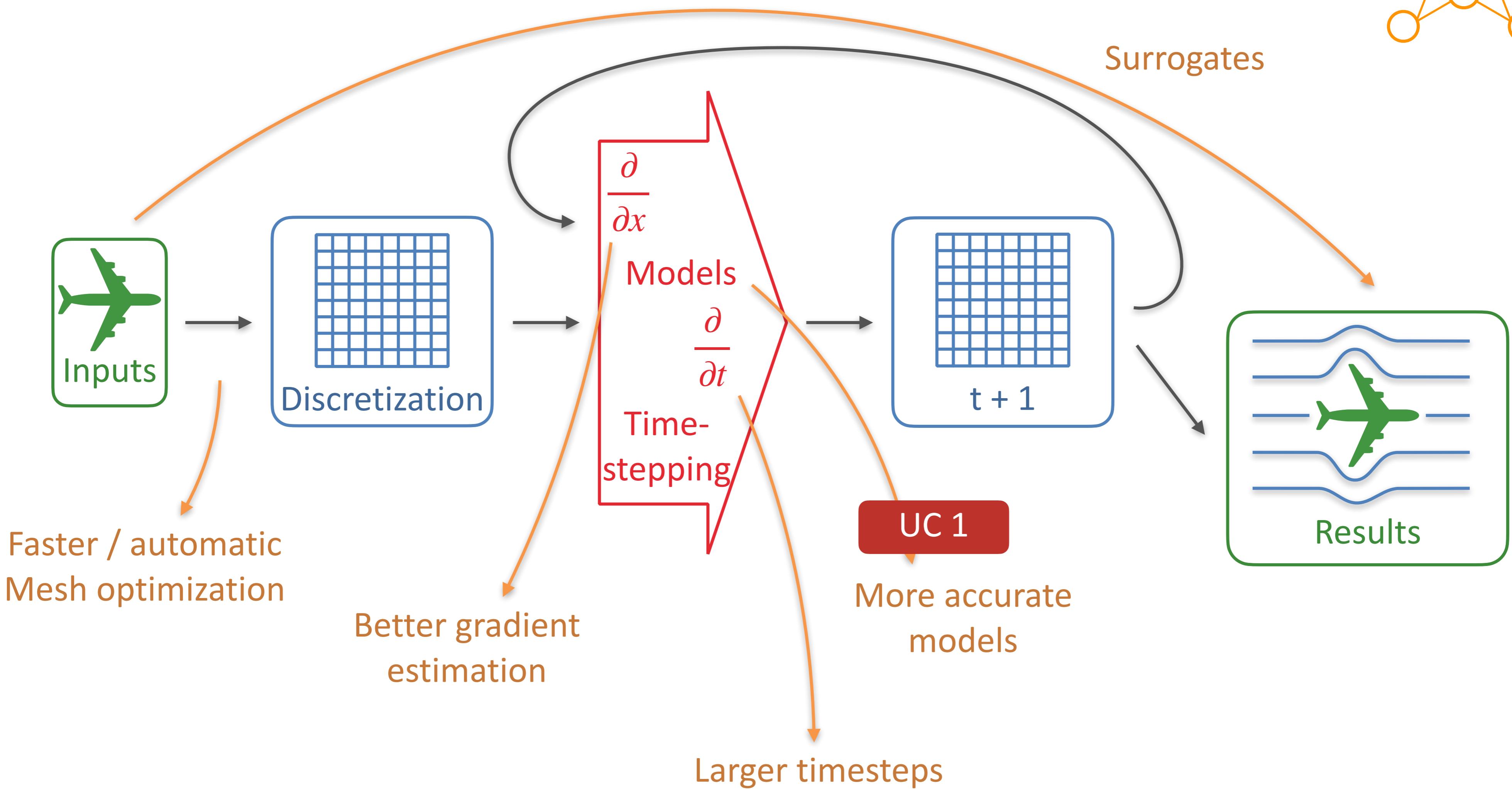
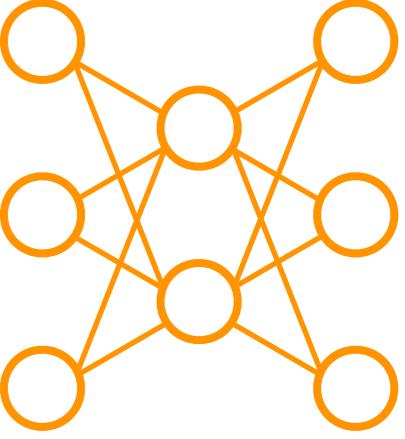


AI for « better » CFD...?



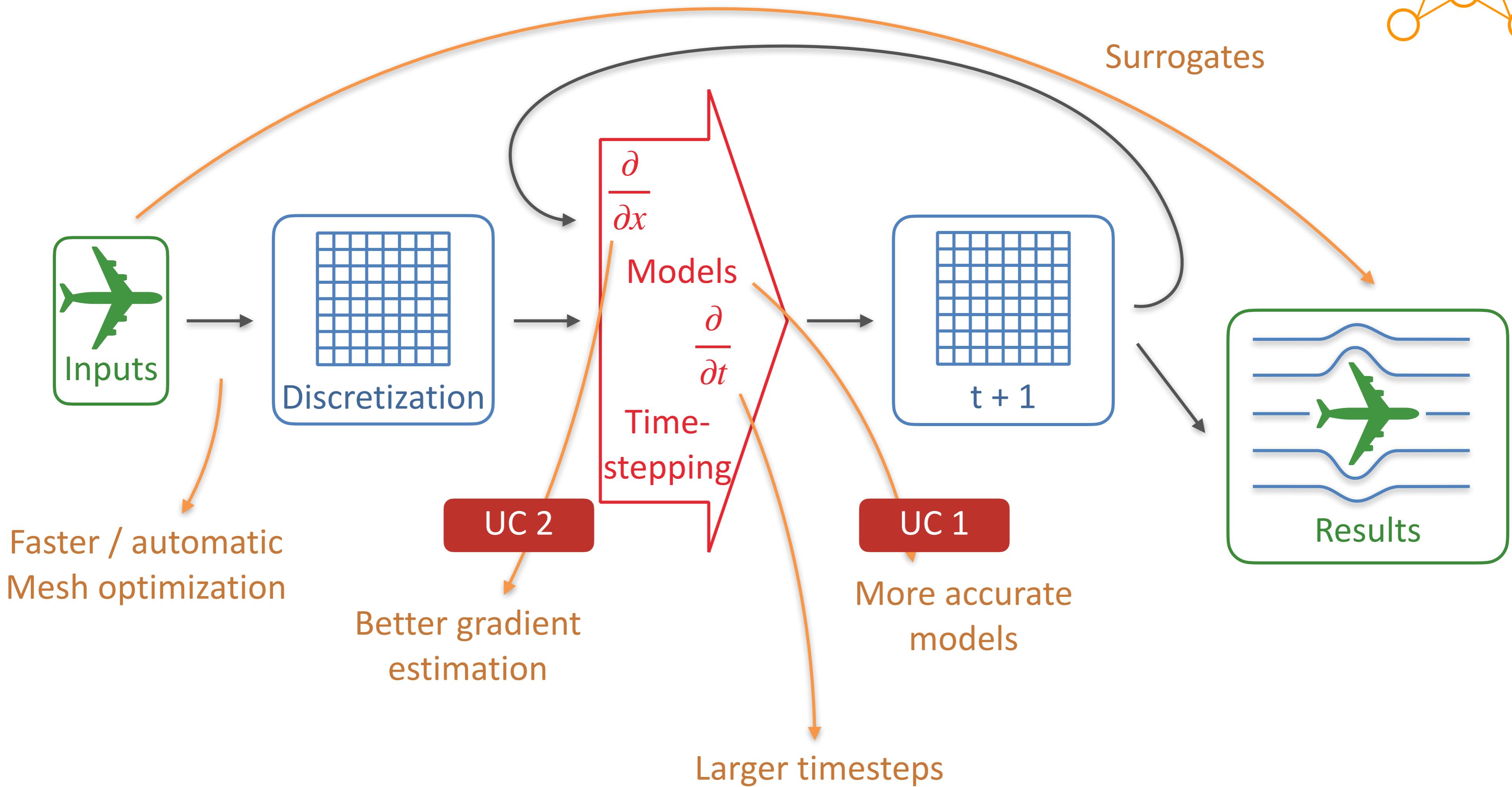
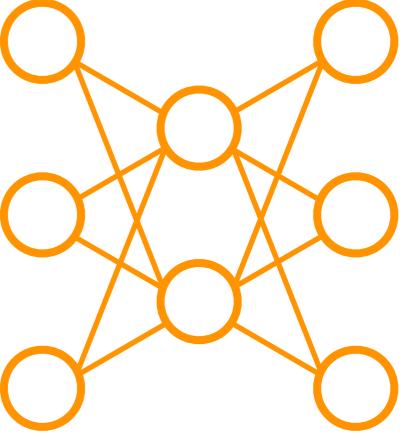
- Many degrees of AI « intrusion » in CFD are possible
- It is not yet clear which is the best way to go!

AI for « better » CFD...?

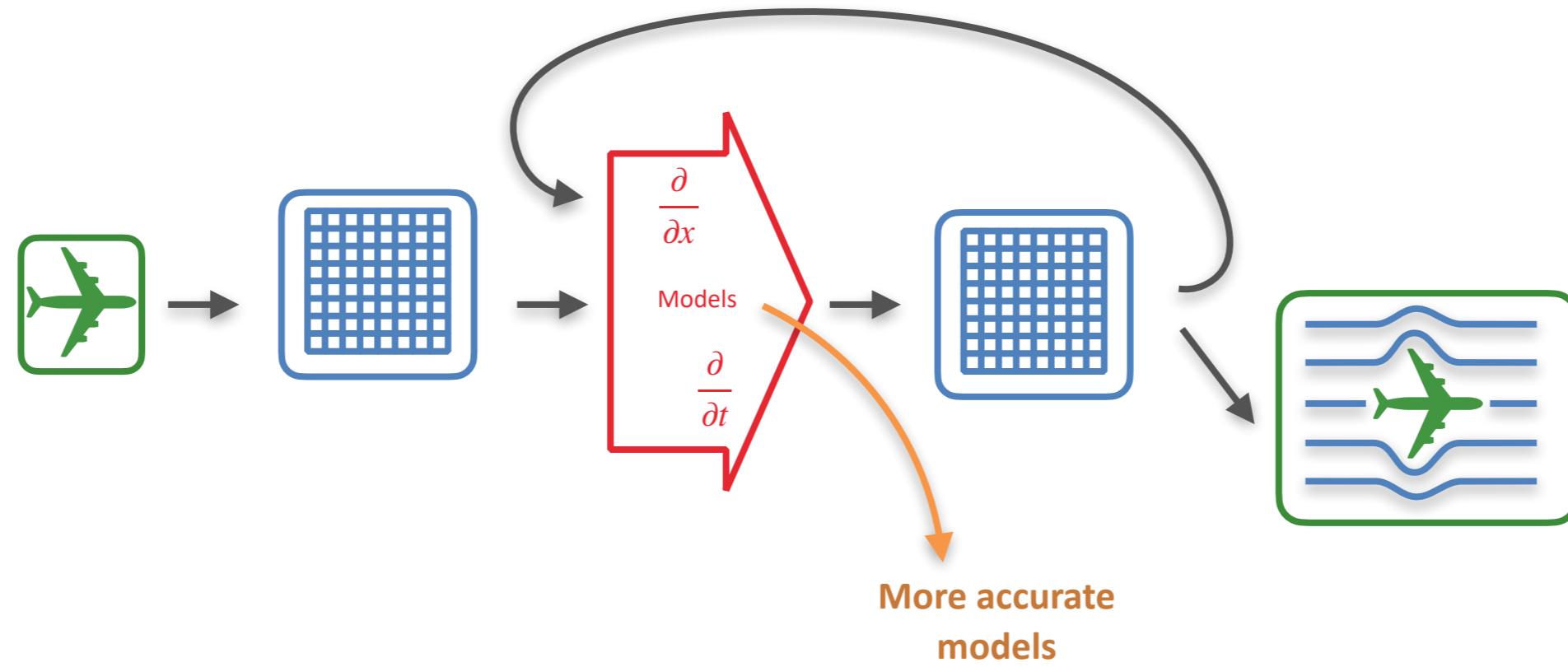


- Many degrees of AI « intrusion » in CFD are possible
- It is not yet clear which is the best way to go!

AI for « better » CFD...?



- Many degrees of AI « intrusion » in CFD are possible
- It is not yet clear which is the best way to go!



1. Subgrid-scale modeling with CNNs

Ongoing PhD of Victor Xing, Cerfacs

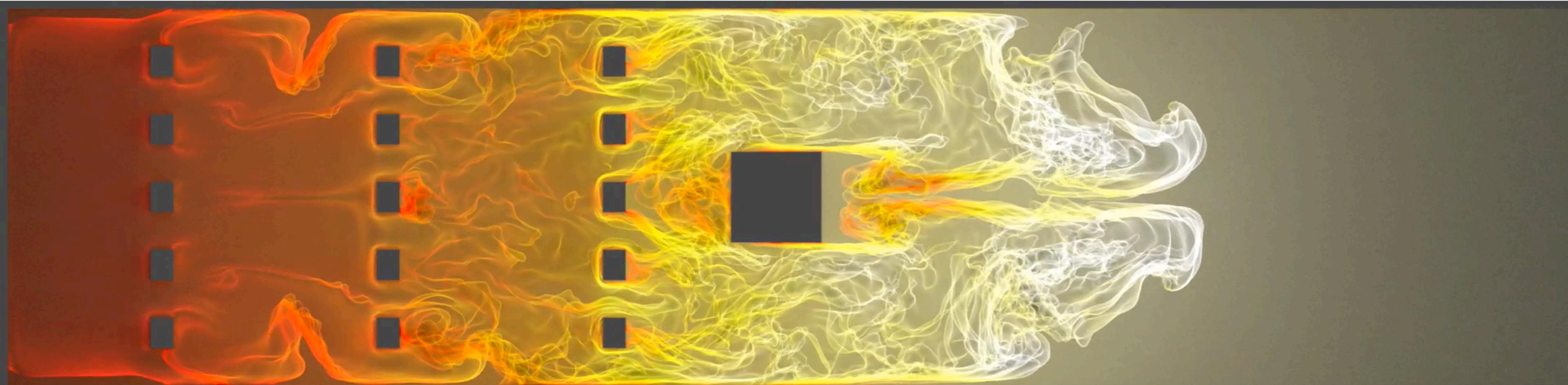
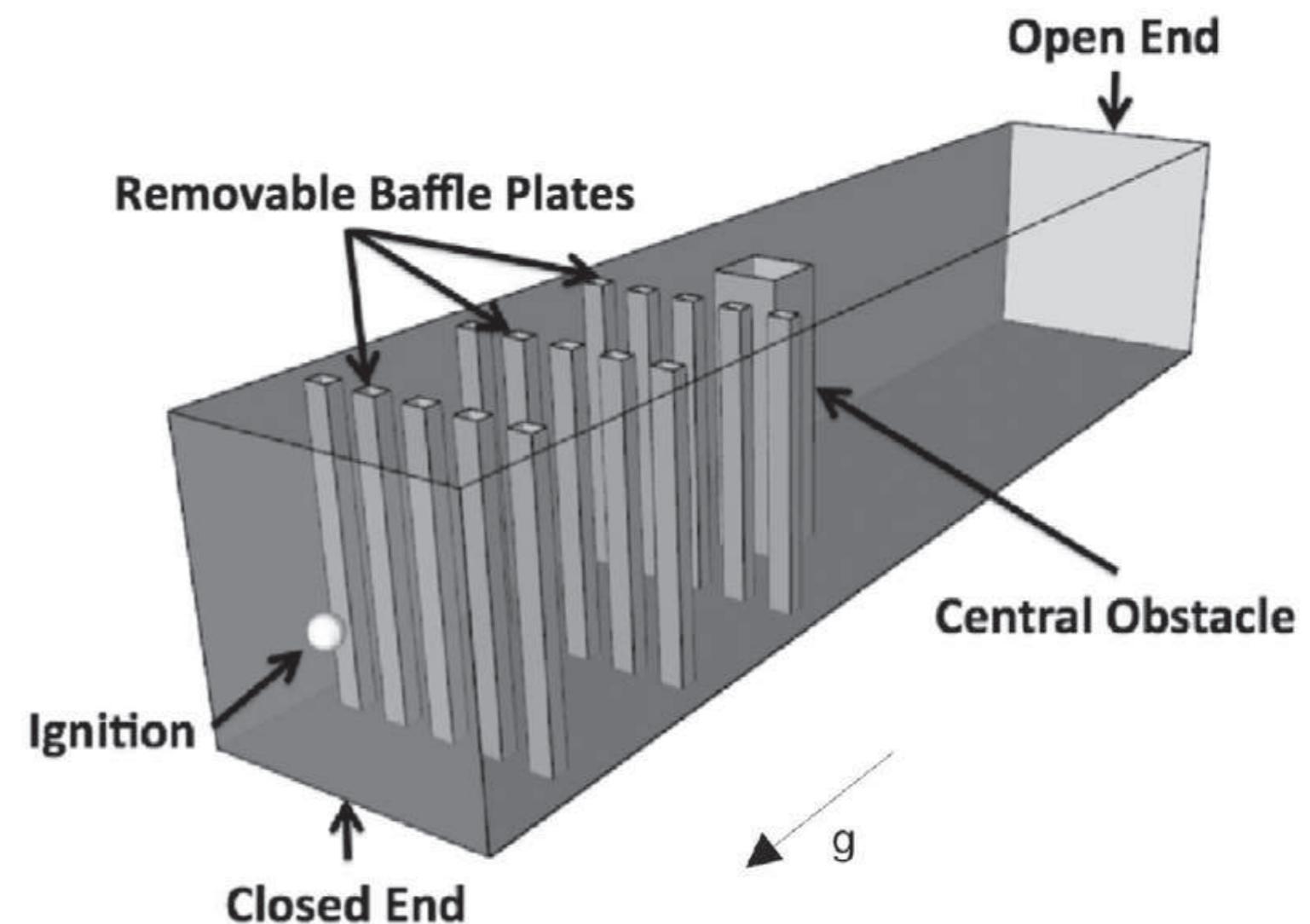
Lapeyre, C.J., Misdariis, A., Cazard, N. & Poinsot, T (2018). A-posteriori evaluation of a deep convolutional neural network approach to subgrid-scale flame surface estimation. Proc. CTR Summer Program, 349-358.

Lapeyre, C.J., Misdariis, A., Cazard, N., Veynante, D. & Poinsot, T. (2019). Training convolutional neural networks to estimate turbulent sub-grid scale reaction rates. *Combustion and Flame*, 203, 255-264



Very large scale combustion

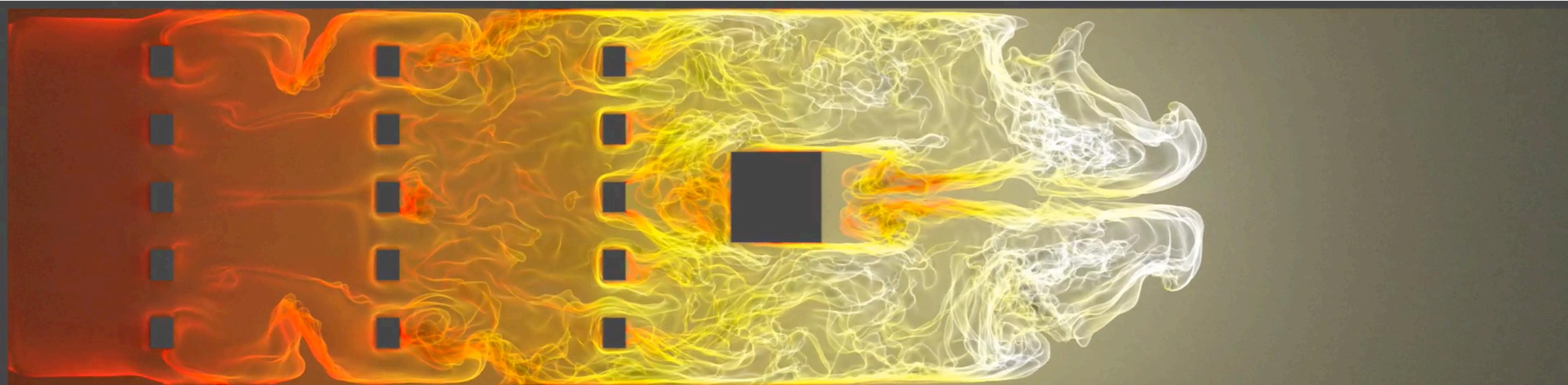
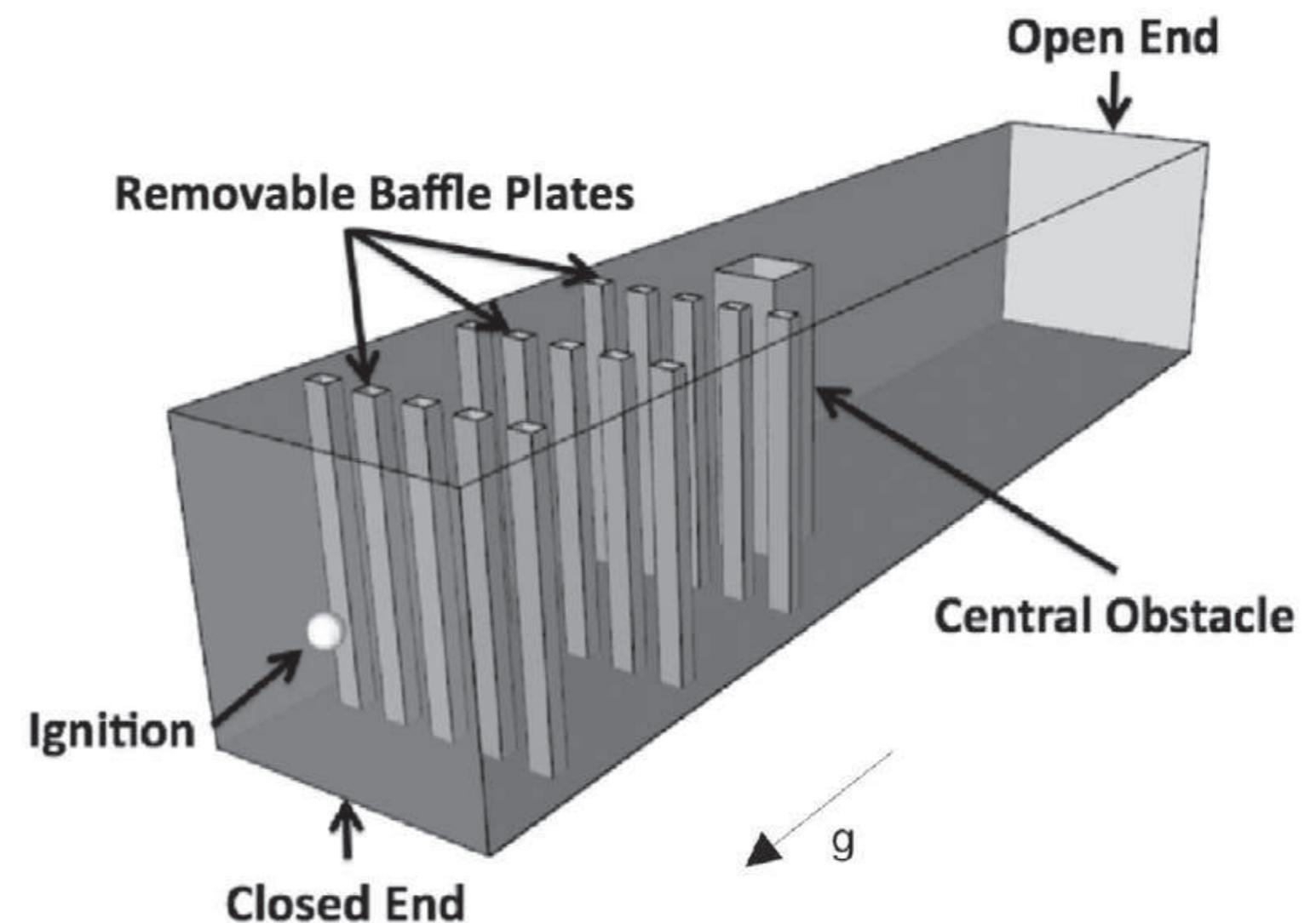
- Context: safety of industrial complexes in combustible gas leaks
- Reactive LES of very large domains



Elsa Gullaud, Post-Doc 2019

Very large scale combustion

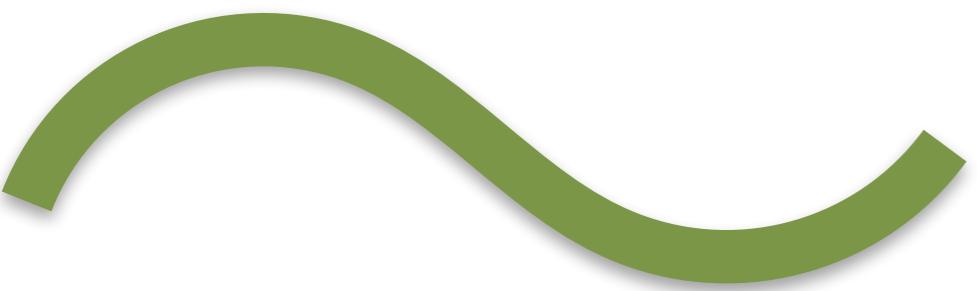
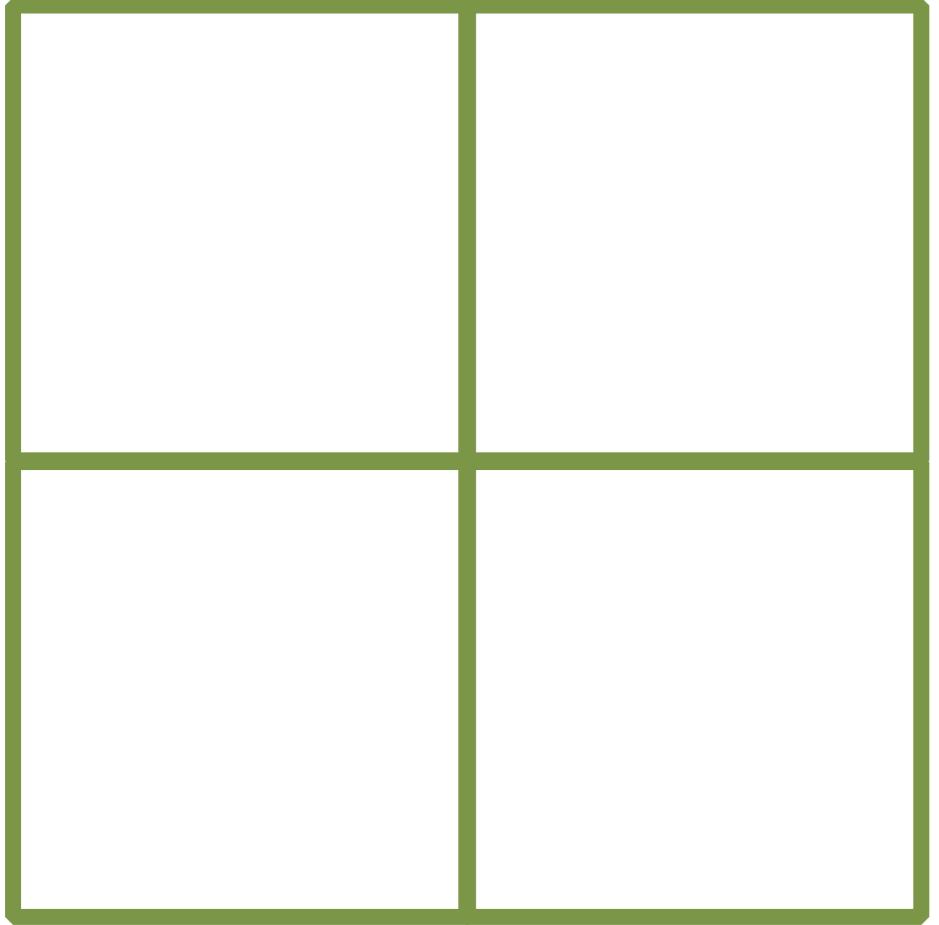
- Context: safety of industrial complexes in combustible gas leaks
- Reactive LES of very large domains



Elsa Gullaud, Post-Doc 2019

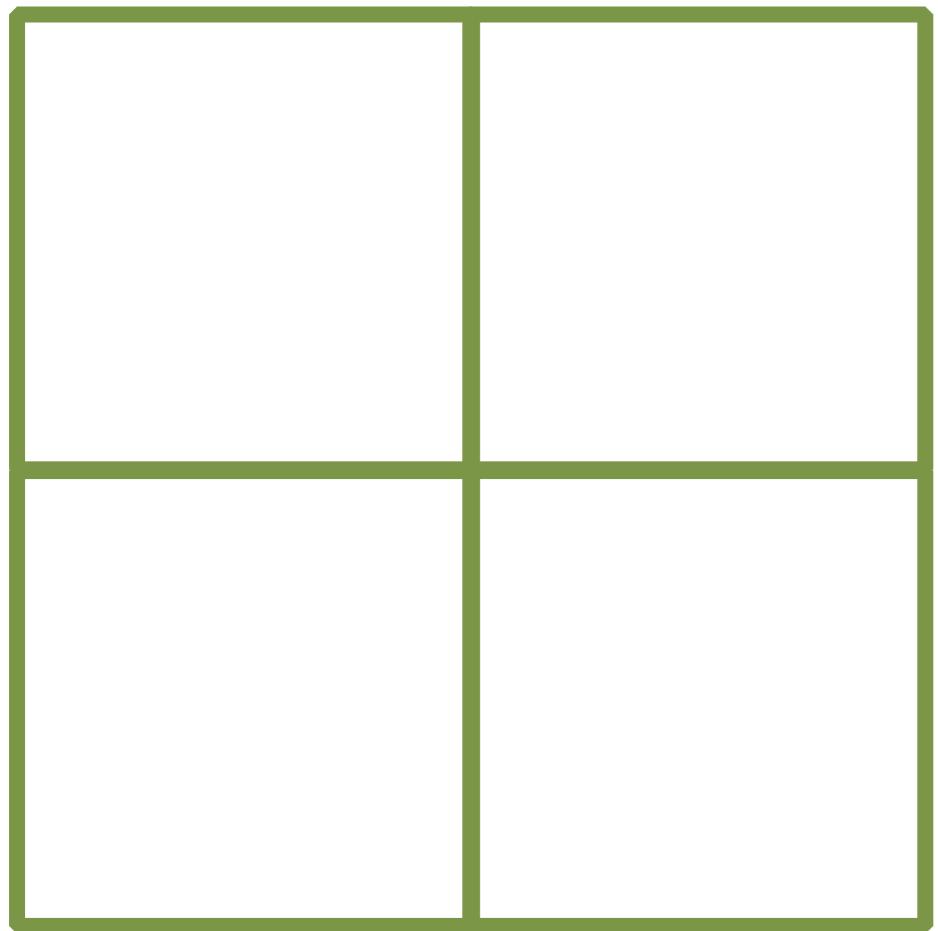
Subgrid-scale models

What I can pay for

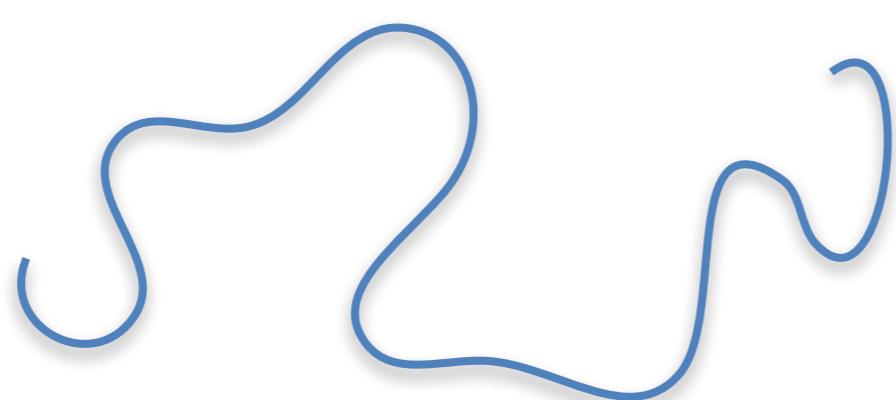
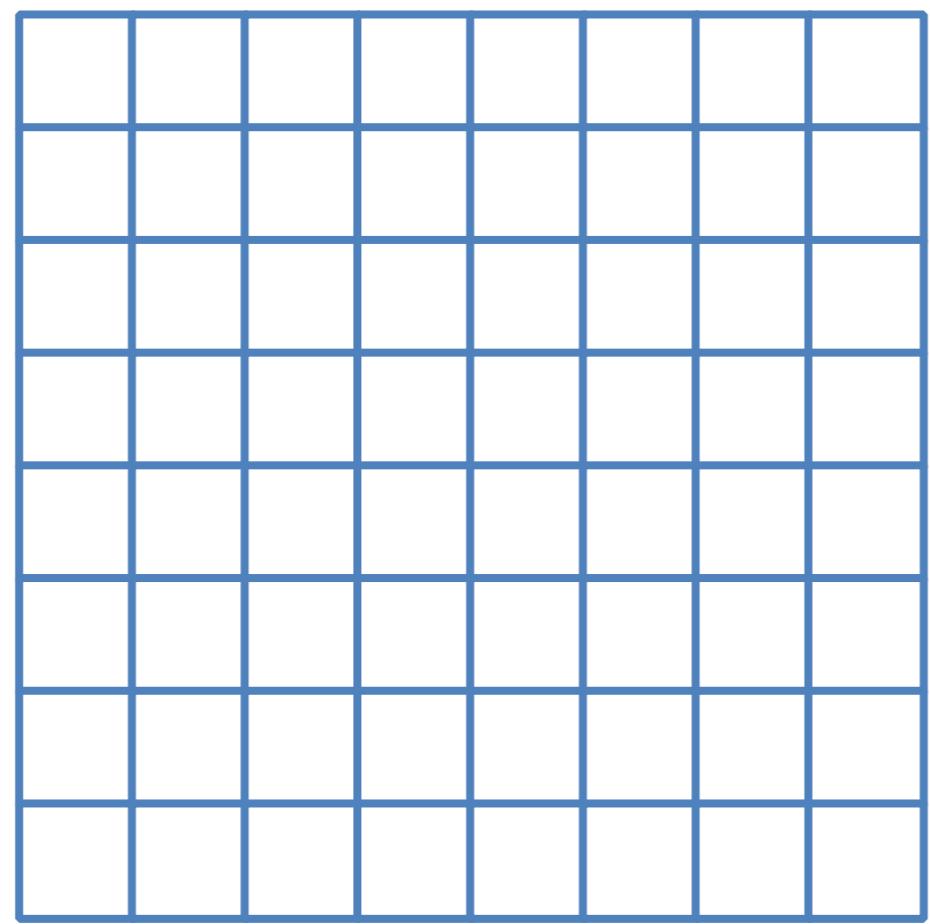


Subgrid-scale models

What I can pay for

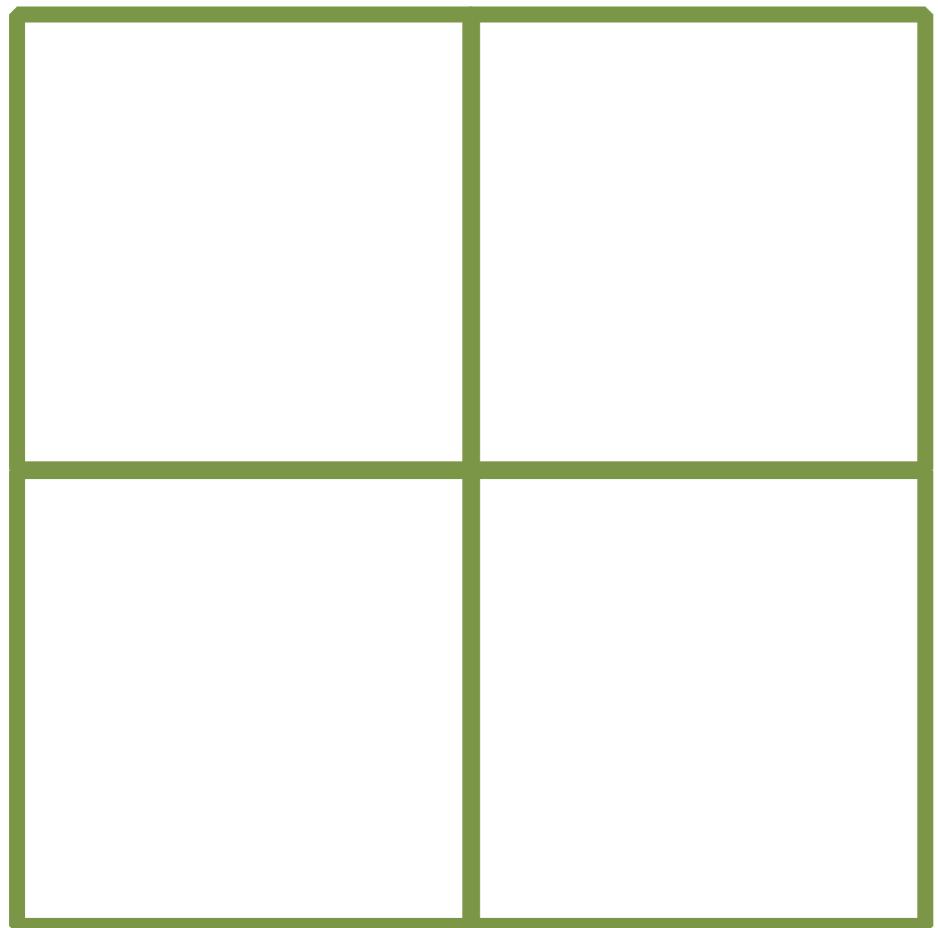


Fully resolved physics

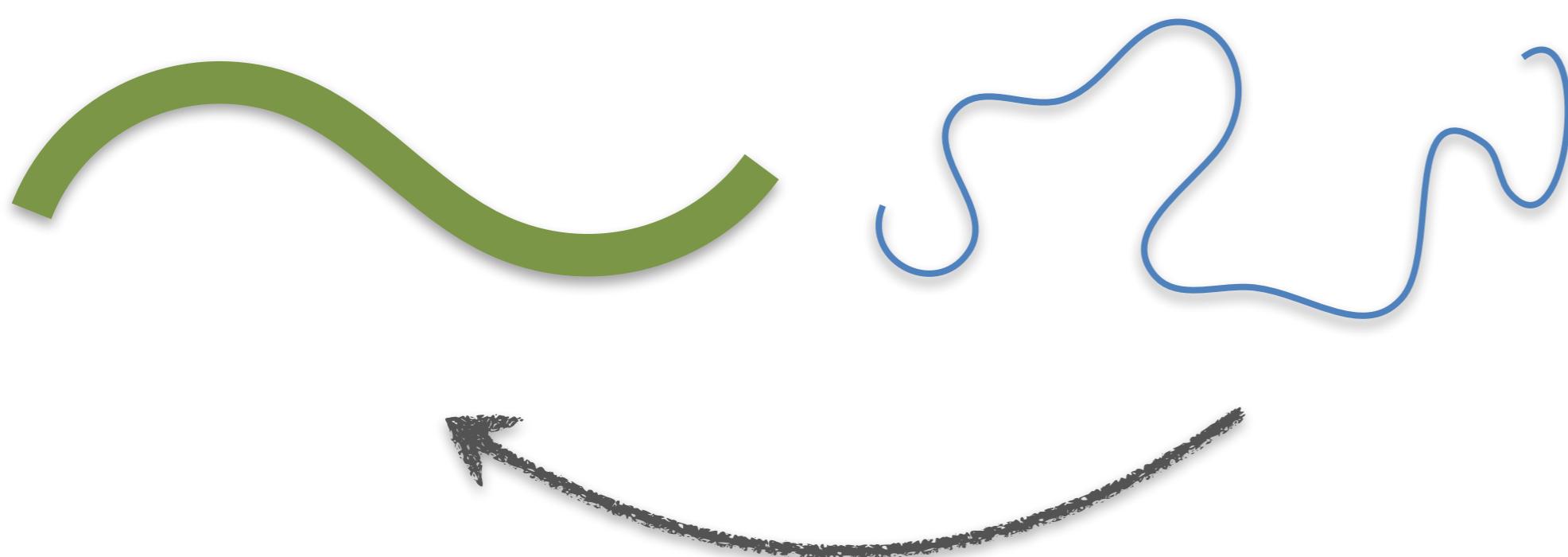
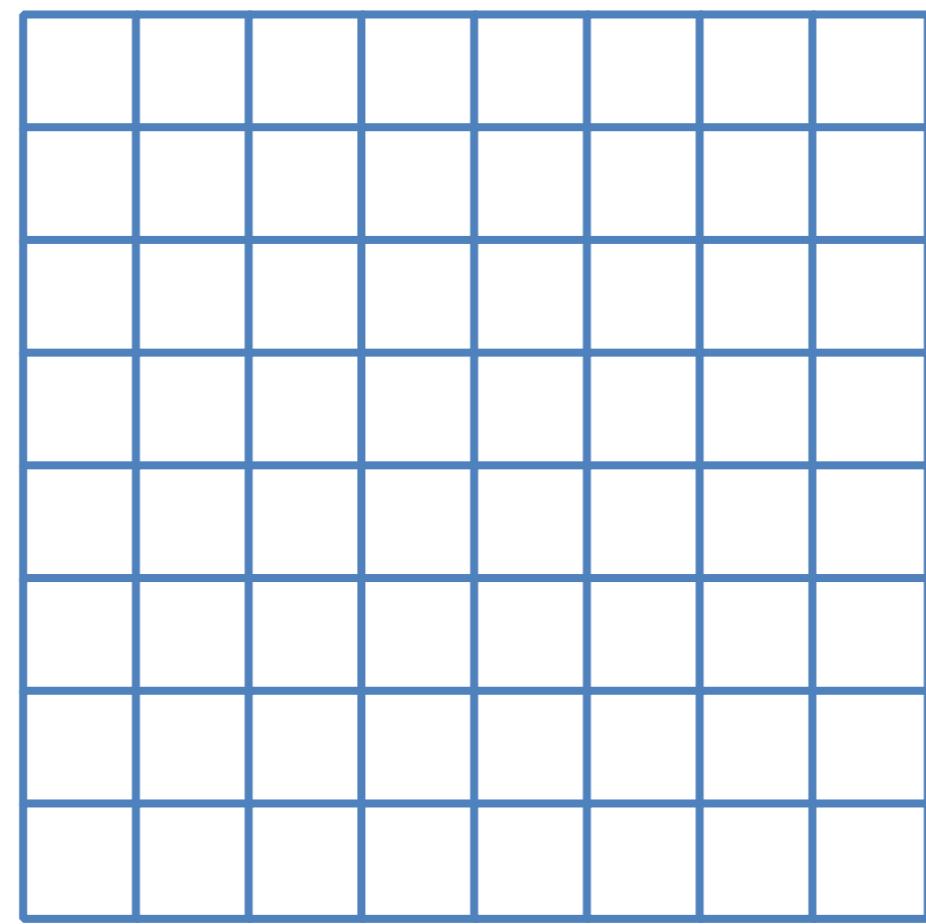


Subgrid-scale models

What I can pay for



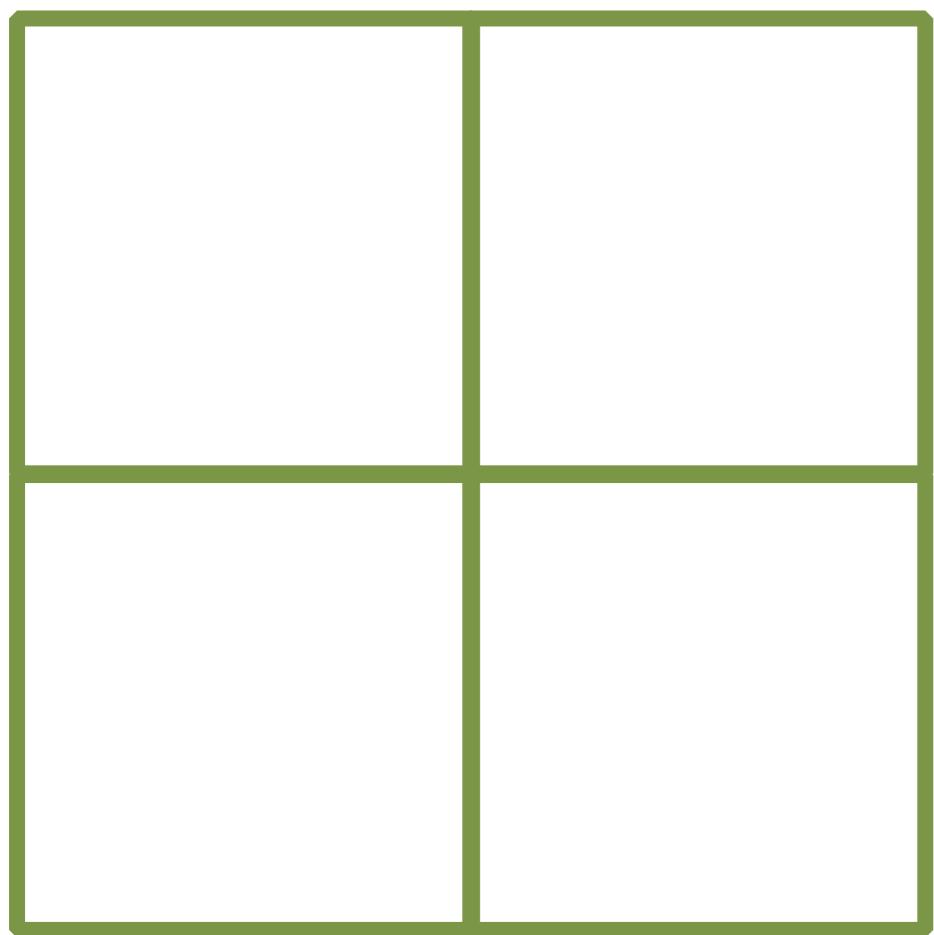
Fully resolved physics



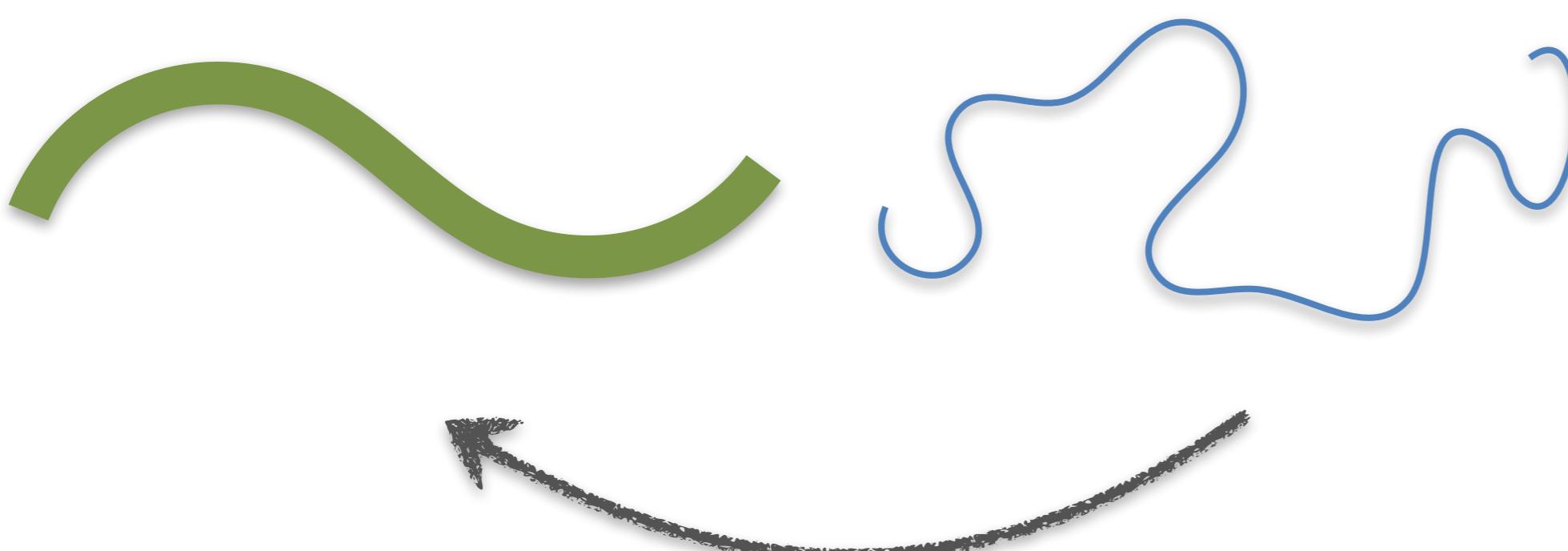
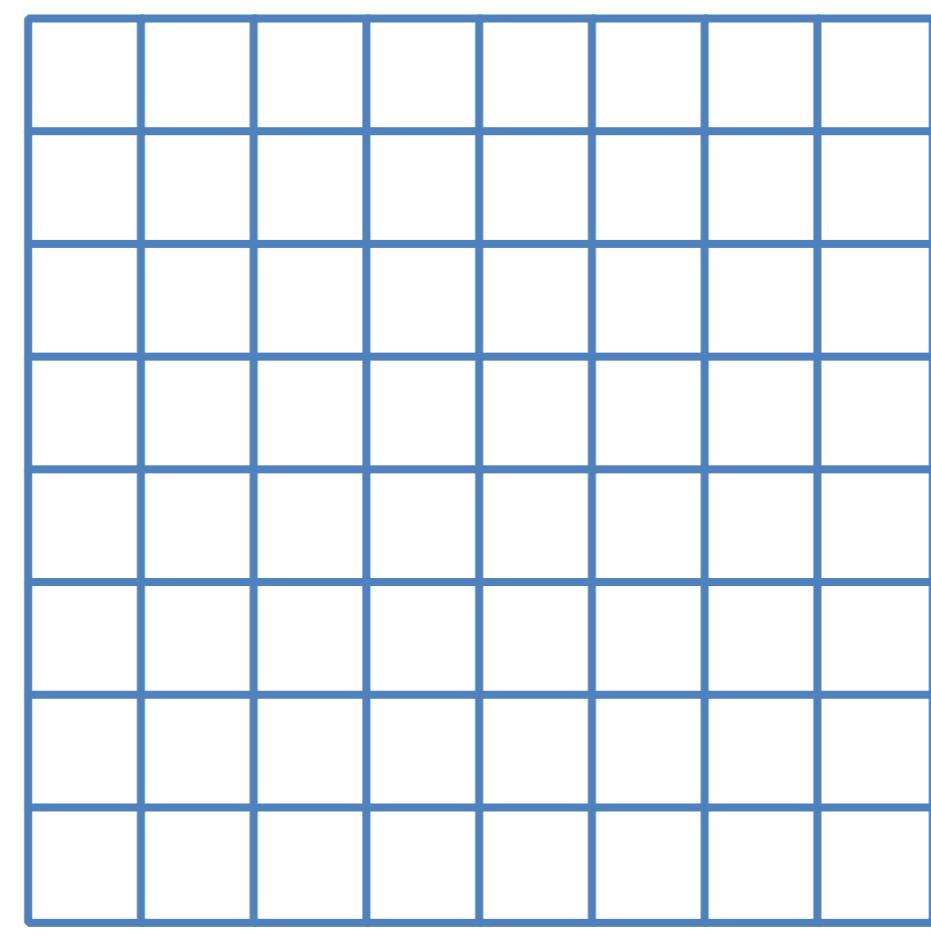
What's missing?

Subgrid-scale models

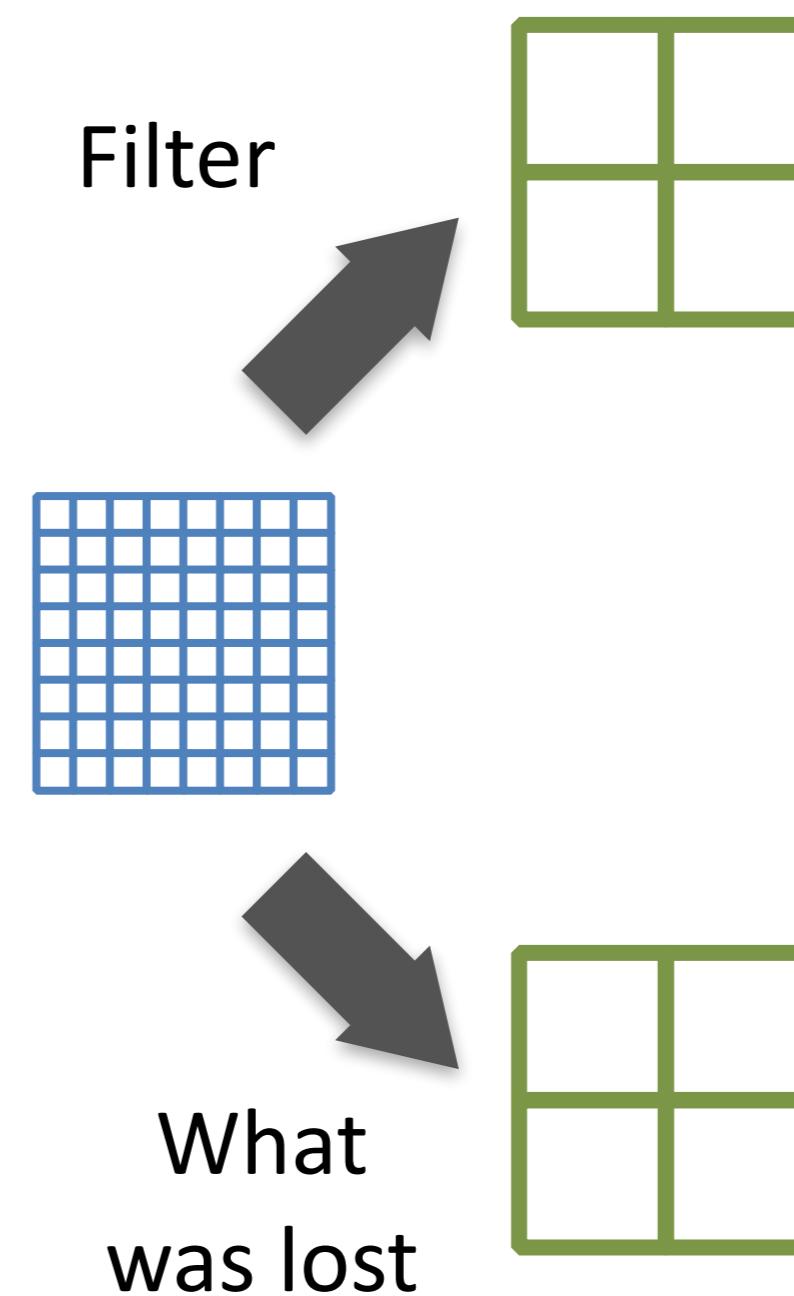
What I can pay for



Fully resolved physics

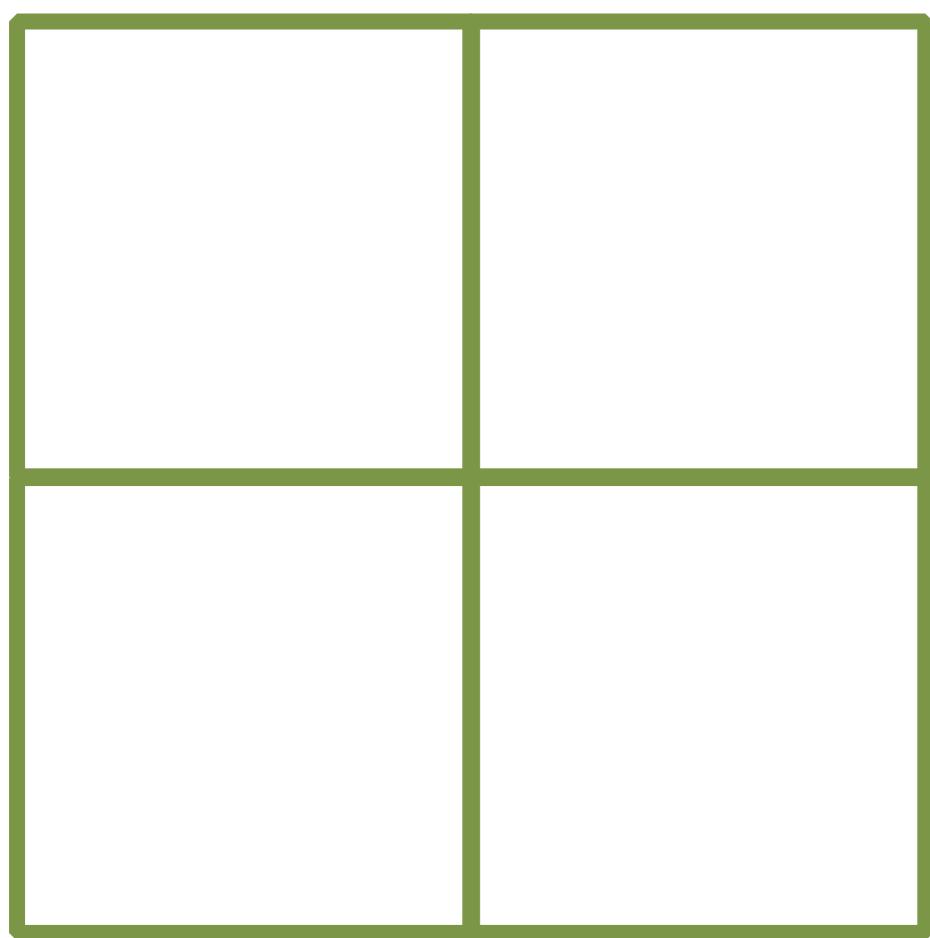


What's missing?

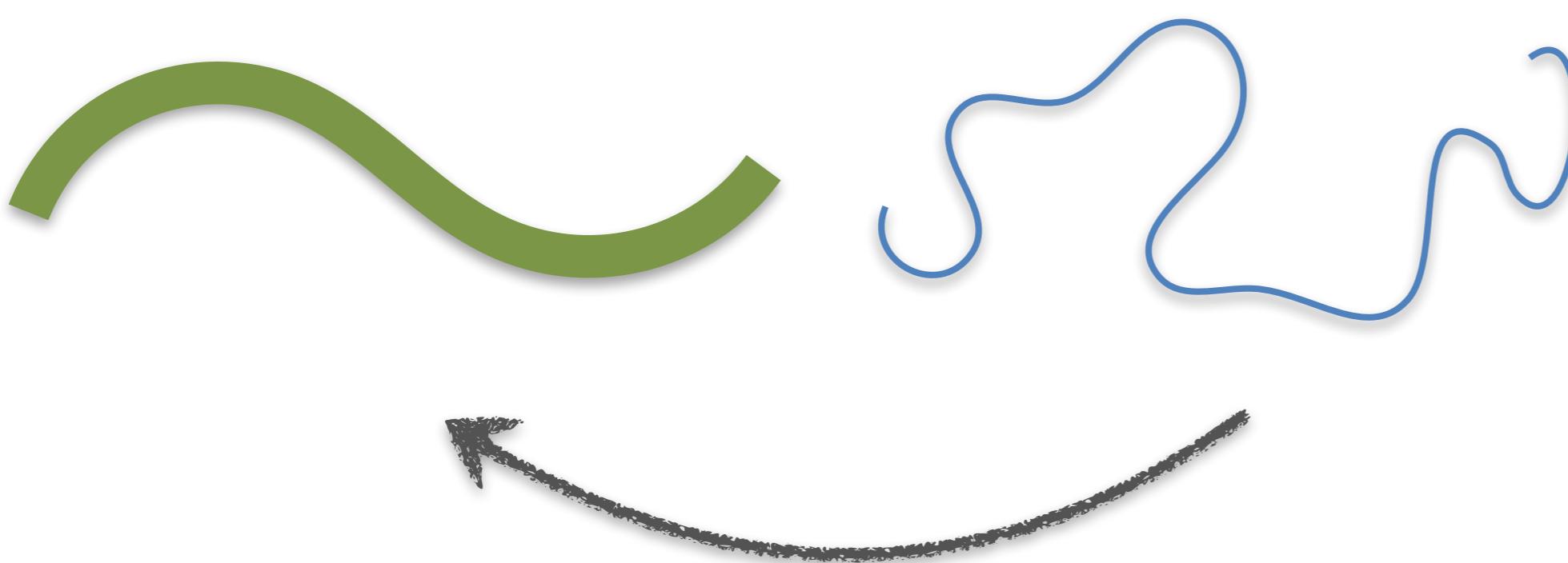
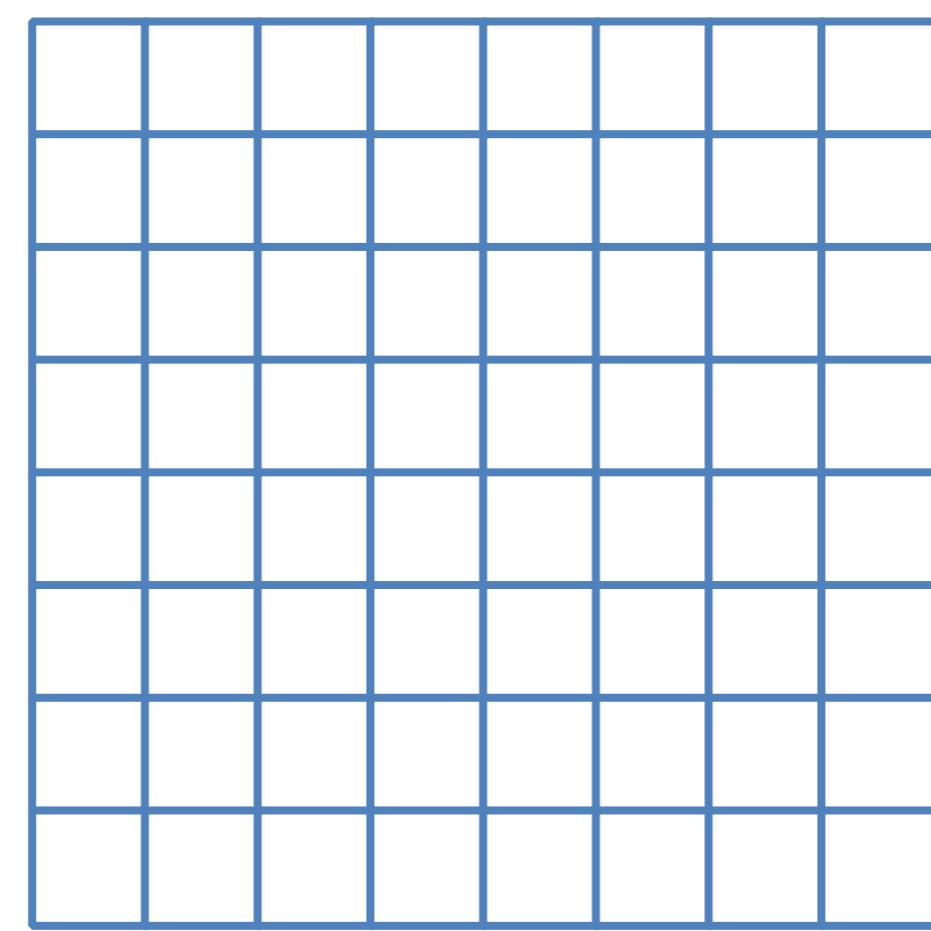


Subgrid-scale models

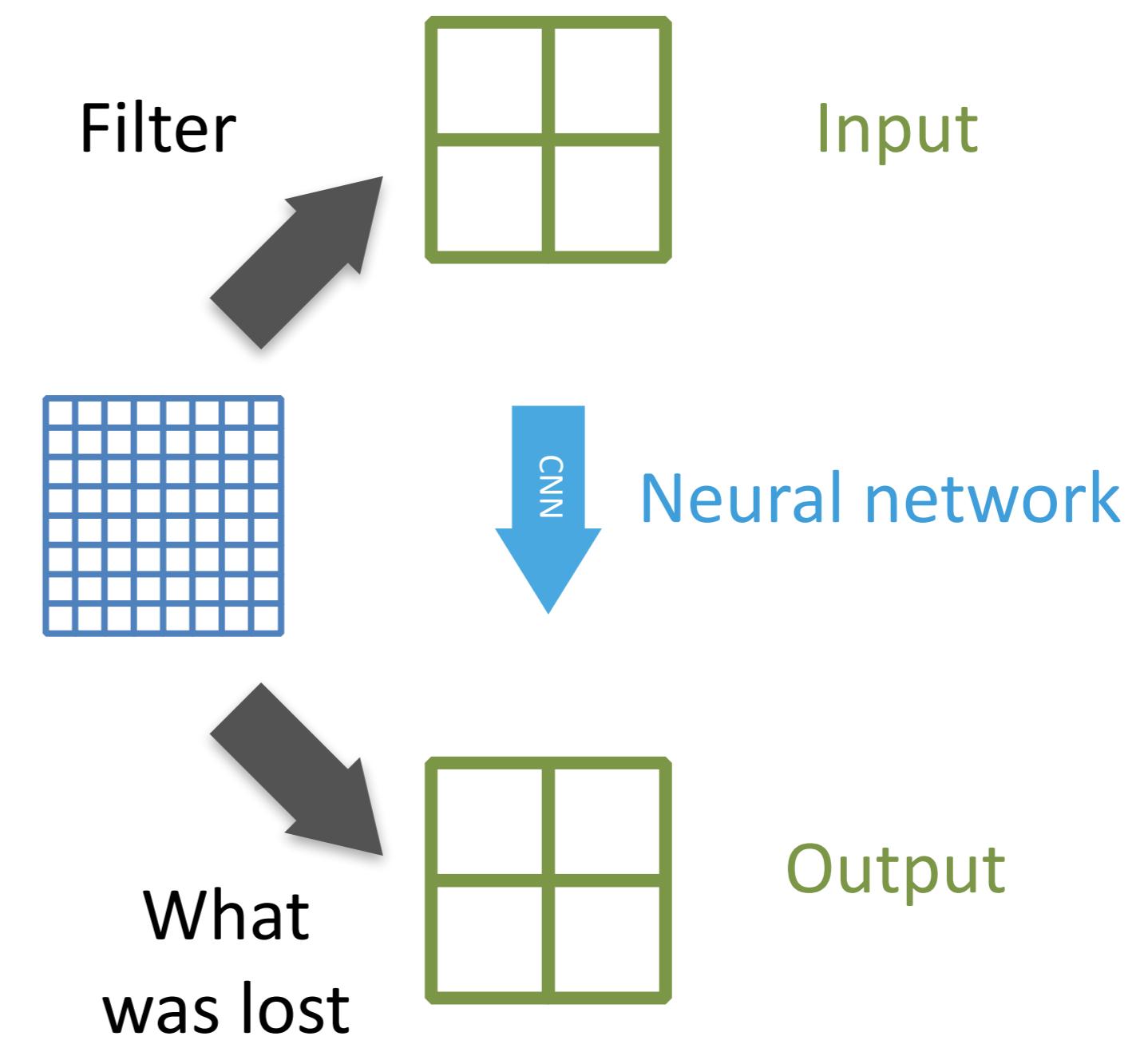
What I can pay for



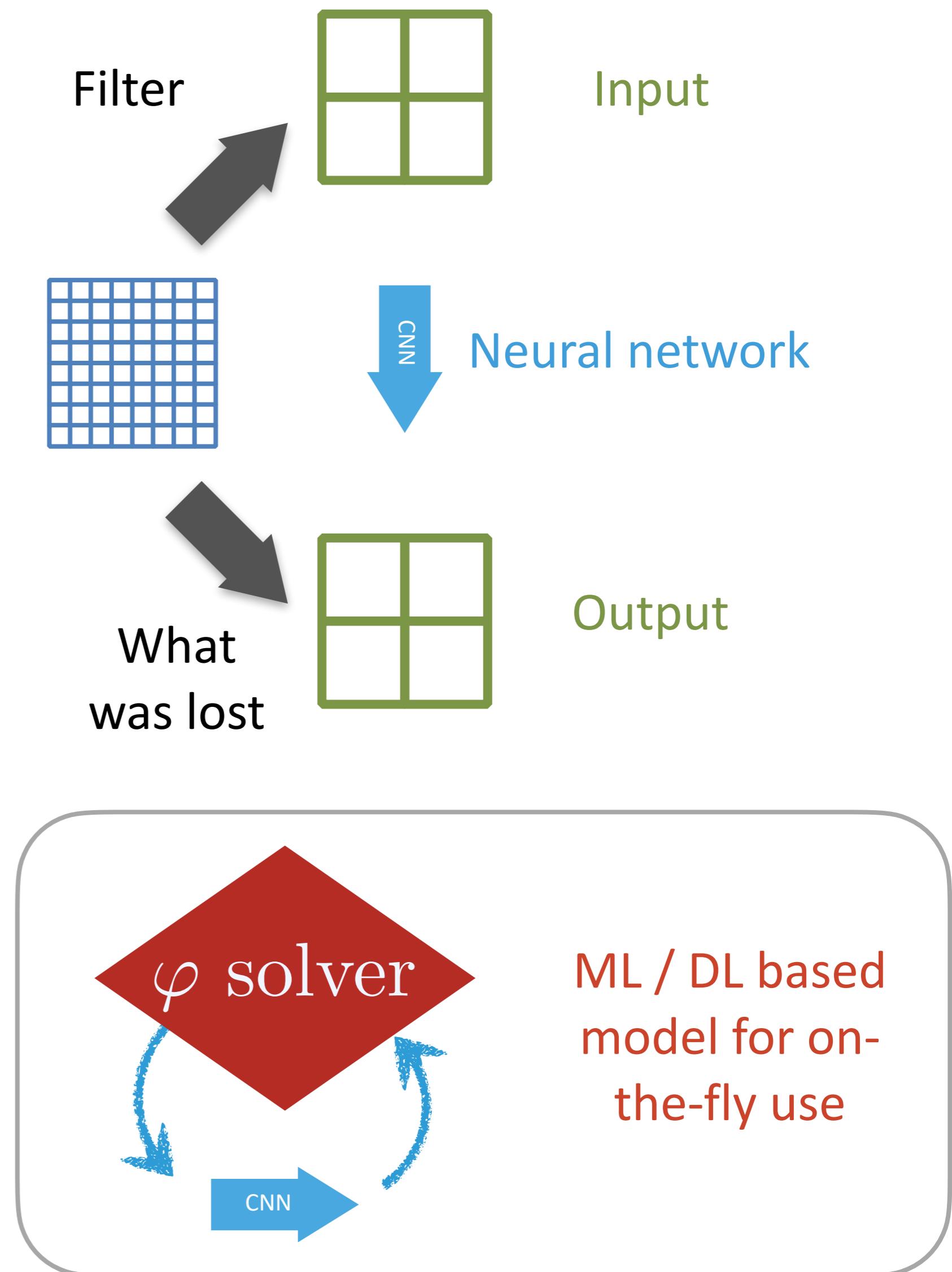
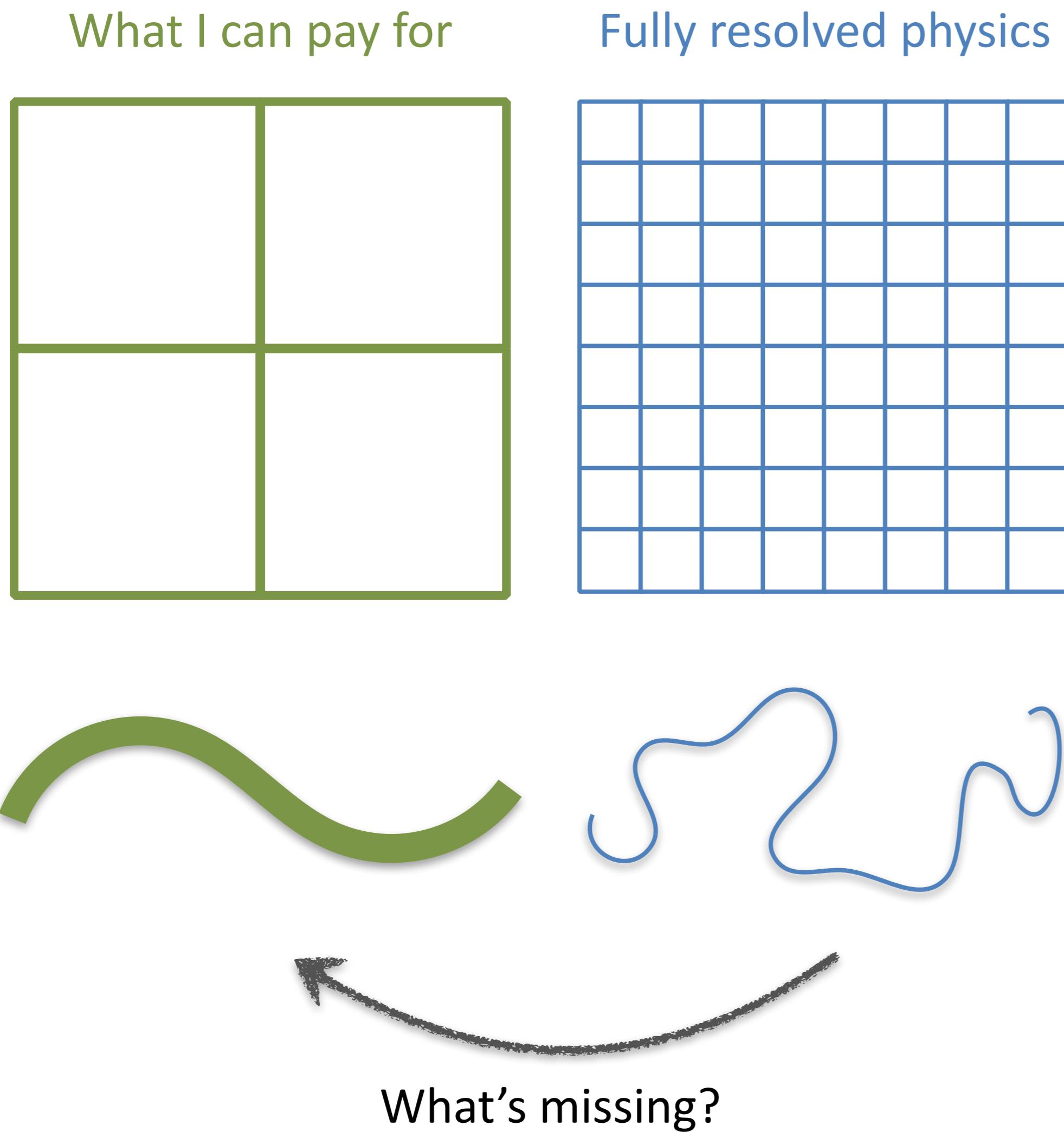
Fully resolved physics



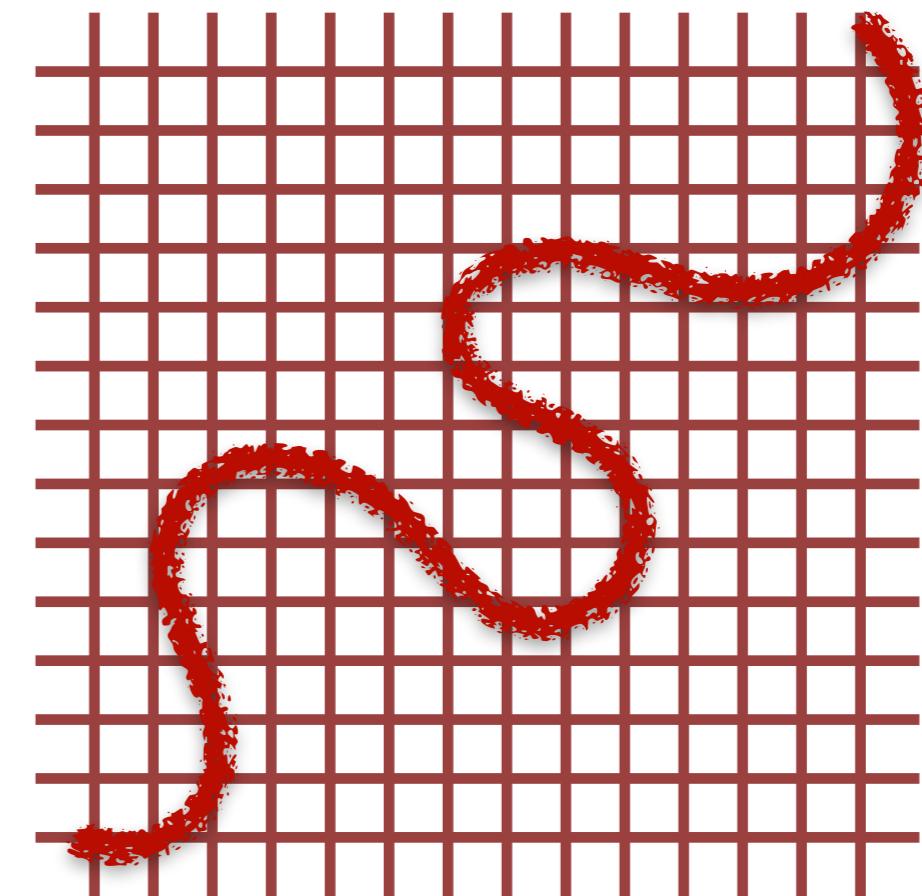
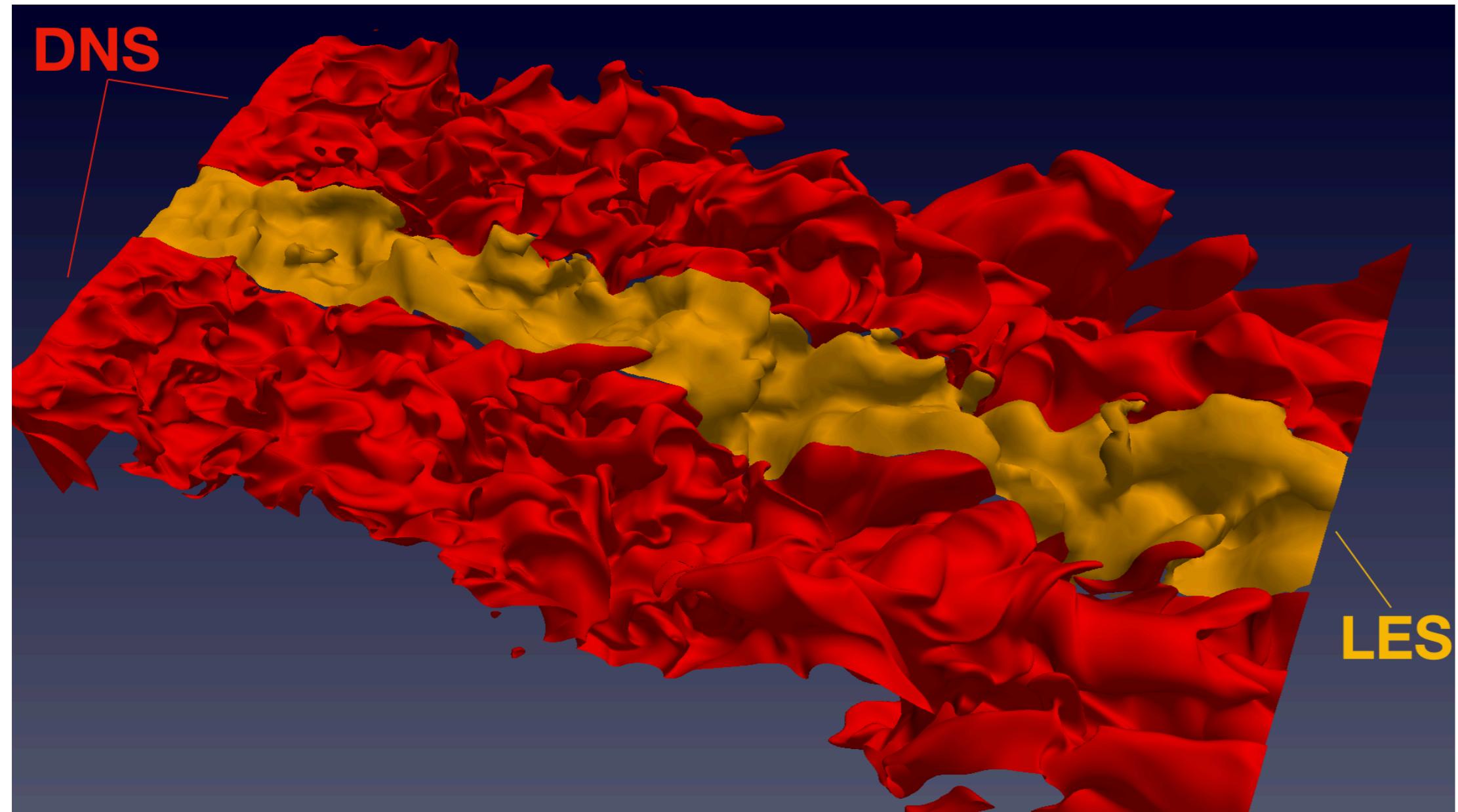
What's missing?



Subgrid-scale models

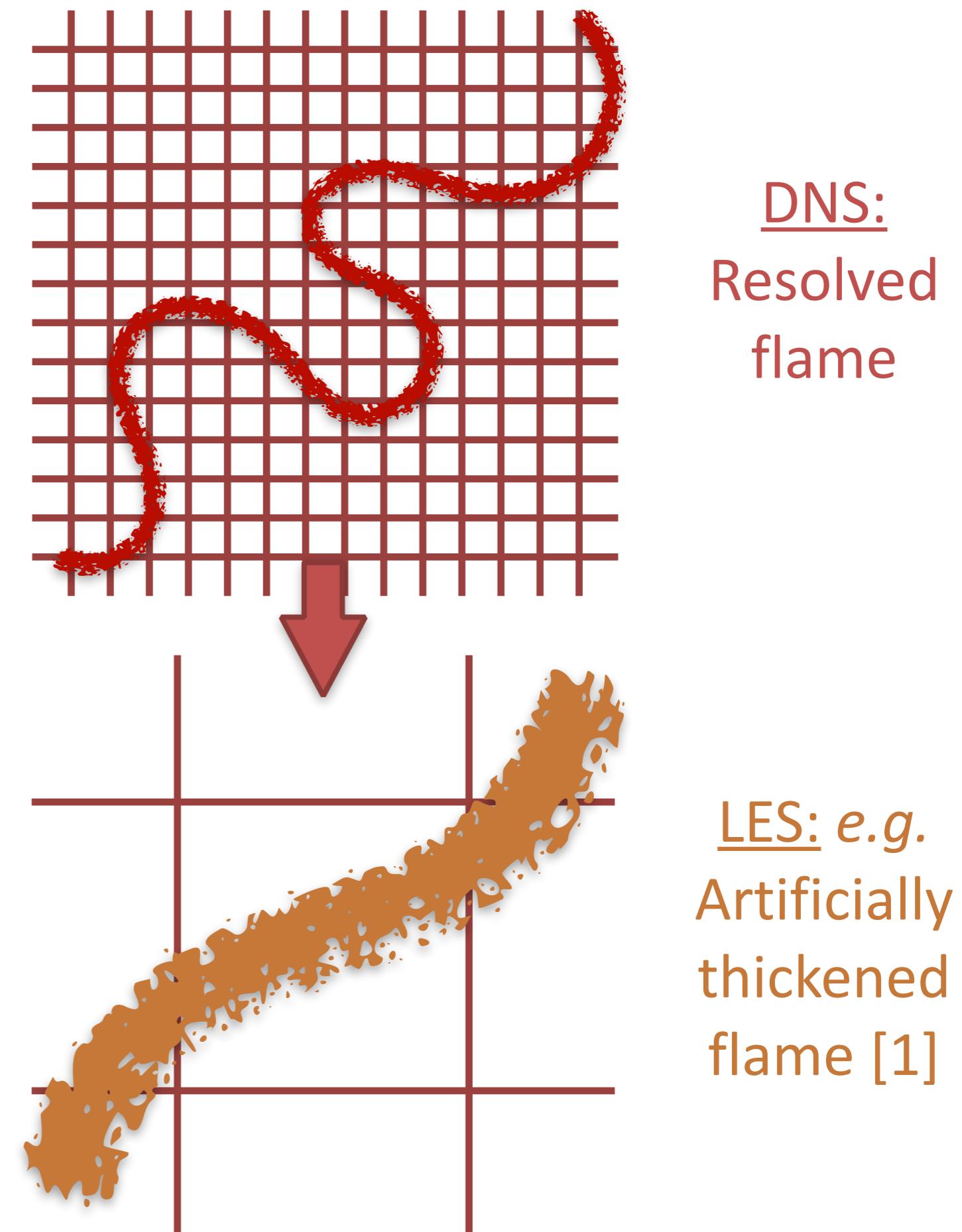
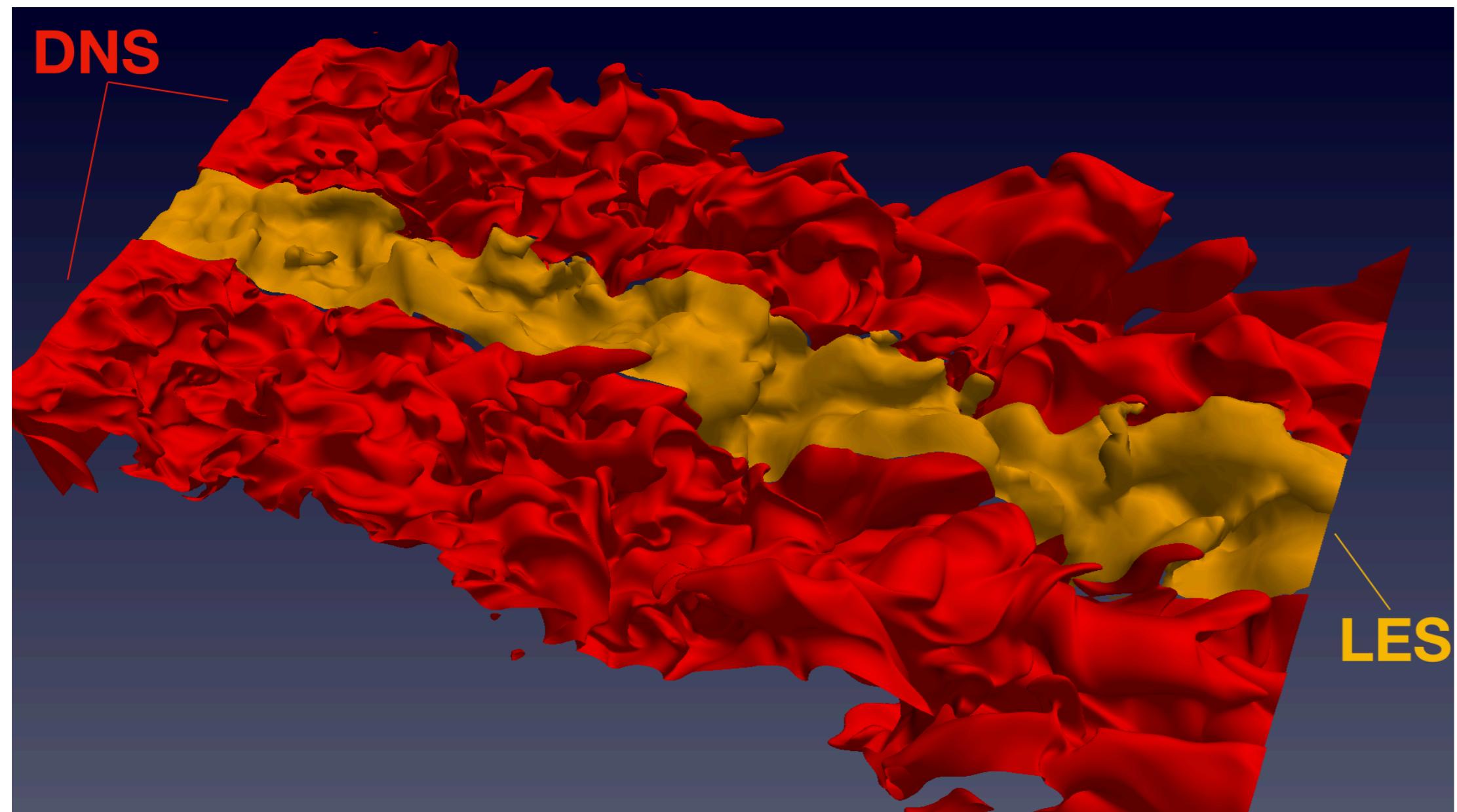


Combustion SGS



DNS:
Resolved
flame

Combustion SGS



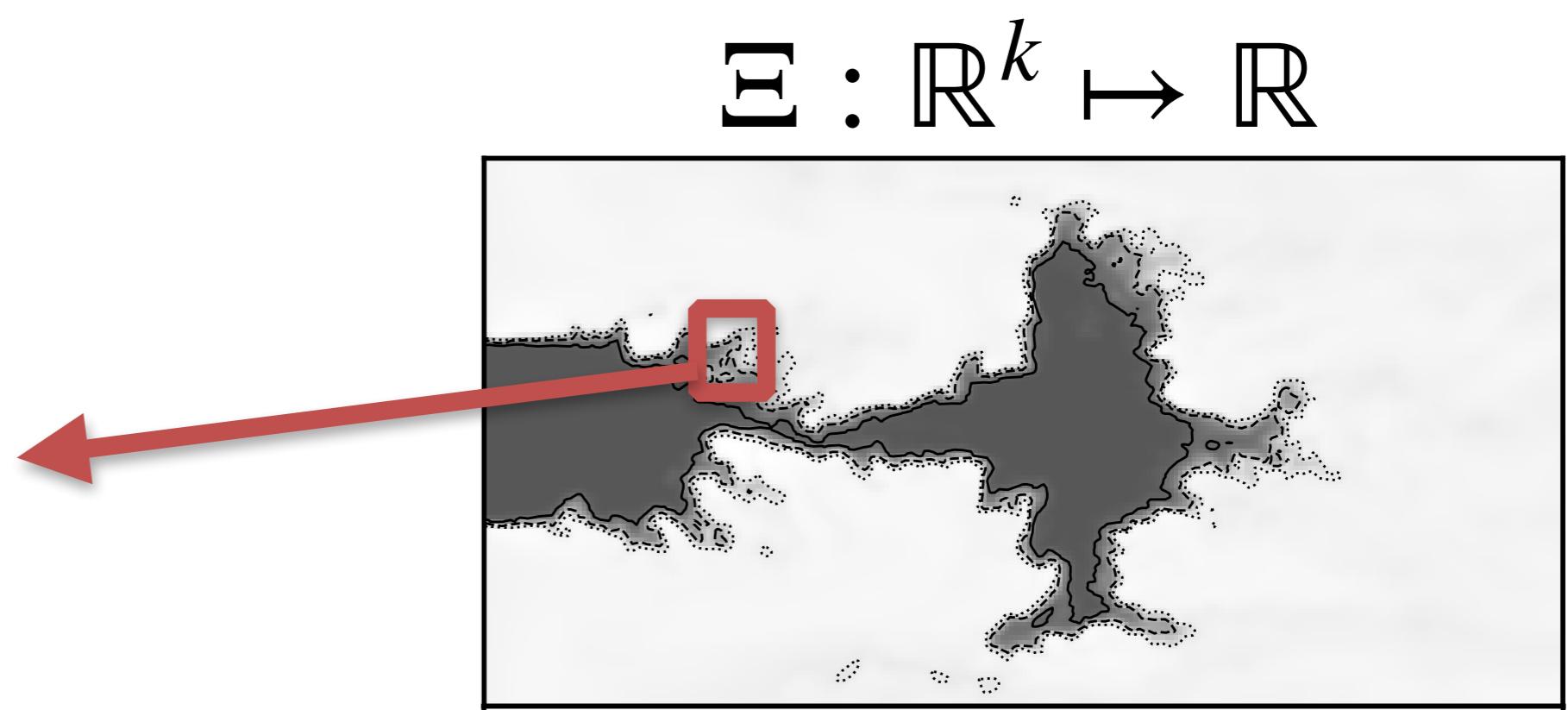
Efficiency functions f - local to global

LOCAL FORMULATIONS:

1989 - Gouldin (fractal)

2000 - Colin *et al.*

2002 - Charlette *et al.*



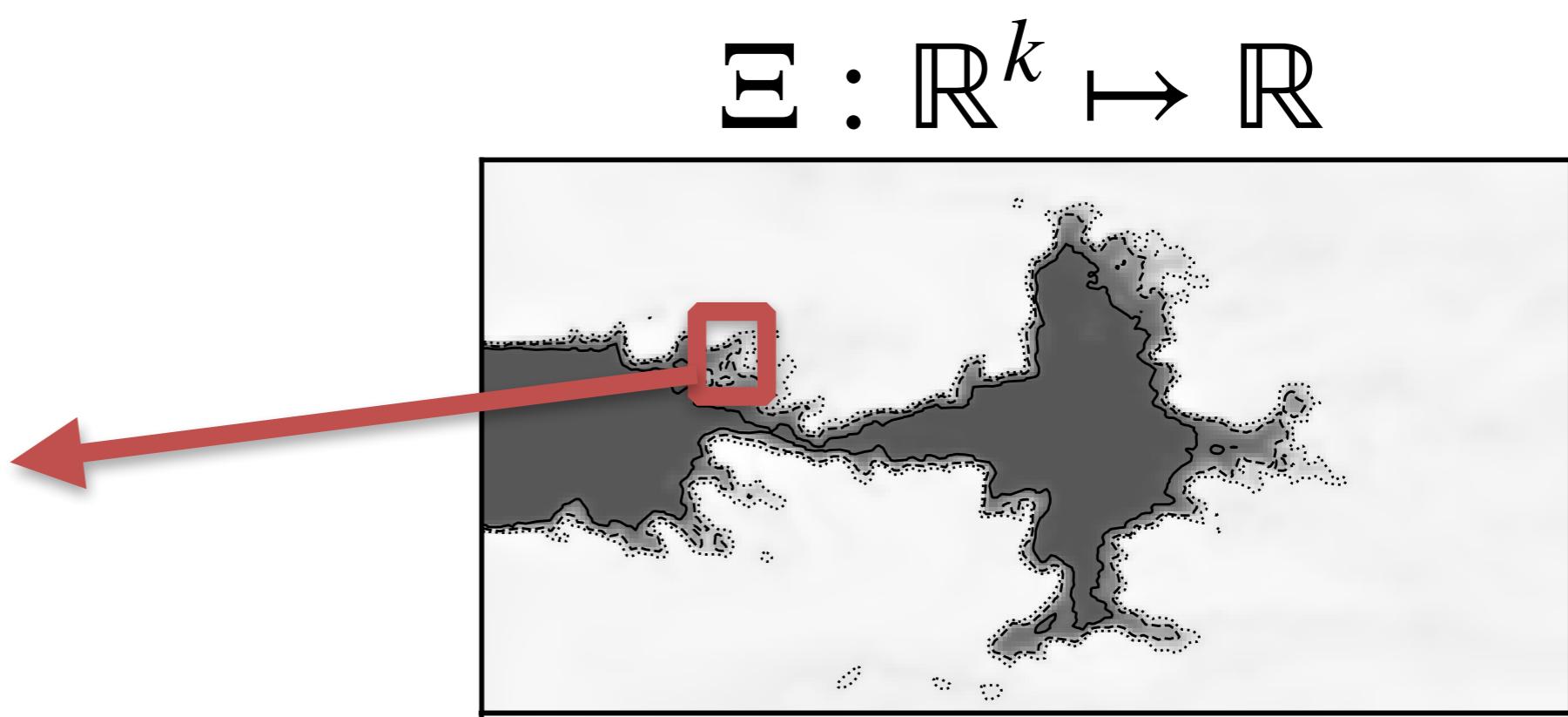
Efficiency functions f - local to global

LOCAL FORMULATIONS:

1989 - Gouldin (fractal)

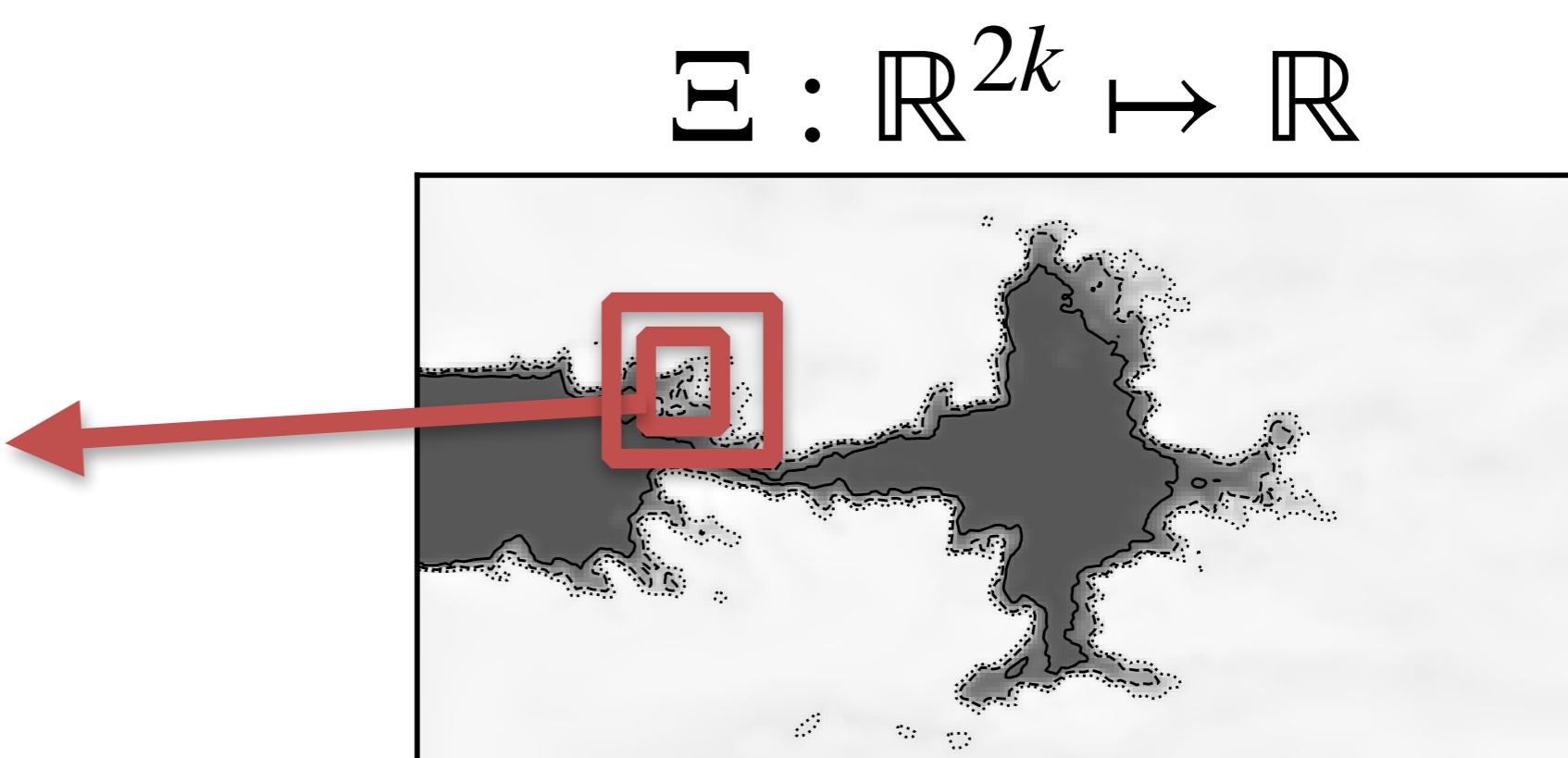
2000 - Colin *et al.*

2002 - Charlette *et al.*



DYNAMIC FORMULATIONS:

2011 - Wang *et al.*



Efficiency functions f - local to global

LOCAL FORMULATIONS:

1989 - Gouldin (fractal)

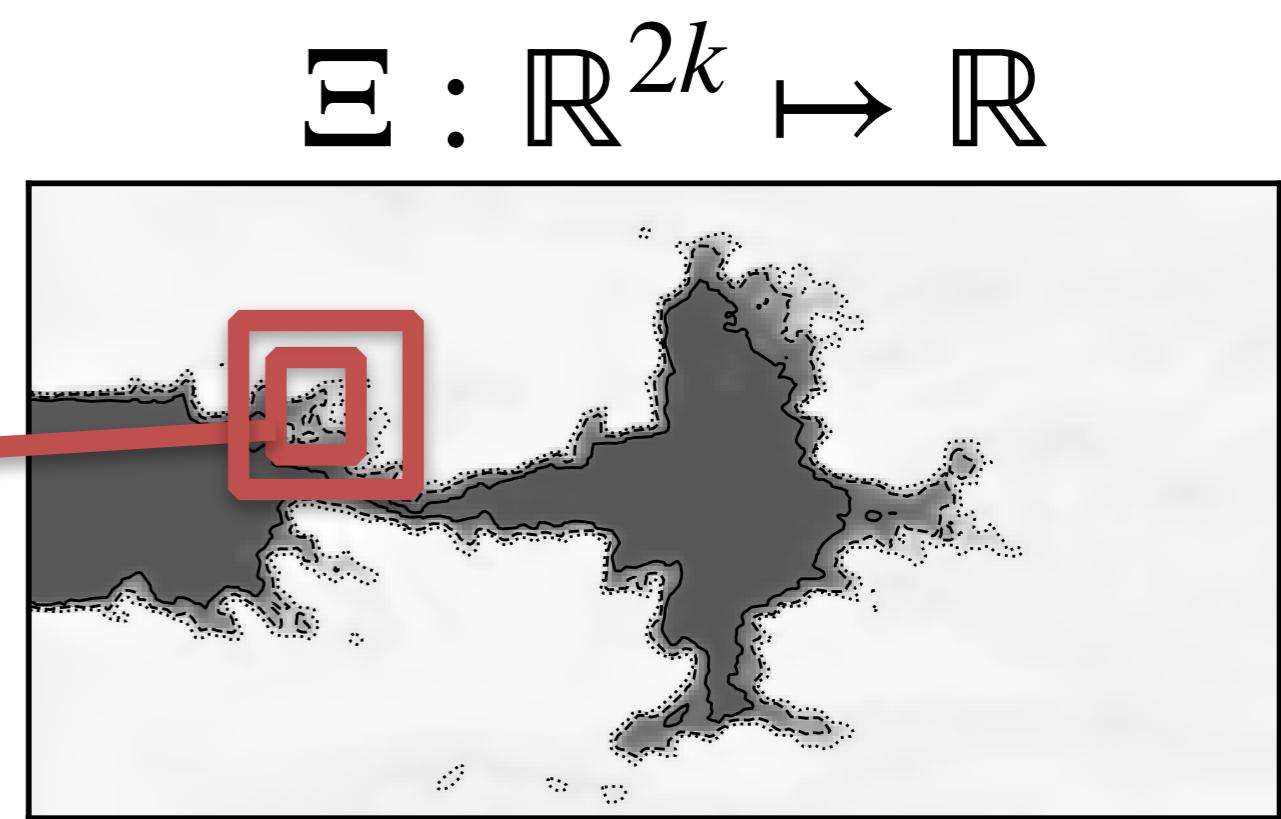
2000 - Colin *et al.*

2002 - Charlette *et al.*



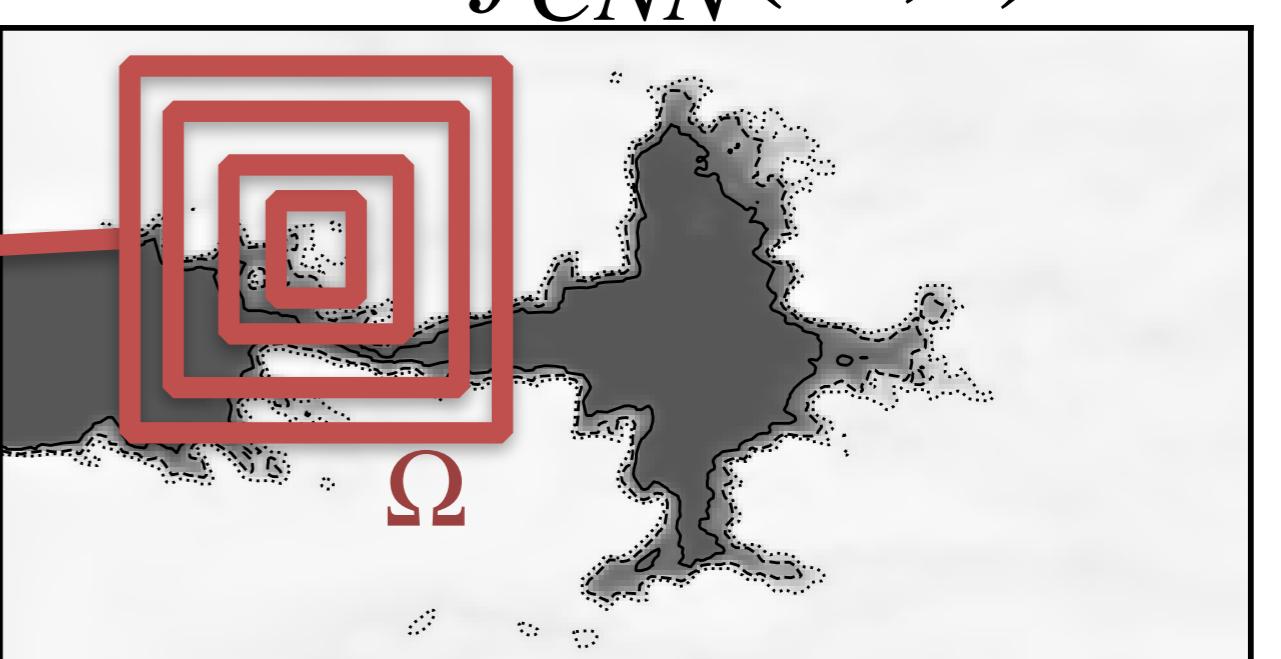
DYNAMIC FORMULATIONS:

2011 - Wang *et al.*

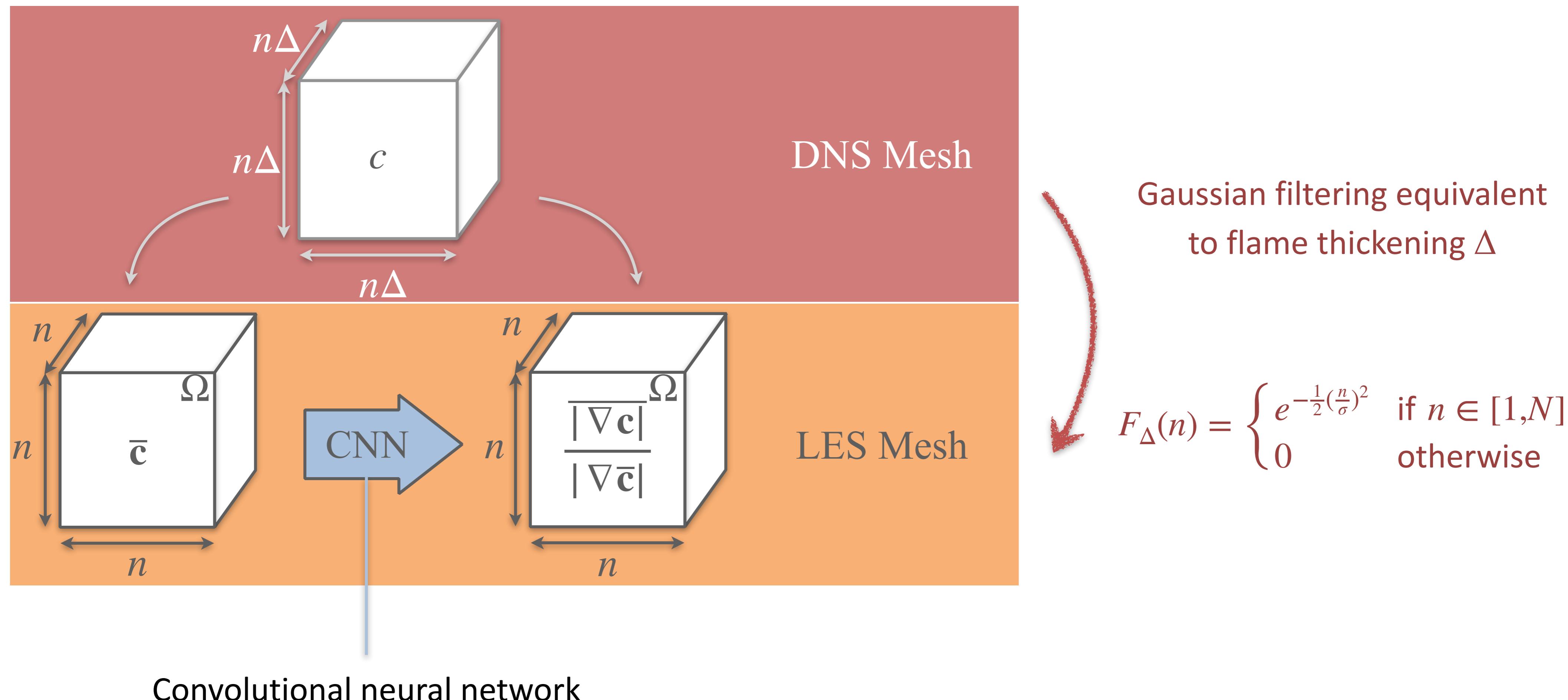


CNN FORMULATION:

2019 - Lapeyre *et al.*

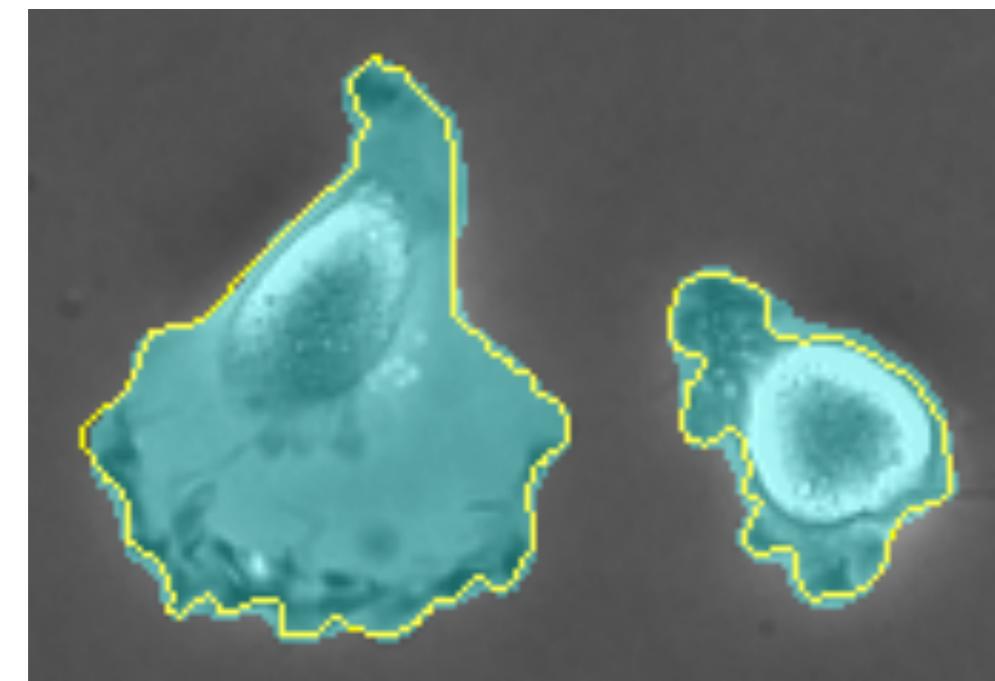
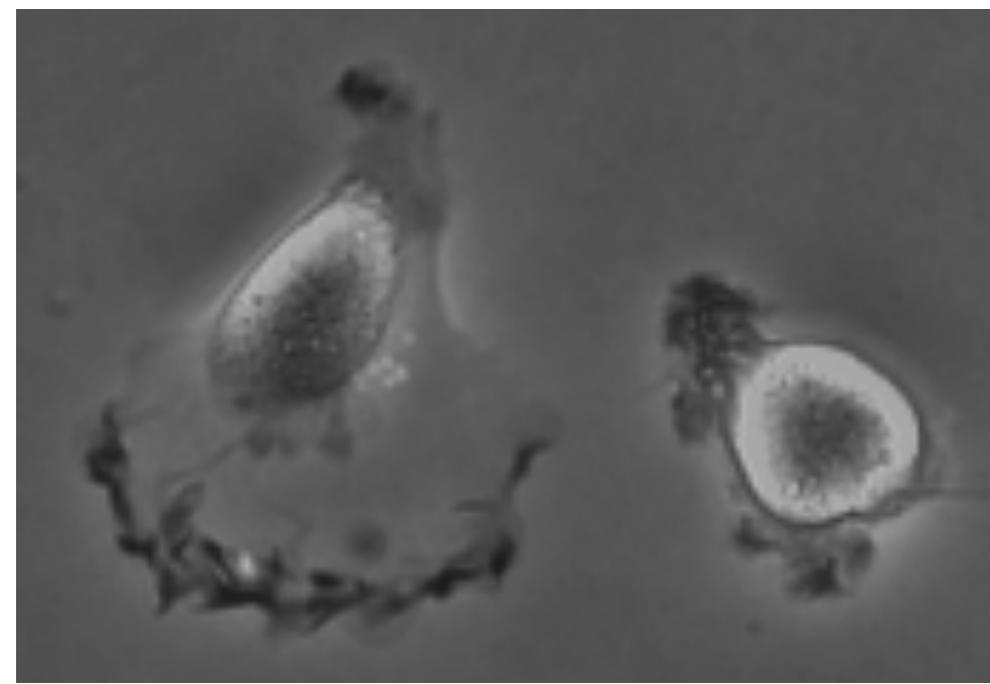


Building the dataset

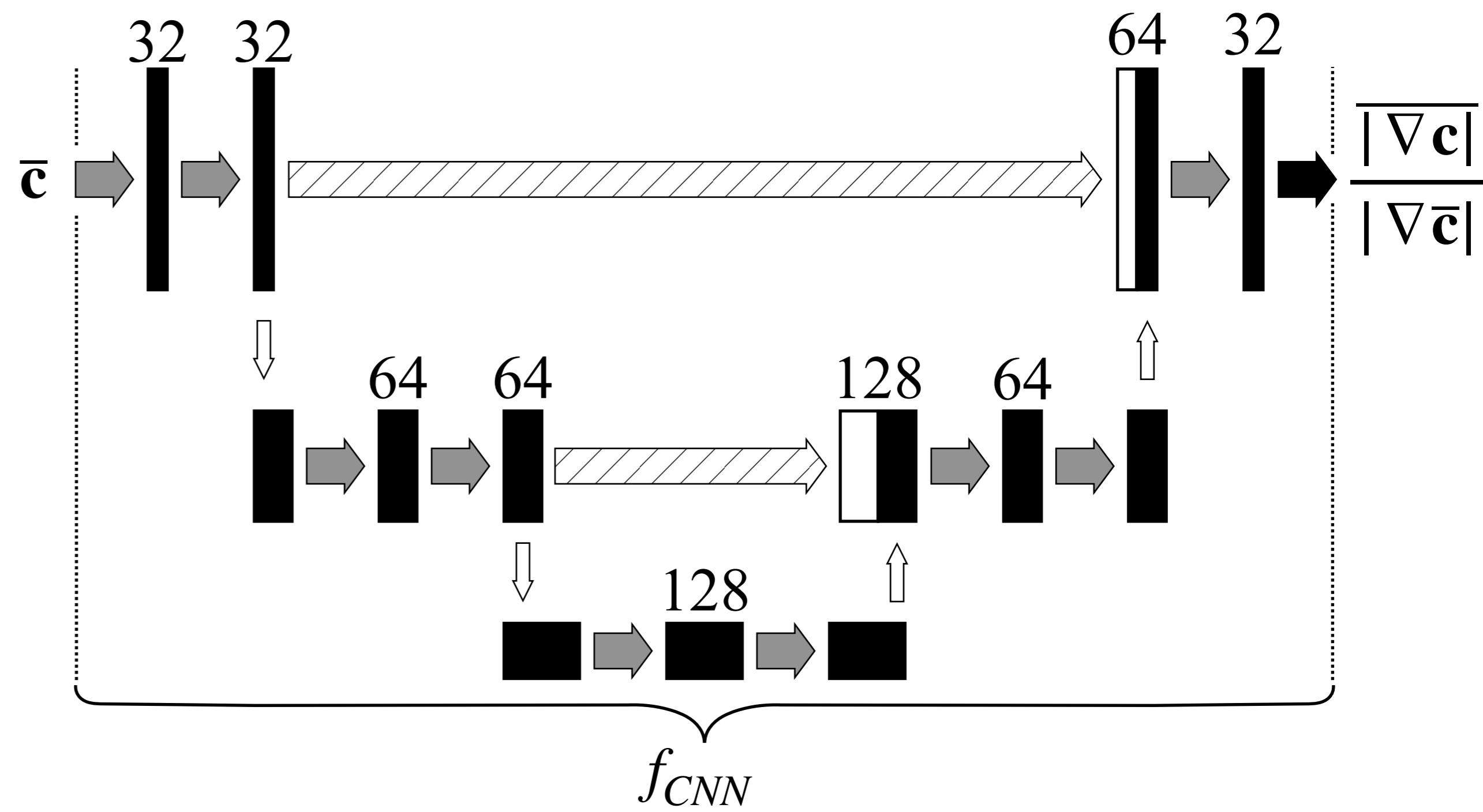
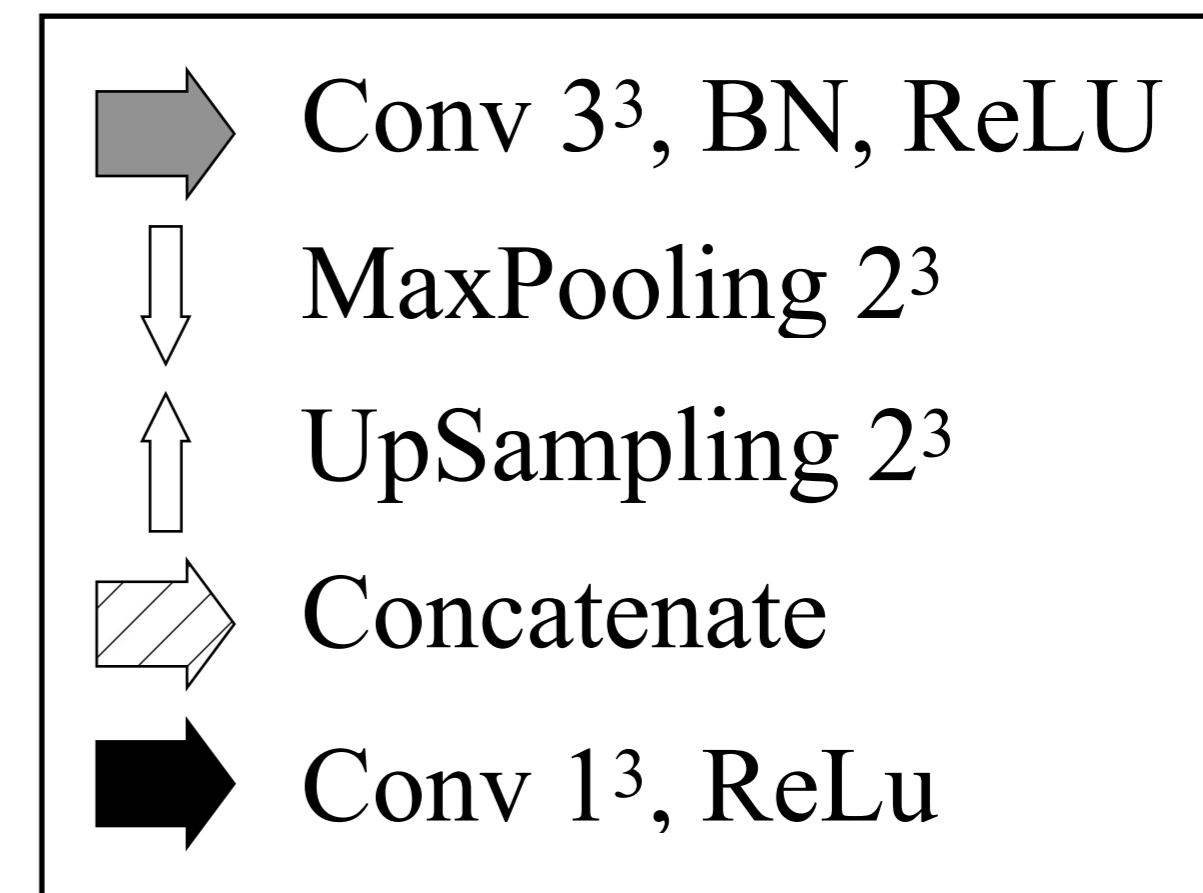


Neural network

Input

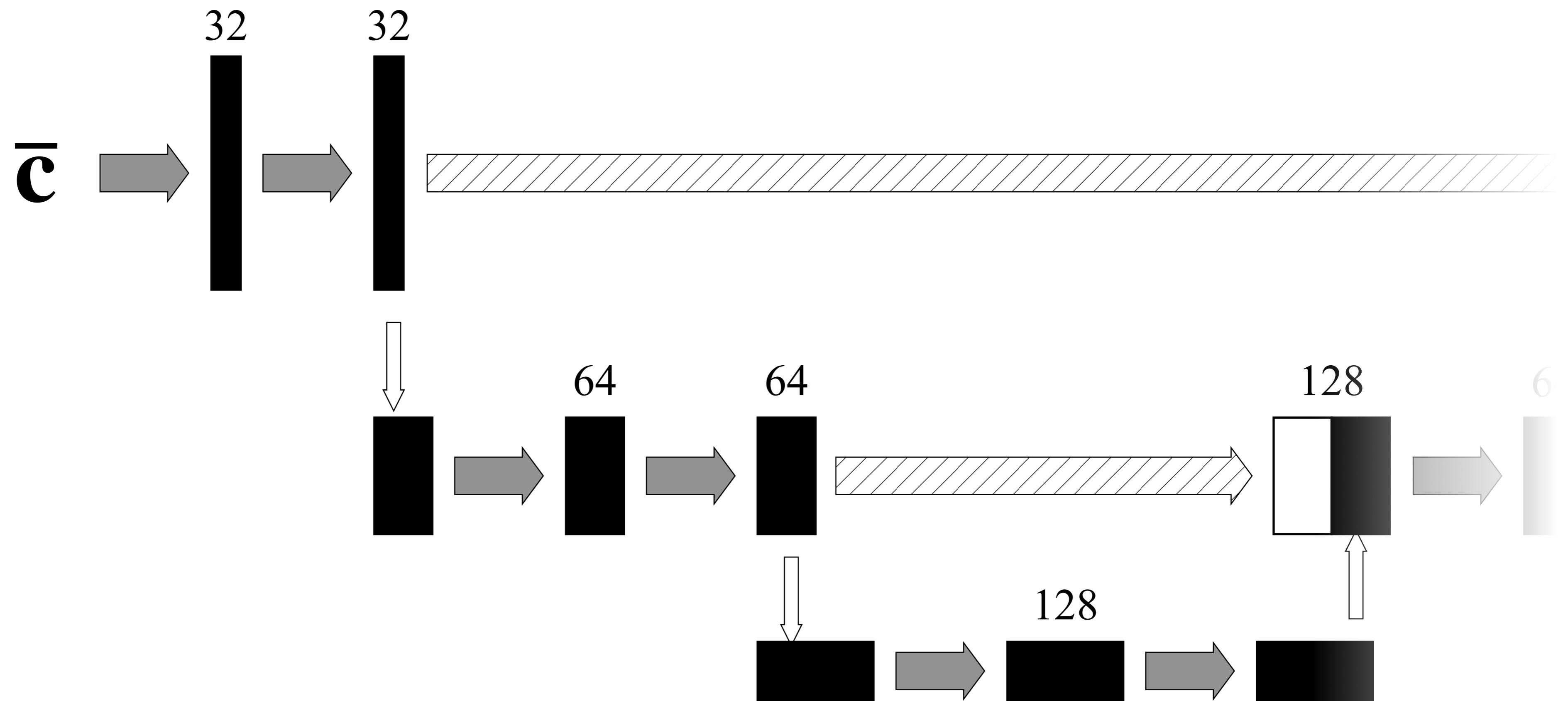


Segmented image



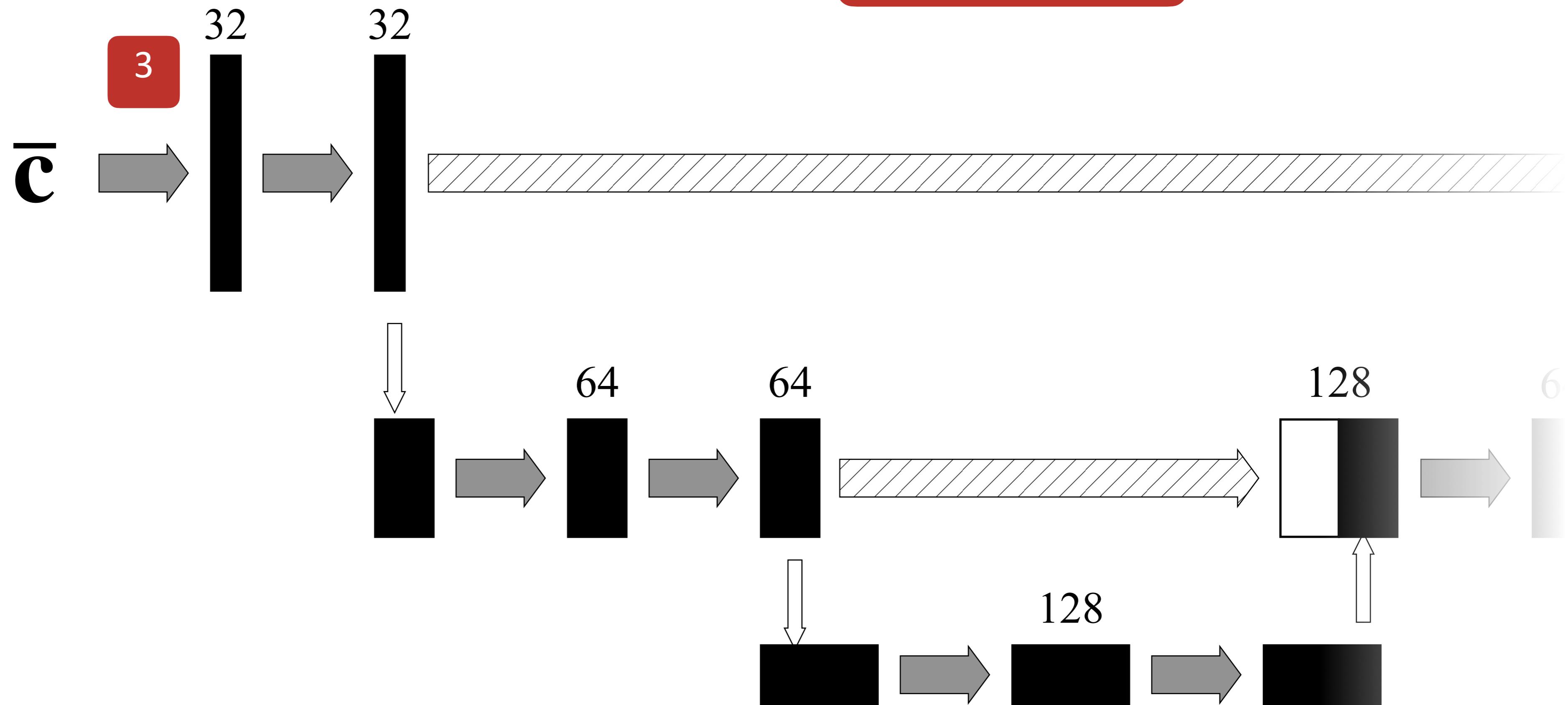
Architecture is adapted from a medical image segmentation network [9]

Neural network



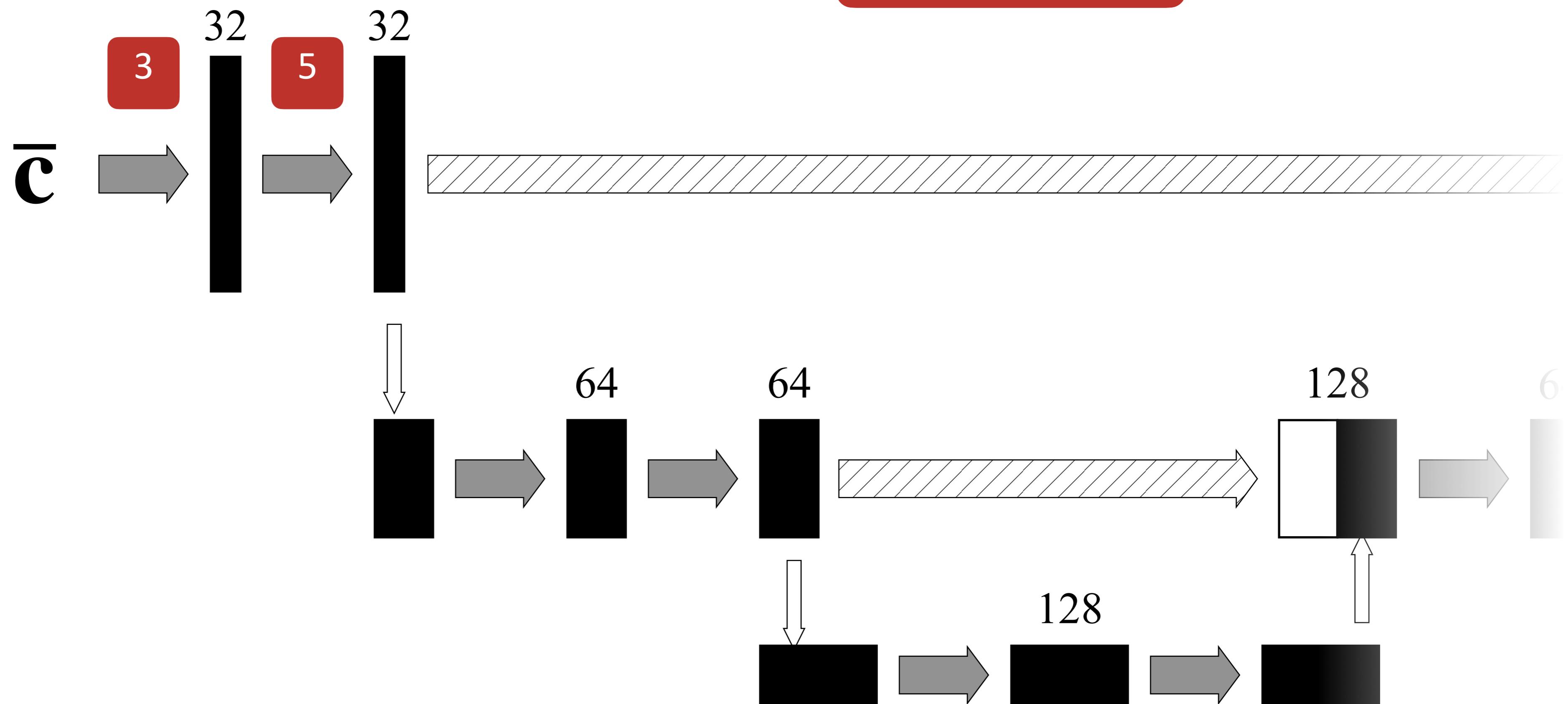
Neural network

Receptive field



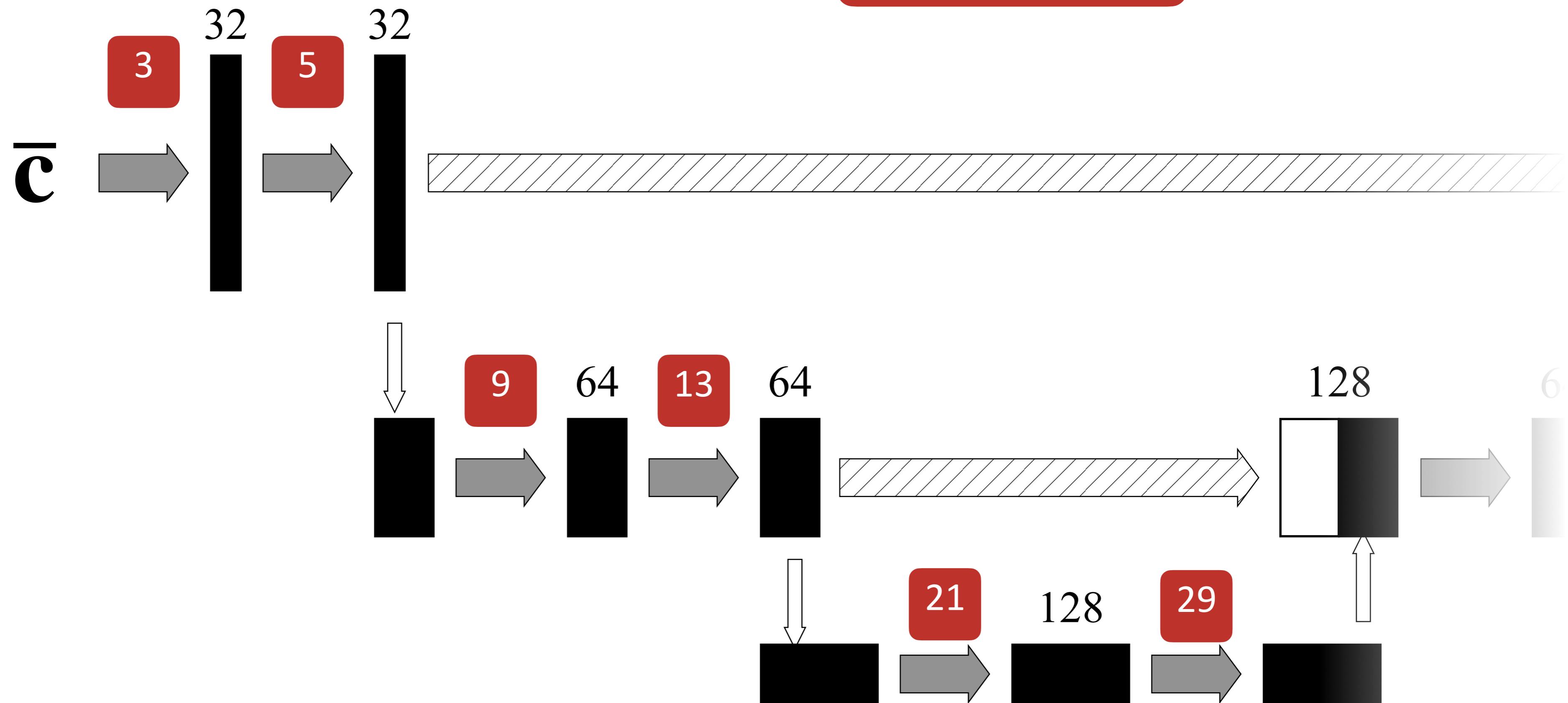
Neural network

Receptive field



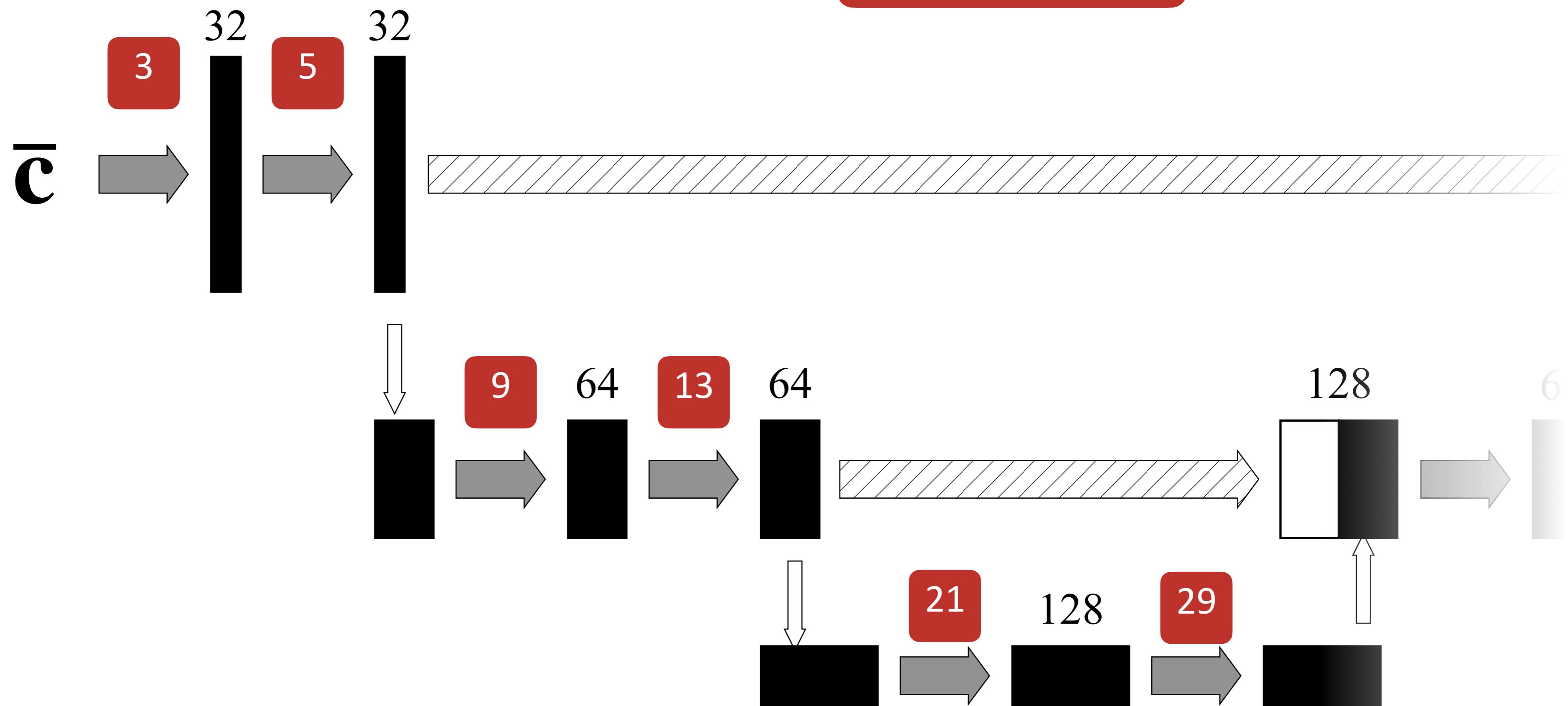
Neural network

Receptive field



Neural network

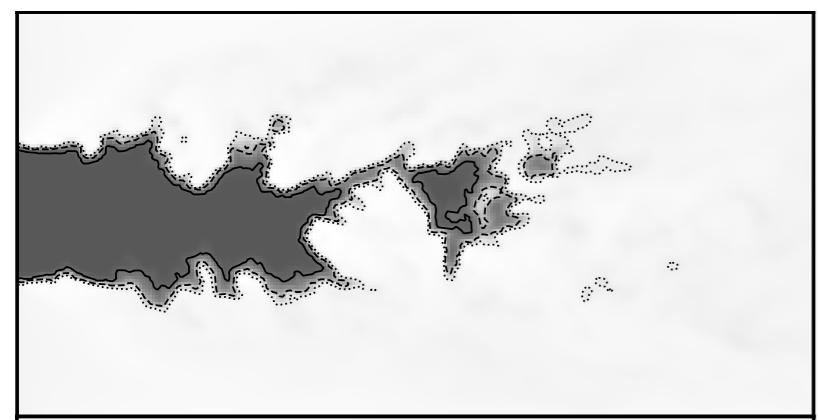
Receptive field



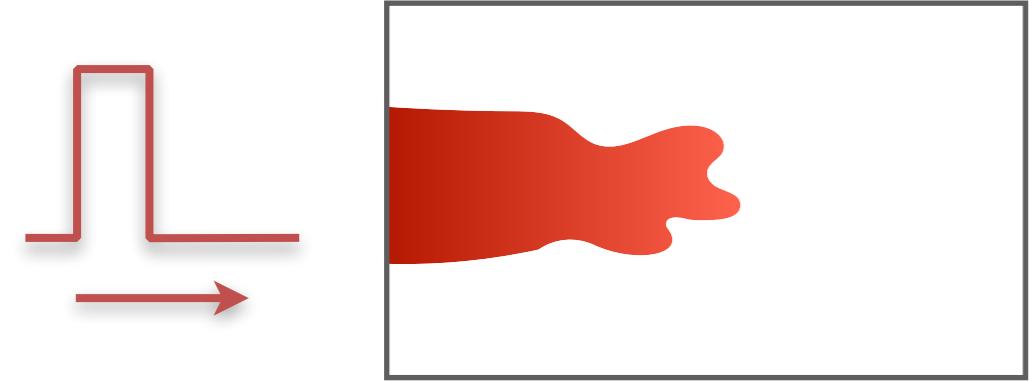
- Network is trained on increasing size inputs: 8^3 , then 16^3 , and finally 32^3 .

A priori strategy

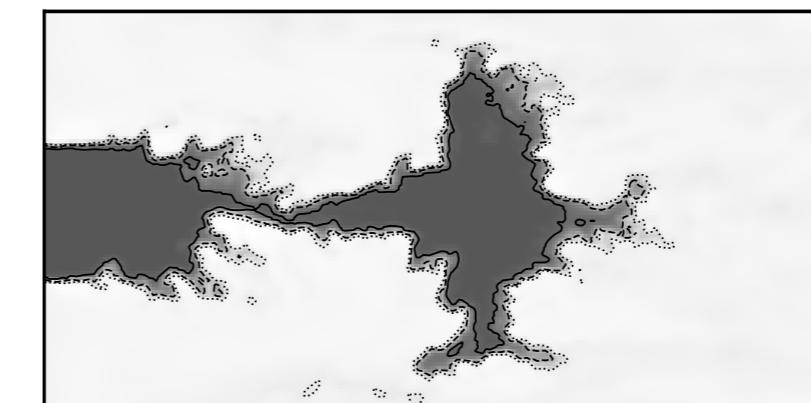
Training setup



Target setup

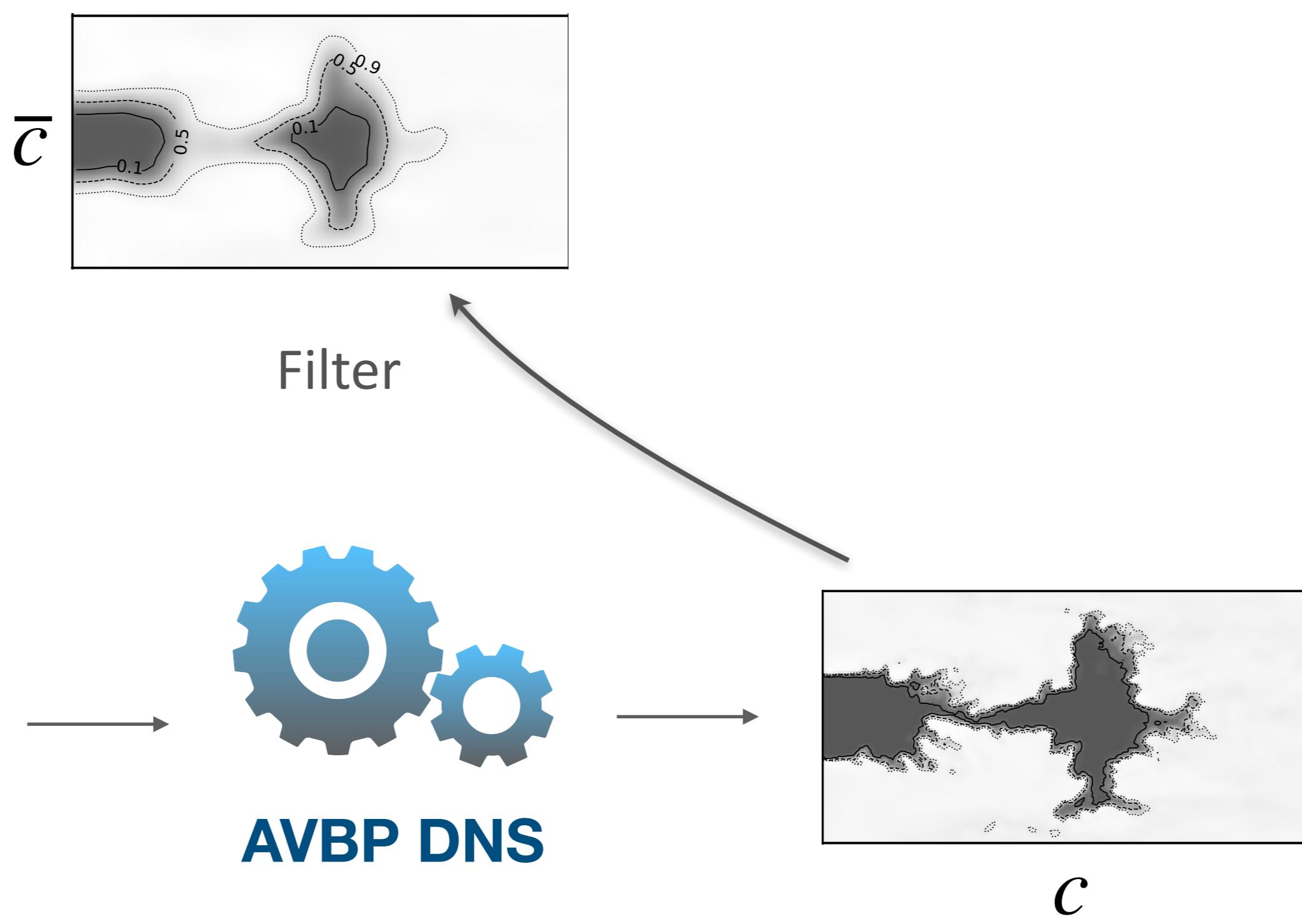
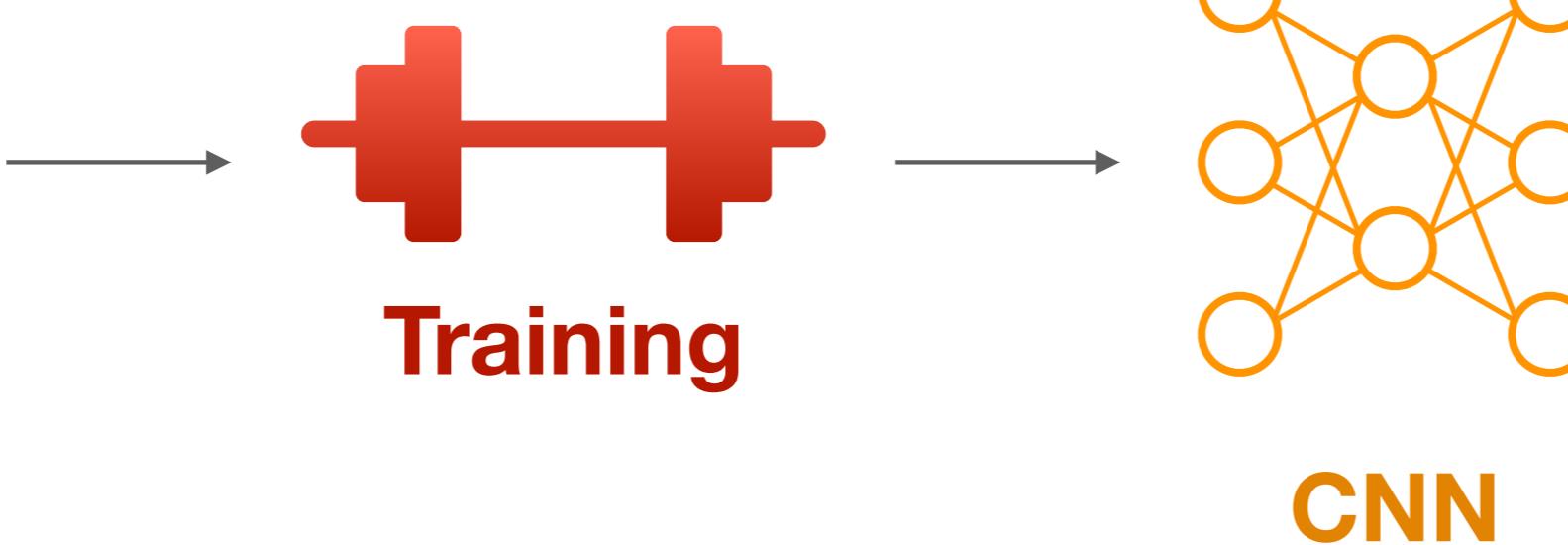
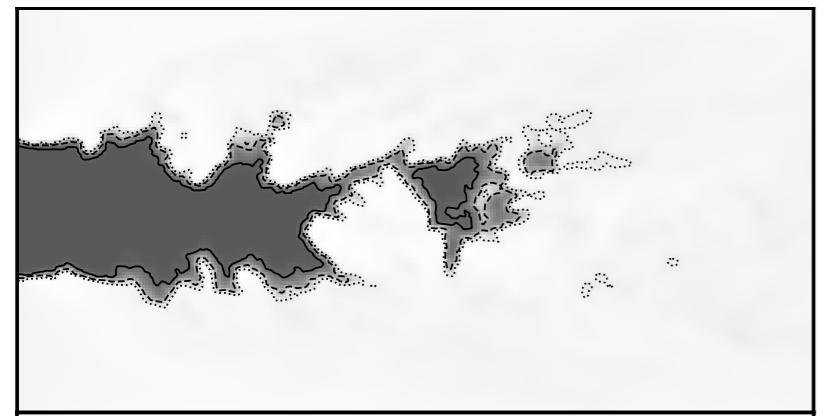


AVBP DNS



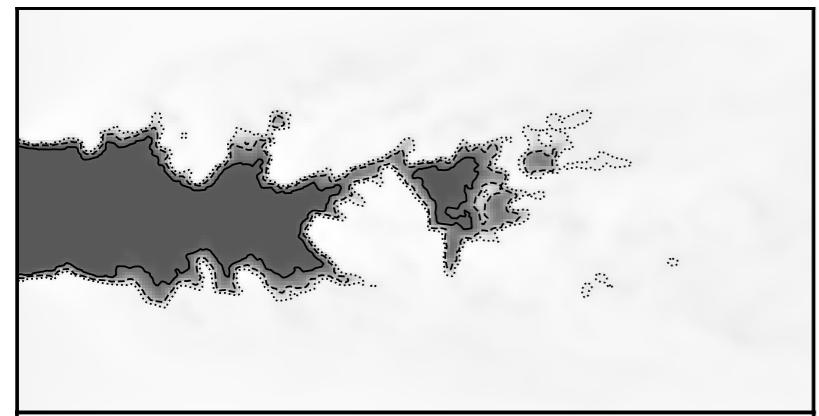
A priori strategy

Training setup

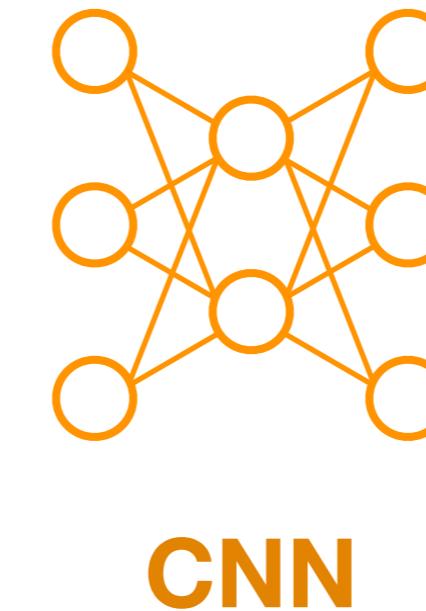


A priori strategy

Training setup

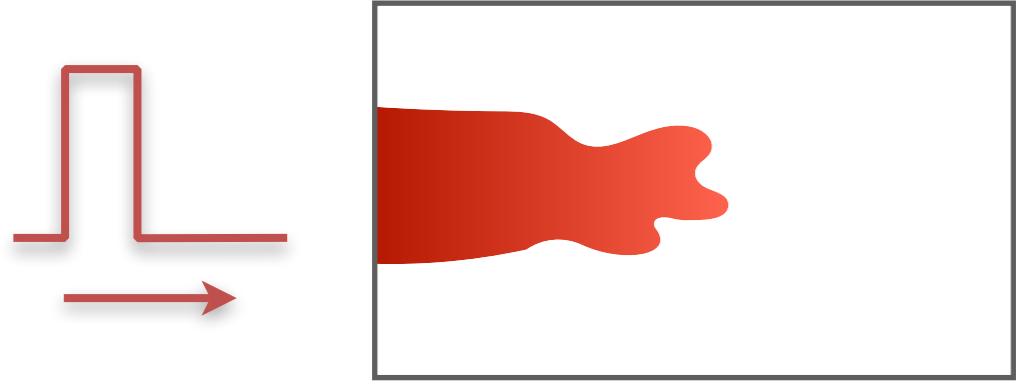


Training

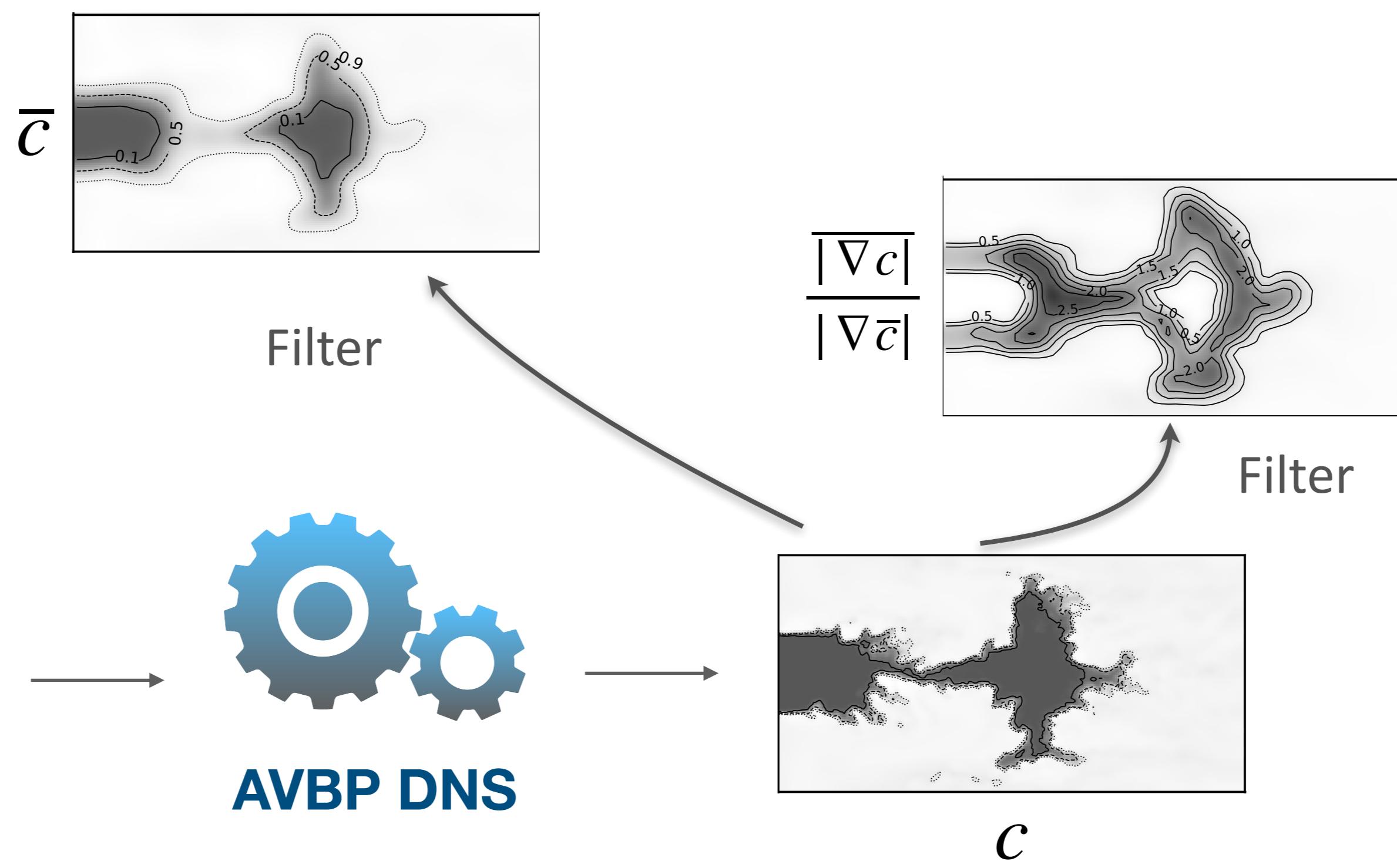


CNN

Target setup



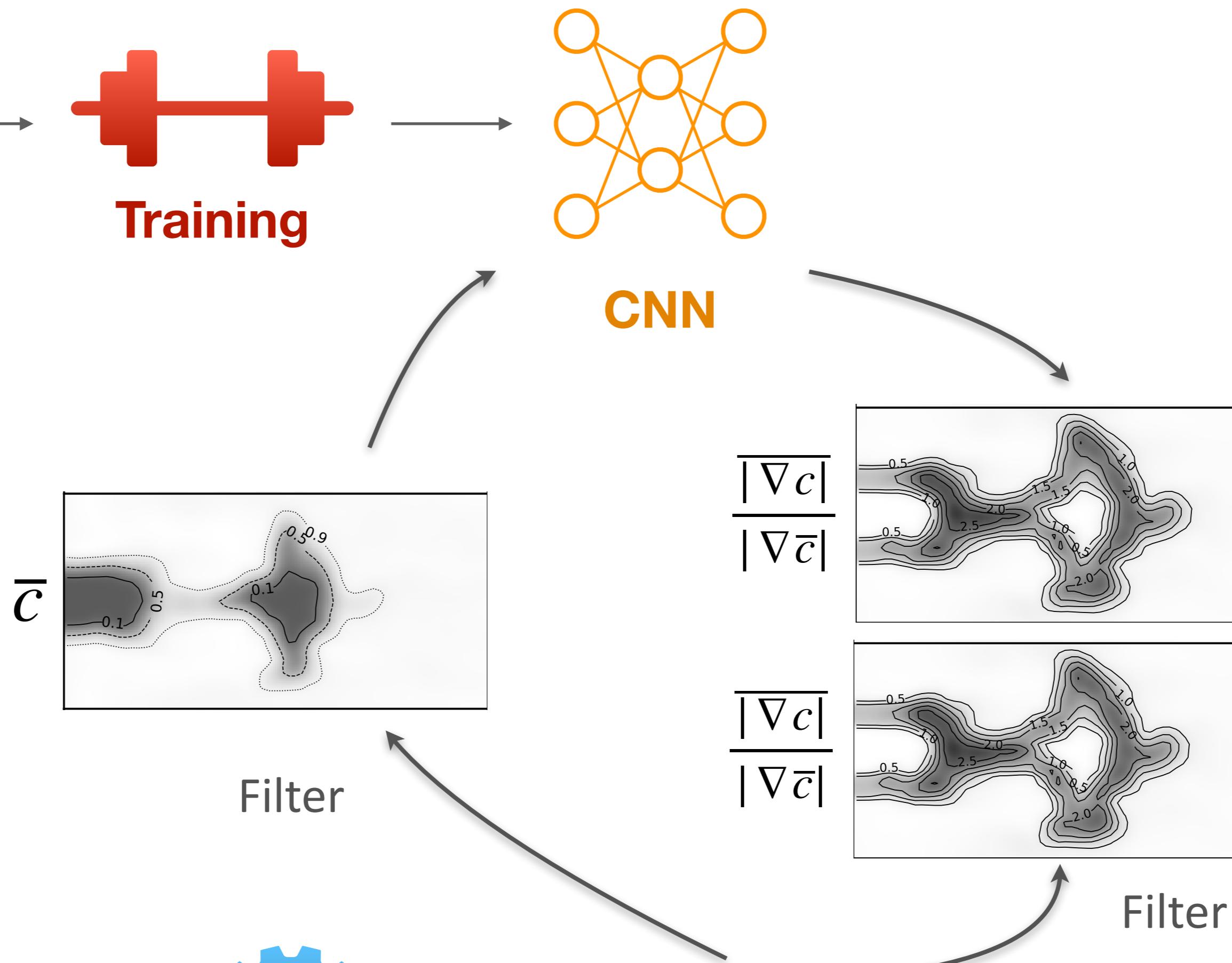
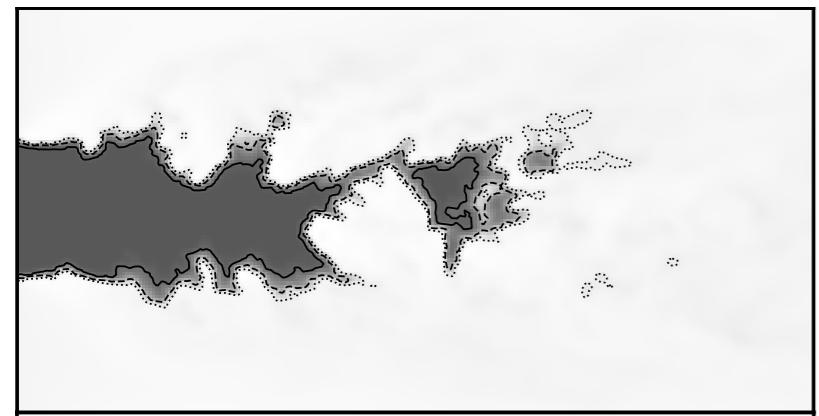
AVBP DNS



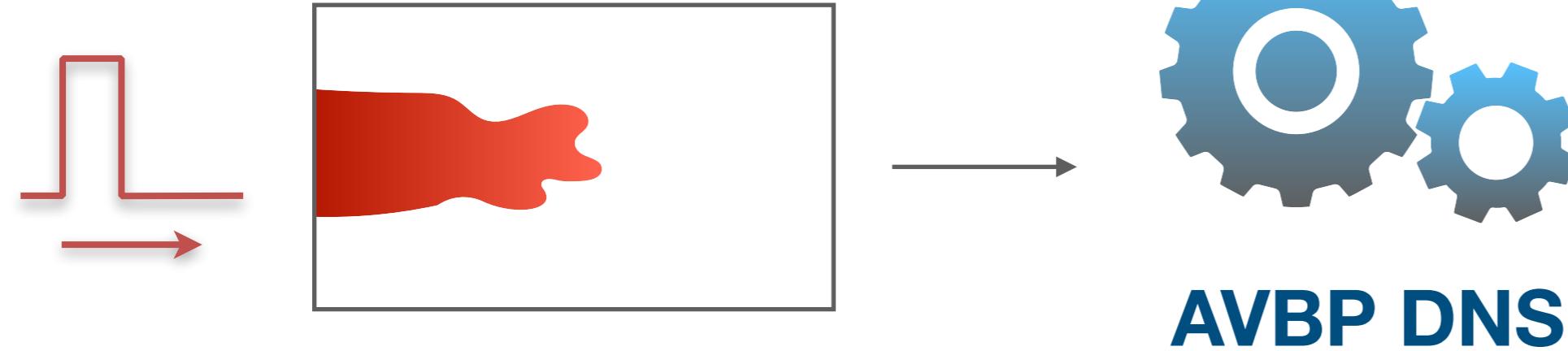
c

A priori strategy

Training setup

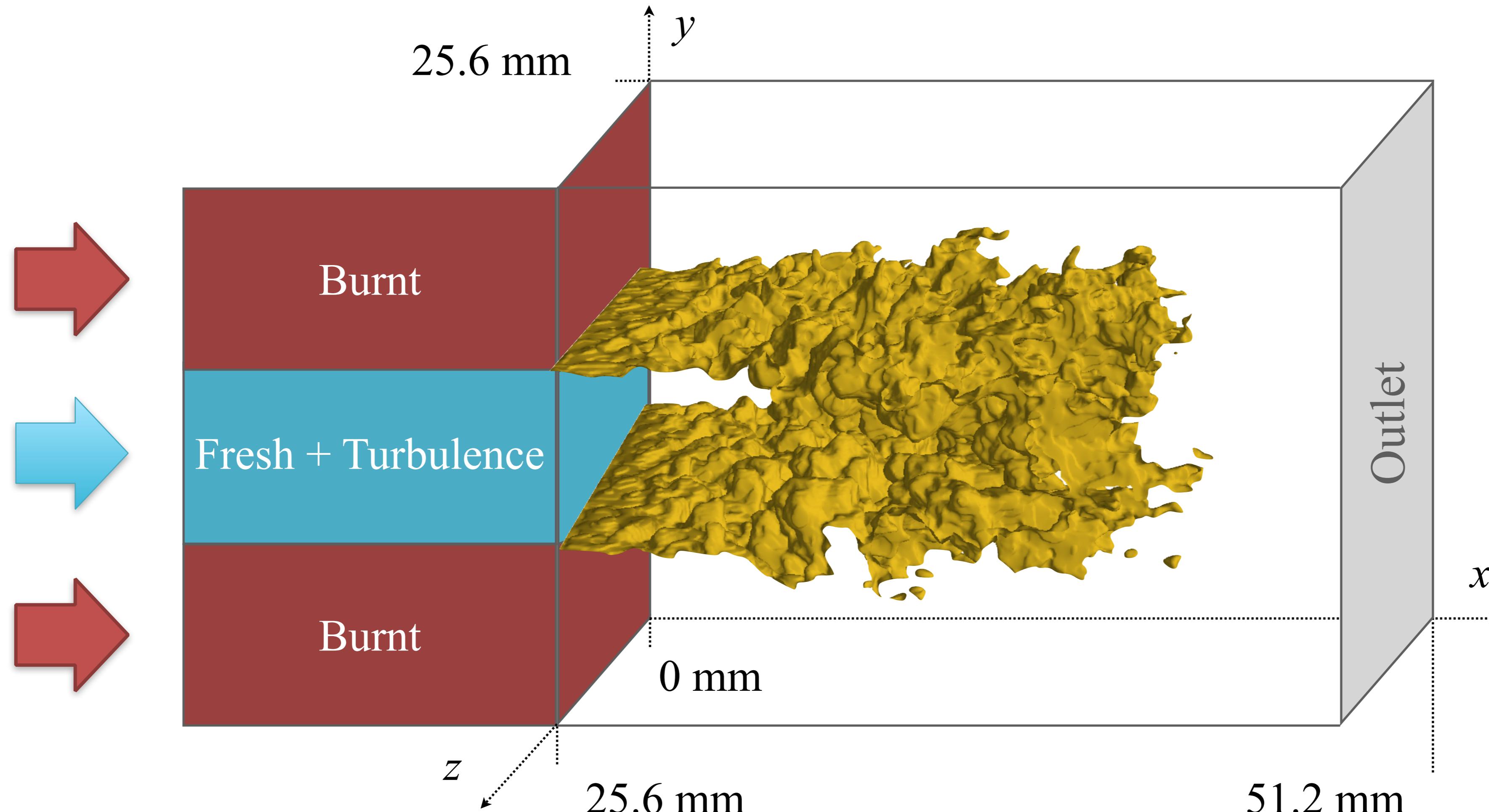


Target setup



c

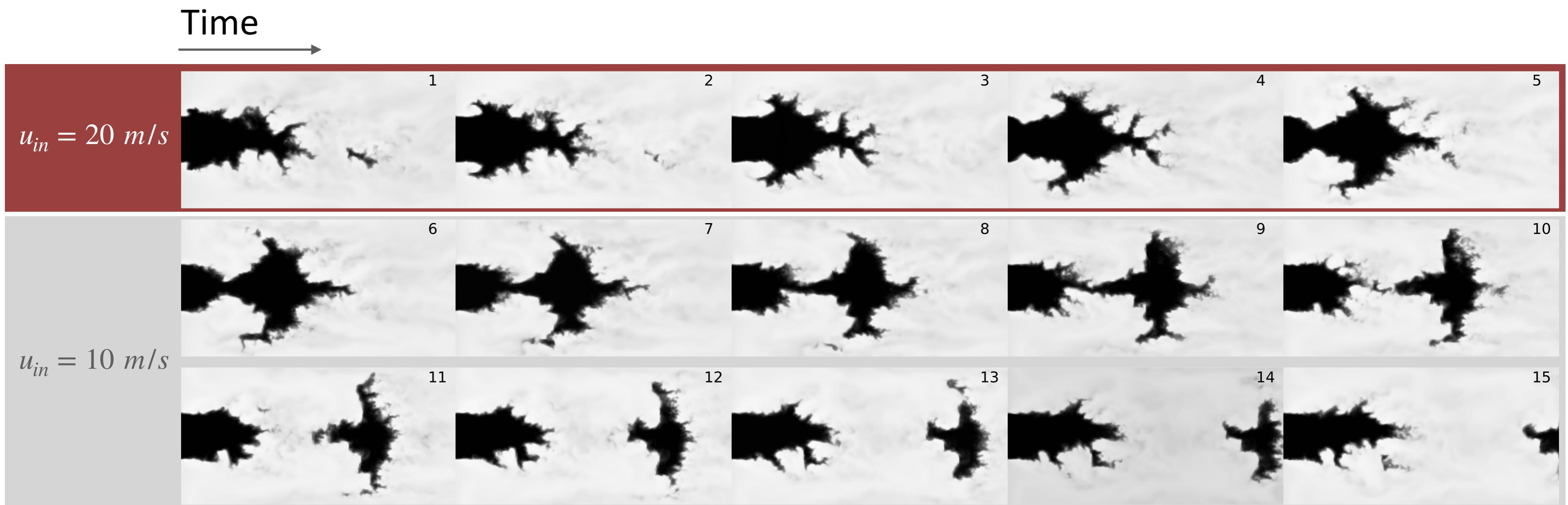
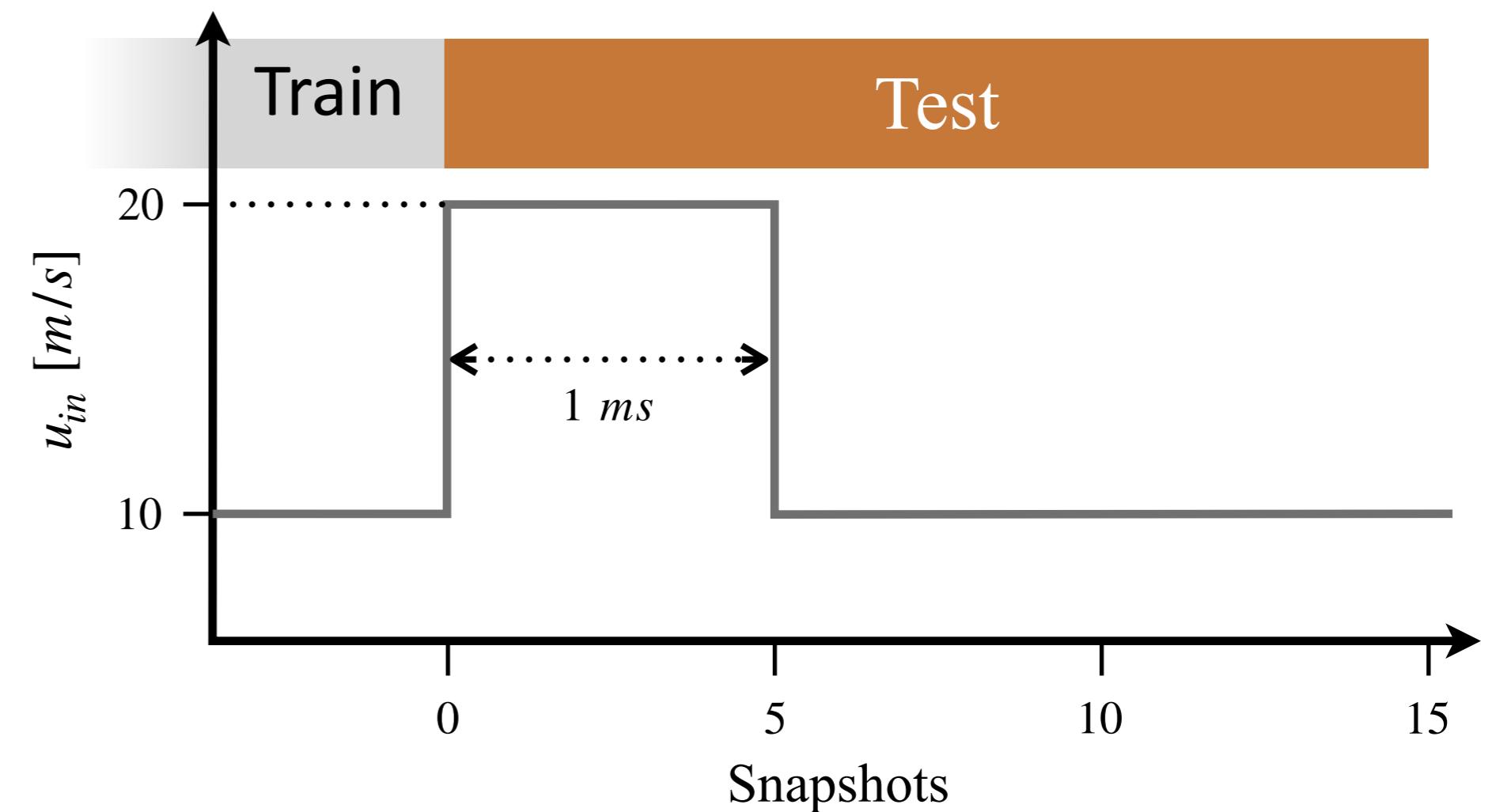
DNS for training



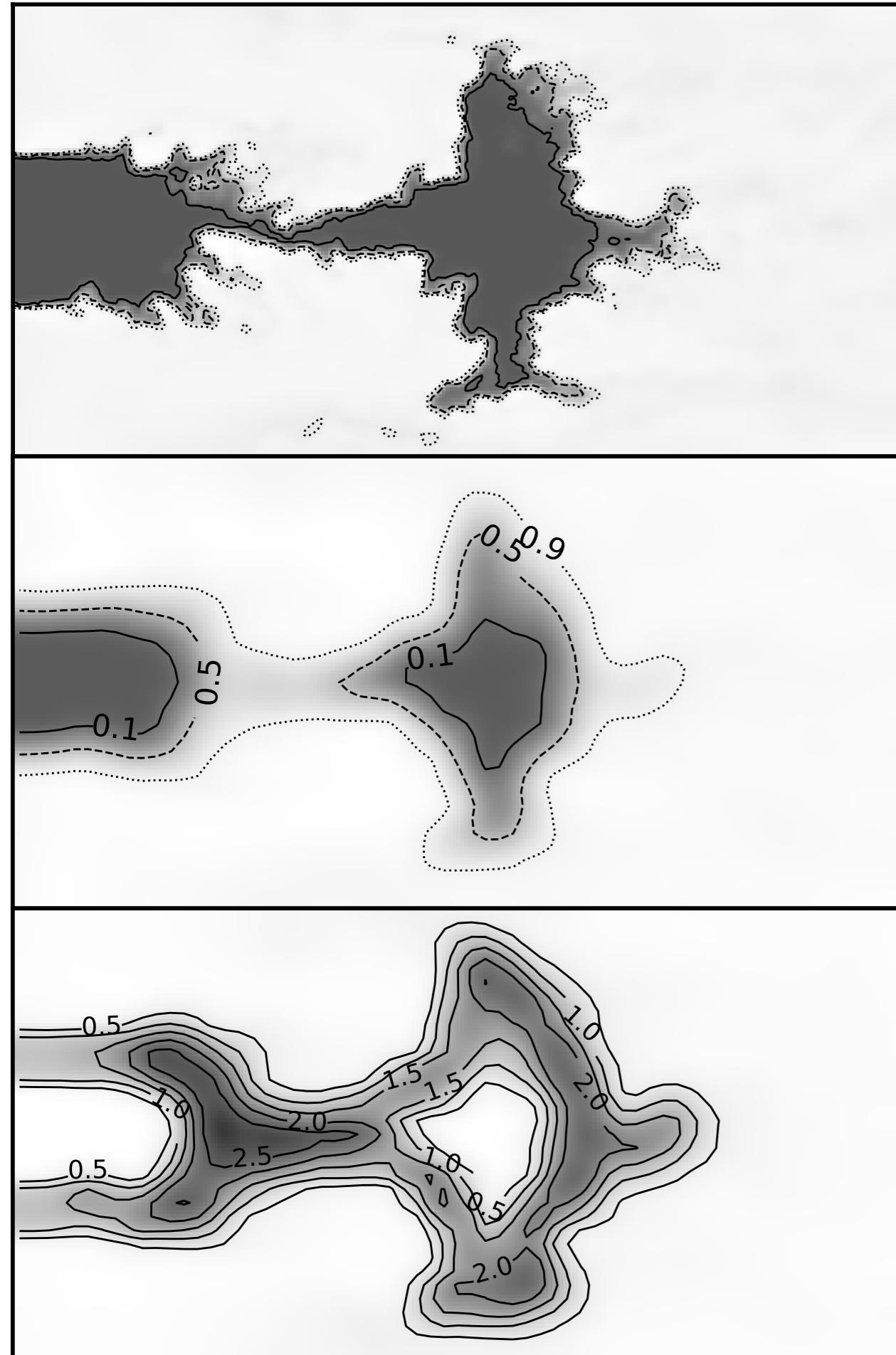
Similar to: Bell, J. B., Day, M. S., Grcar, J. F., Lijewski, M. J., Driscoll, J. F., & Filatyev, S. A. (2007). Numerical simulation of a laboratory-scale turbulent slot flame. *Proceedings of the combustion institute*, 31(1), 1299-1307.

A priori test

- Test case: unsteady flow dynamics

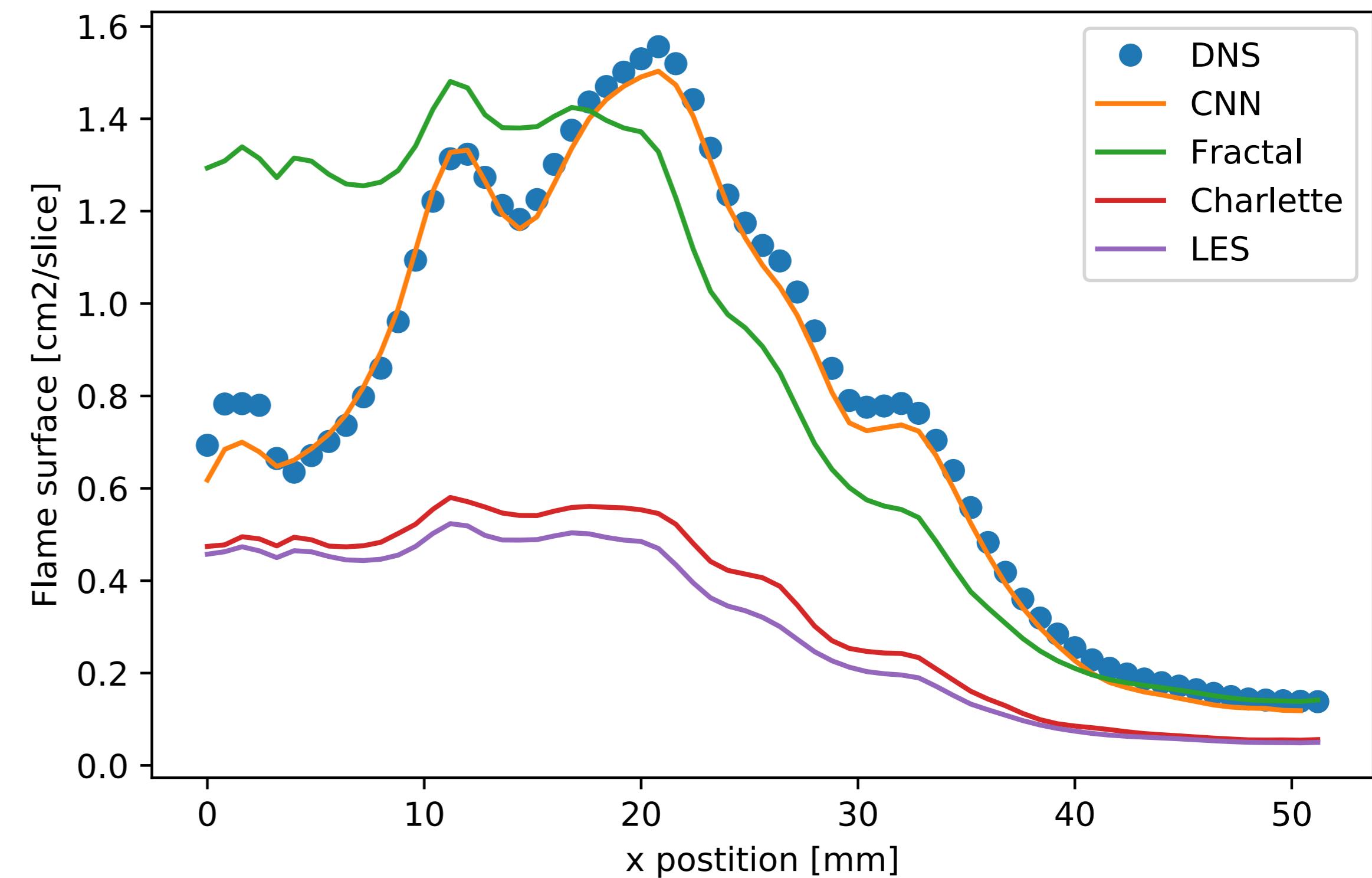


A priori results

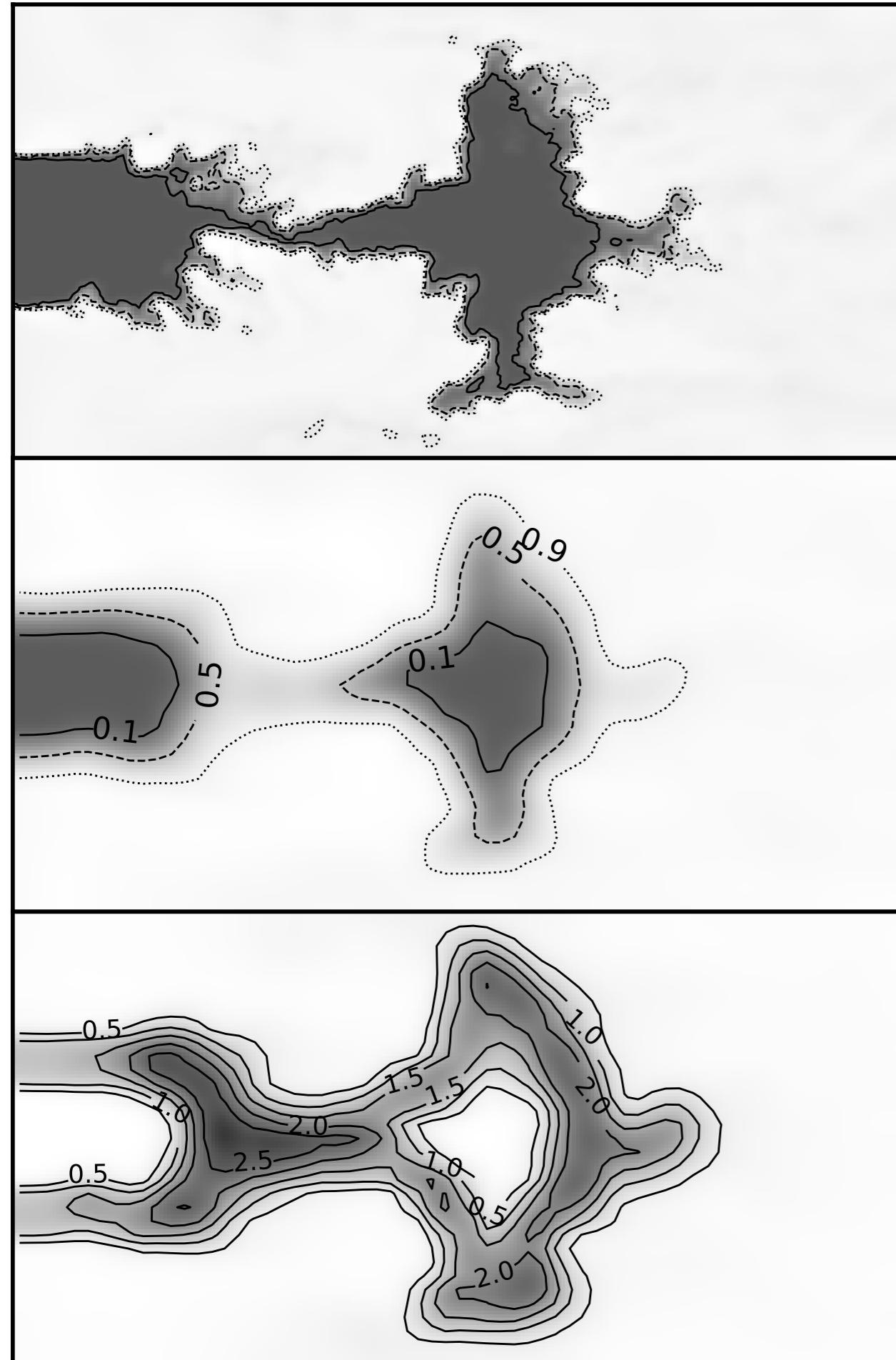


Example snapshot during test

DNS
LES input
LES model

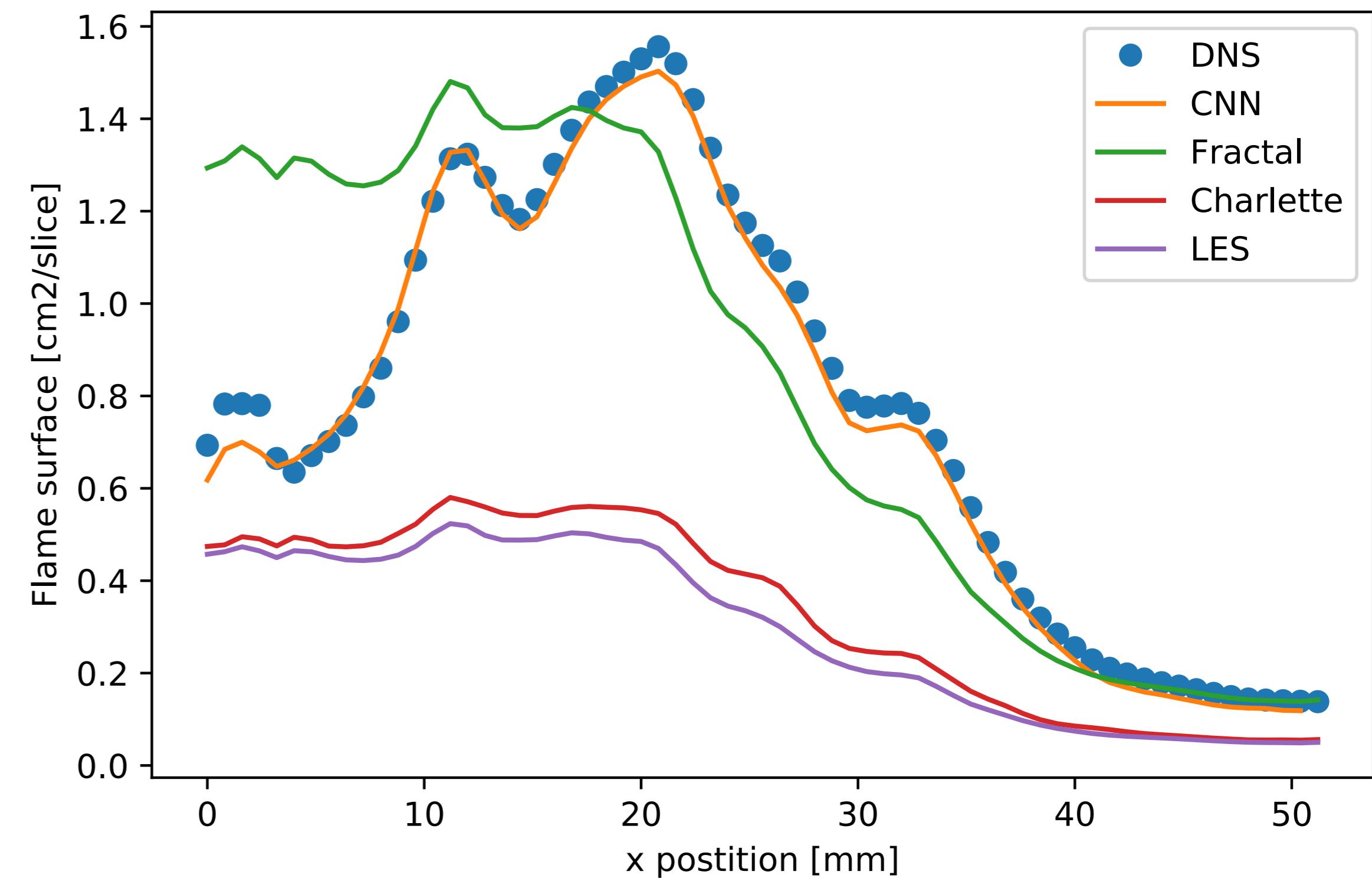


A priori results



Example snapshot during test

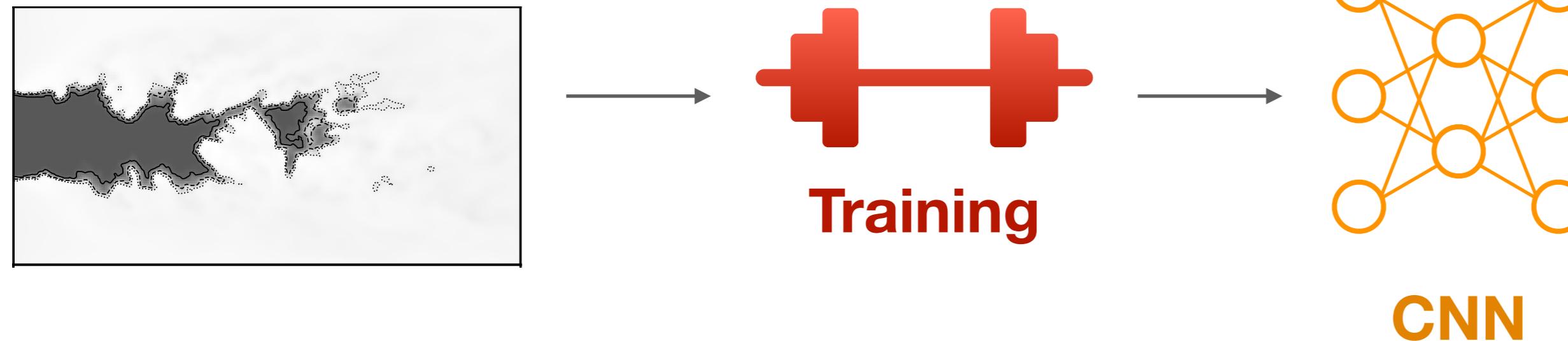
DNS
LES input
LES model



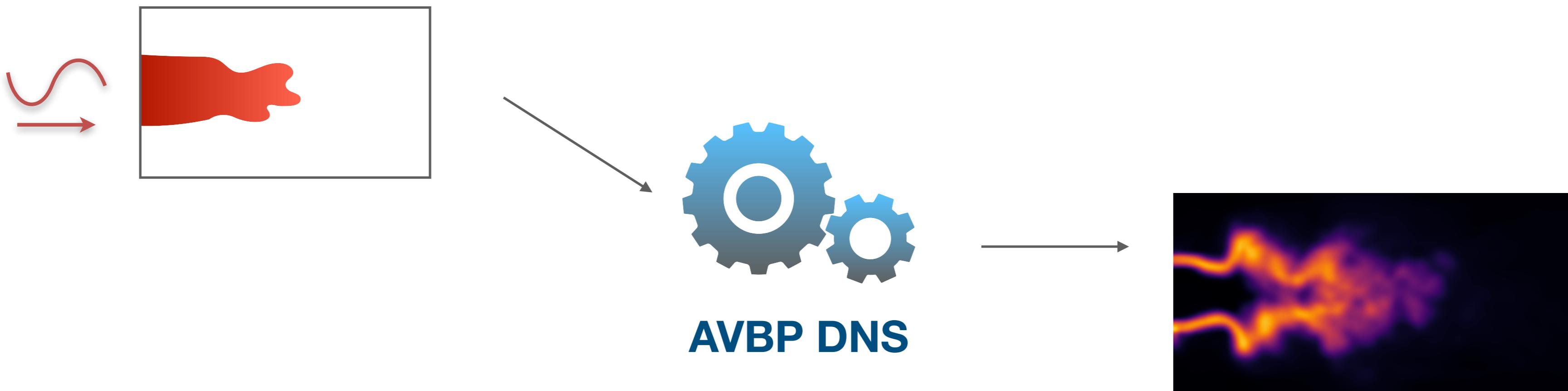
Excellent agreement compared to litterature.

A posteriori strategy

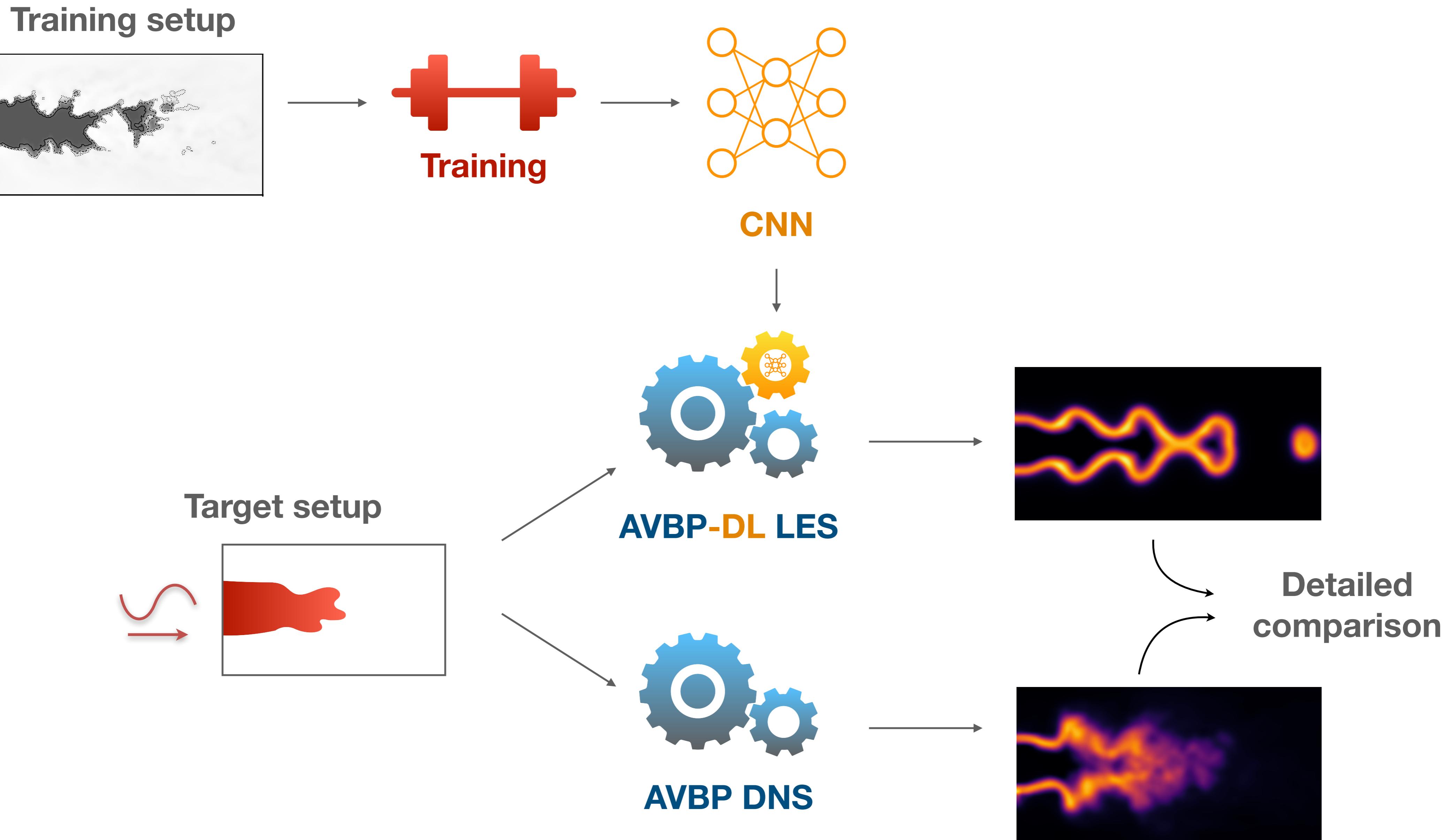
Training setup



Target setup



A posteriori strategy

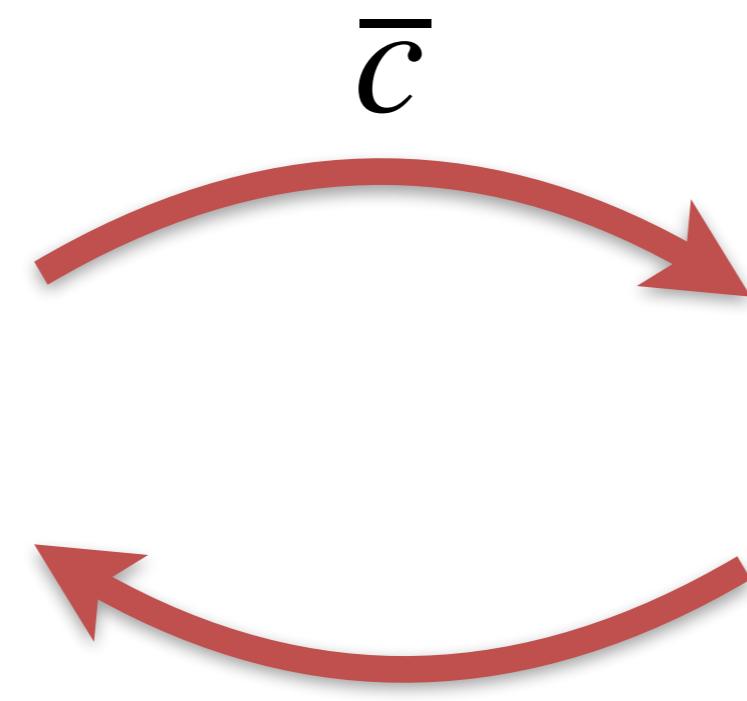


Tests a posteriori in LES:

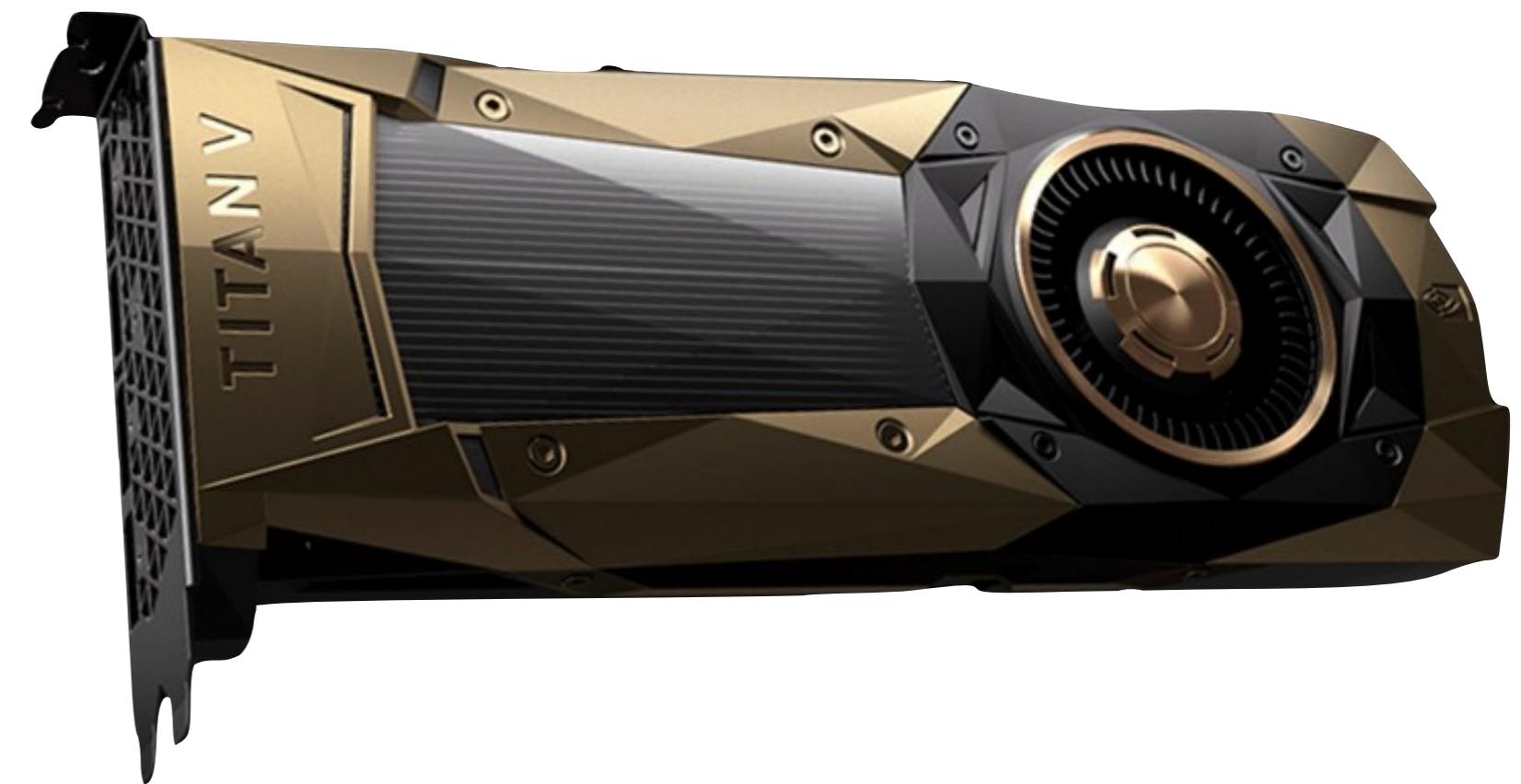
- The CNN can be integrated in AVBP code to compute flame wrinkling but the inference time (evaluation of f_{CNN}) becomes too long on CPU: GPUs are much better
- -> hybrid architecture is needed



CPU : Navier-Stokes solver
(AVBP)



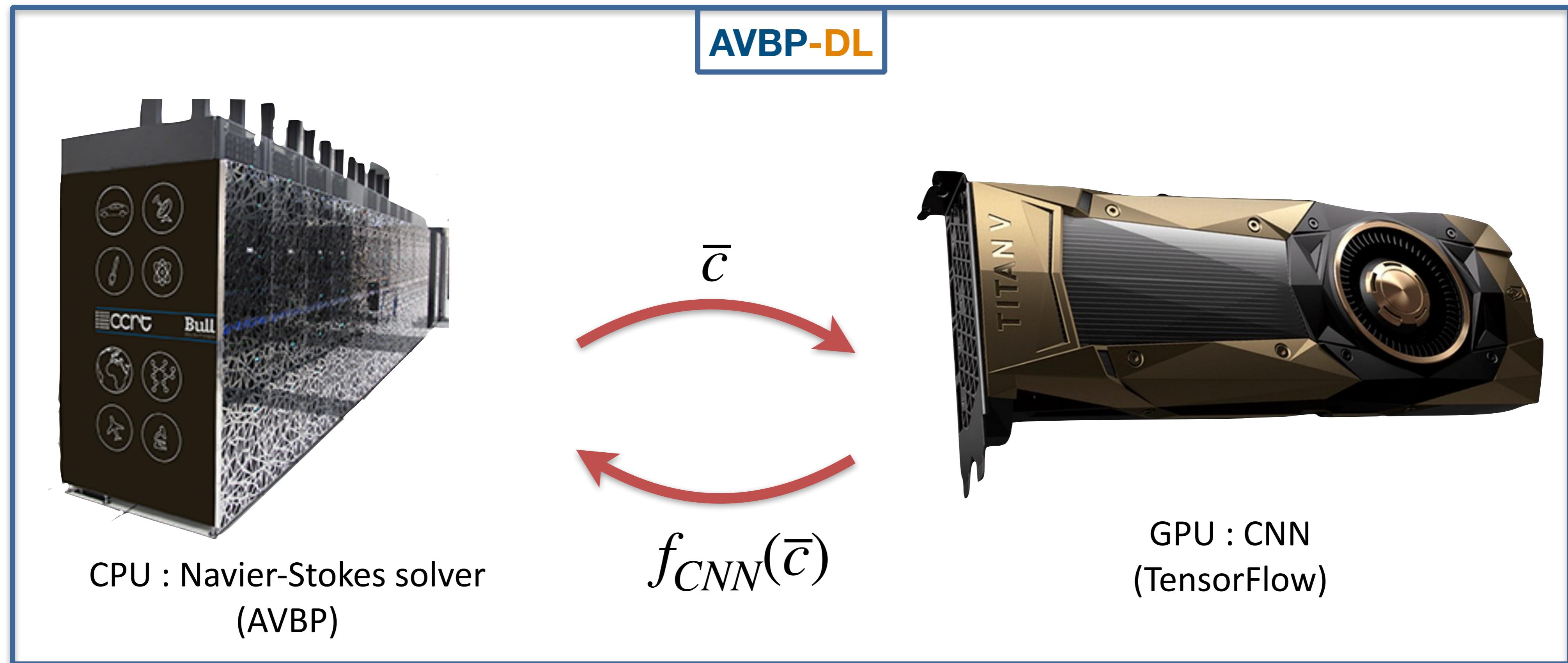
$$f_{CNN}(\bar{c})$$



GPU : CNN
(TensorFlow)

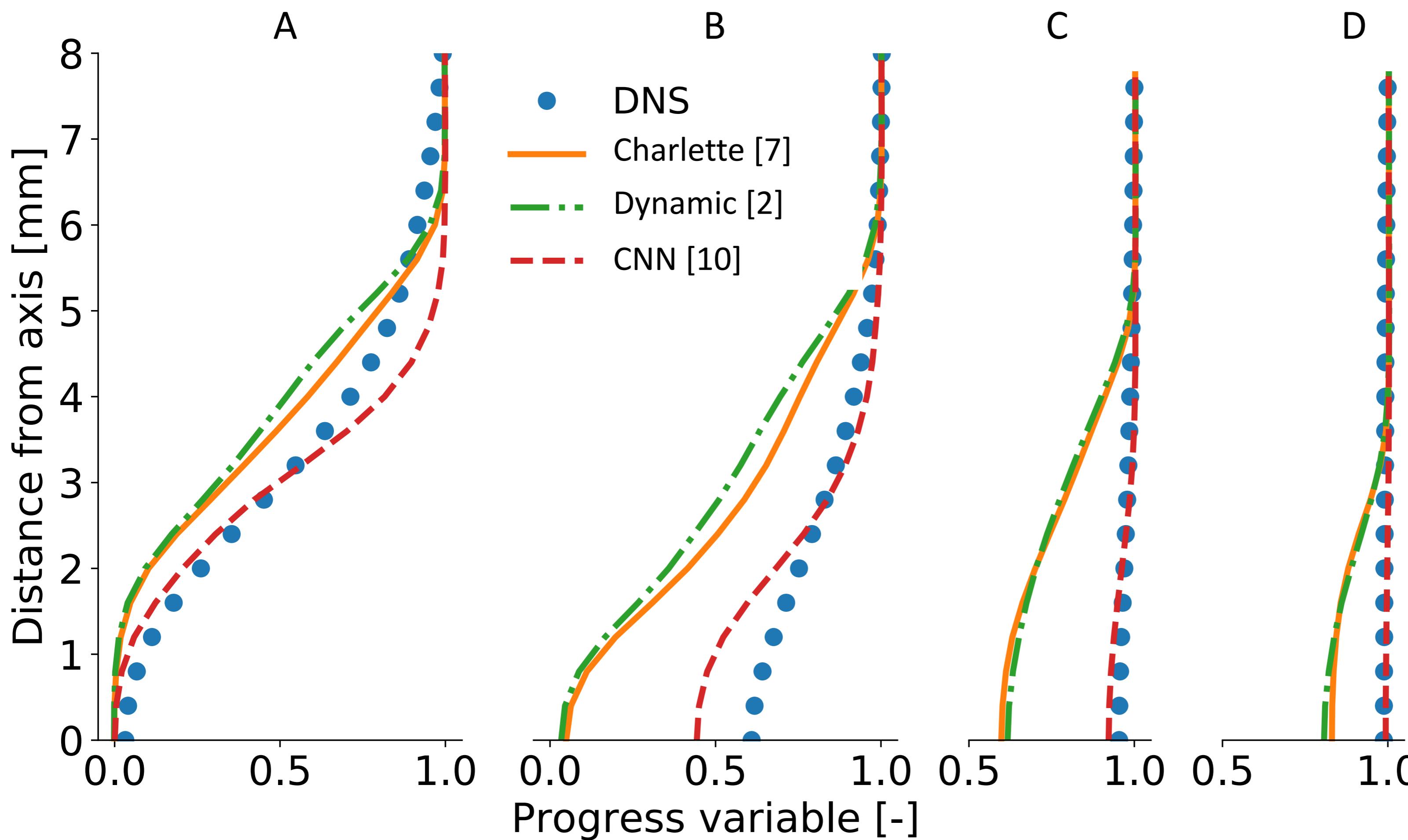
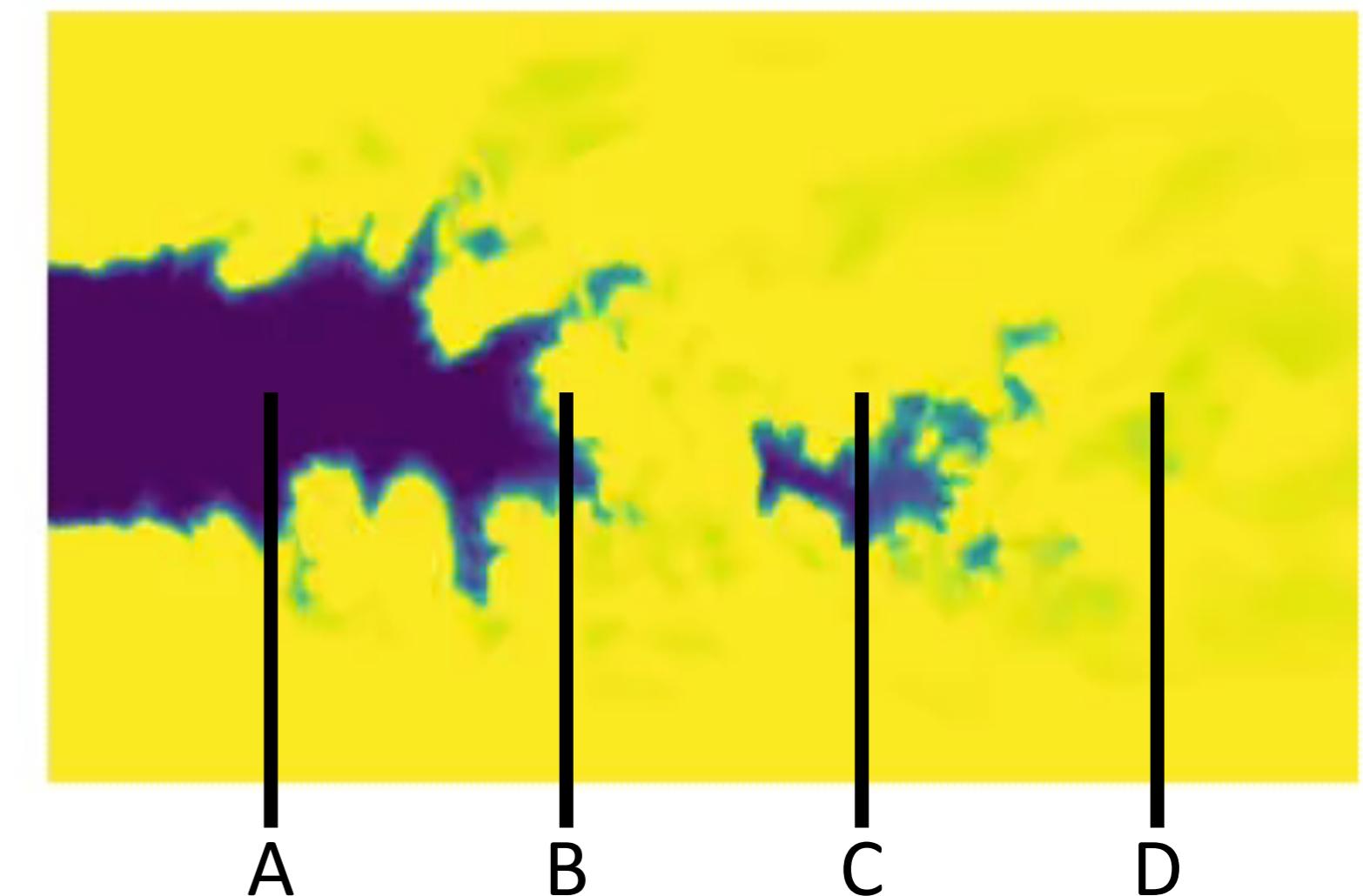
Tests a posteriori in LES:

- The CNN can be integrated in AVBP code to compute flame wrinkling but the inference time (evaluation of f_{CNN}) becomes too long on CPU: GPUs are much better
- -> hybrid architecture is needed



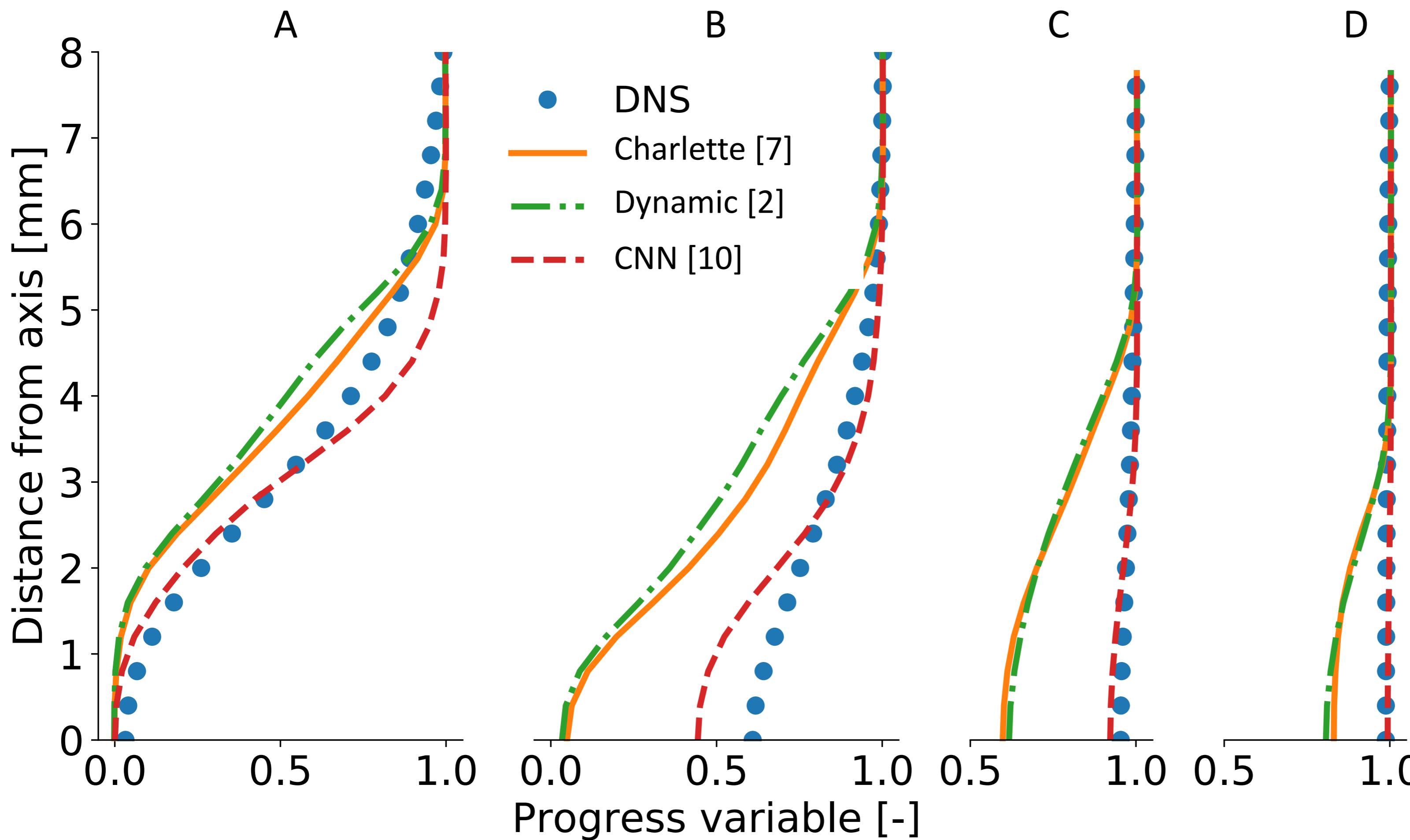
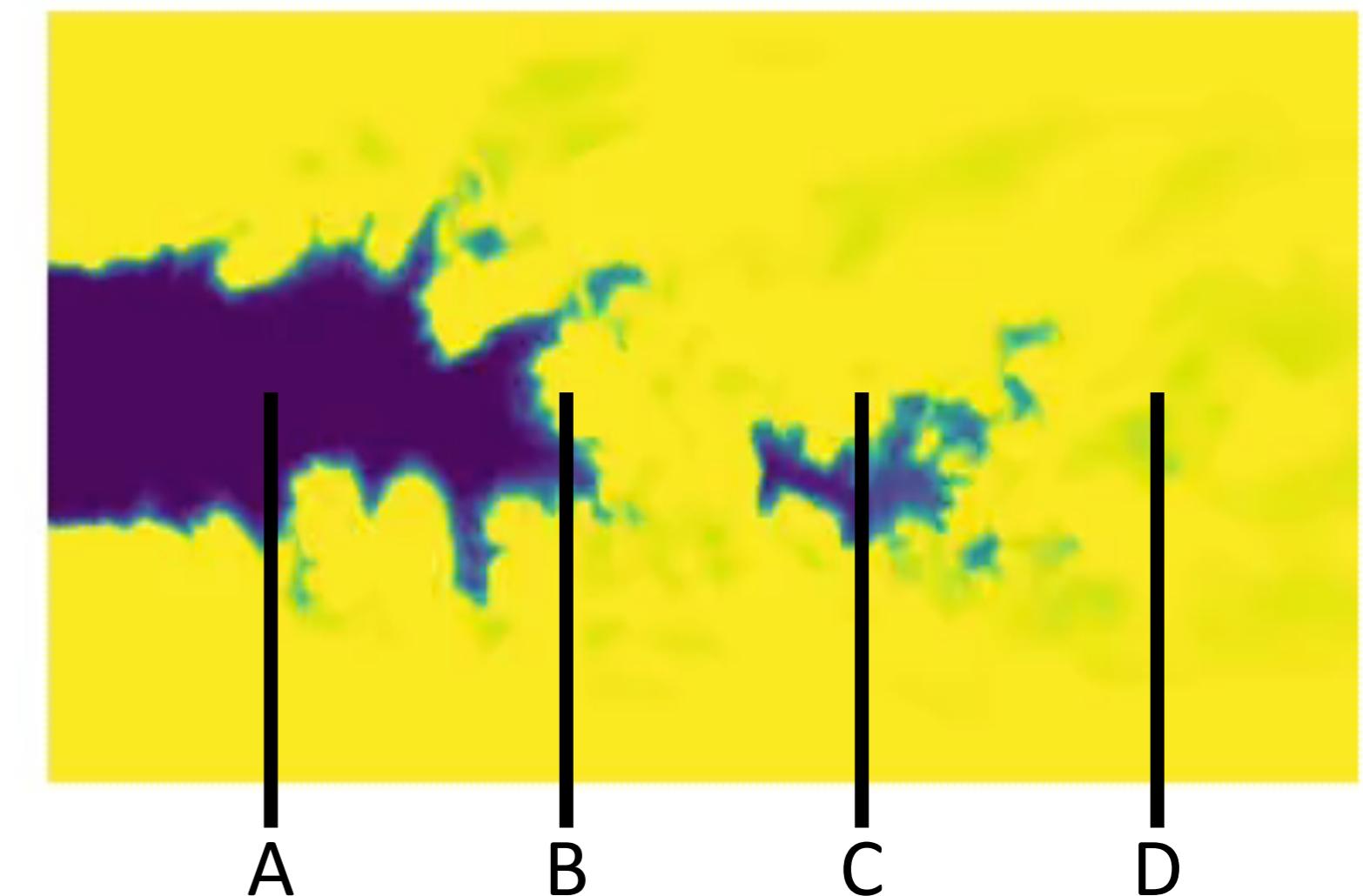
A posteriori results

- CNN performs better than state-of-the-art models on this setup



A posteriori results

- CNN performs better than state-of-the-art models on this setup

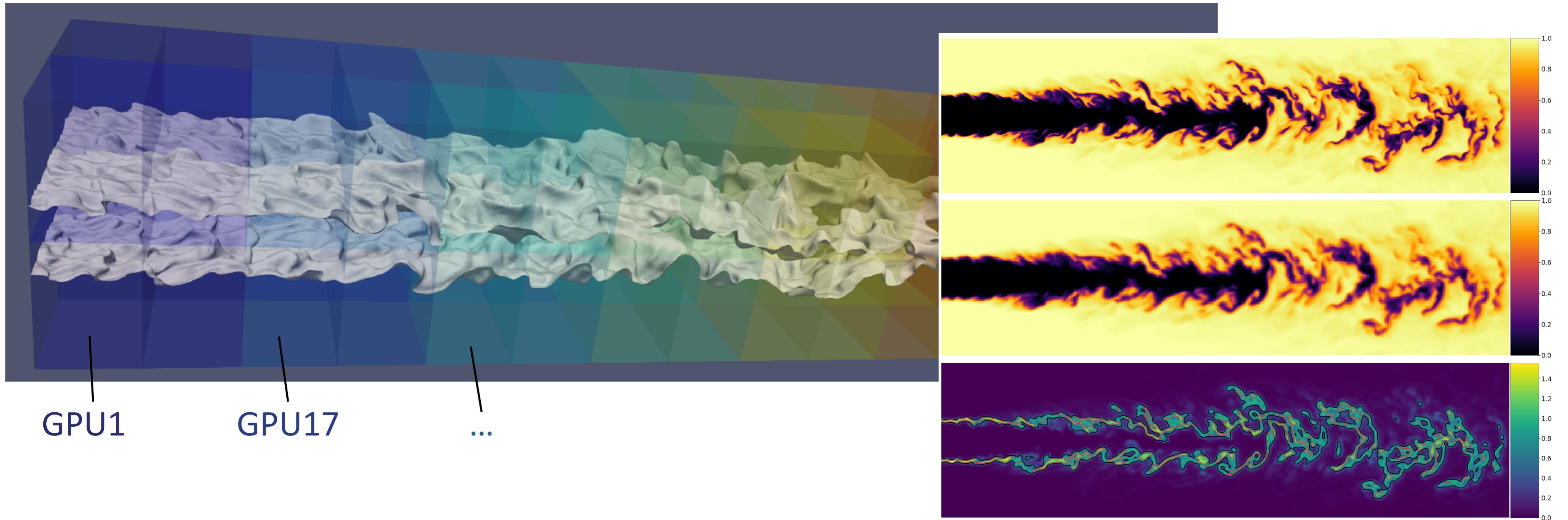


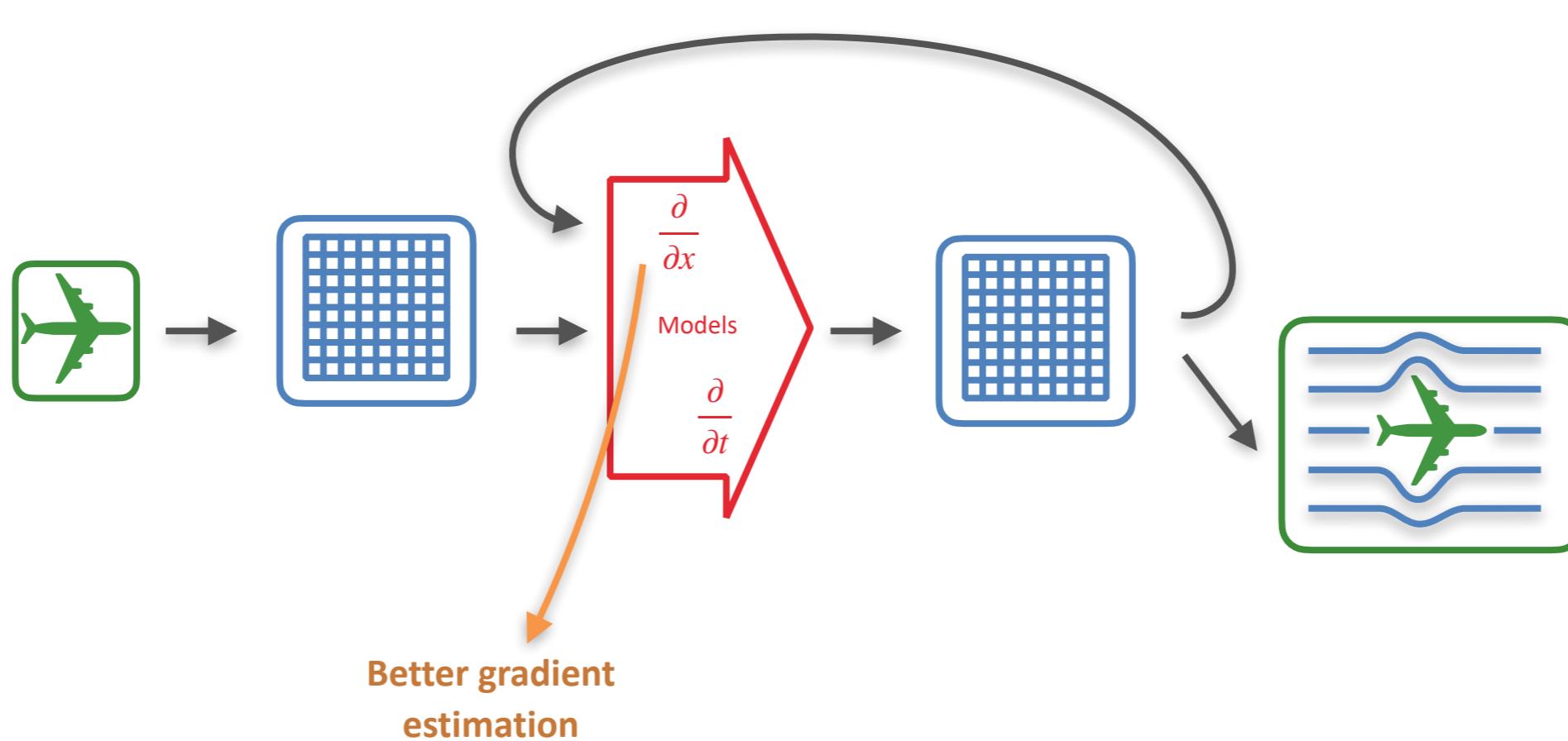
JZ Grand Challenge

- We target large scale LES => hybrid CPU/GPU and solver/neural network approach must scale to HPC
- 2019-2020: Jean Zay Grand Challenge

AVBP-DL: 2000 CPU + 64 GPU simulation on Jean Zay

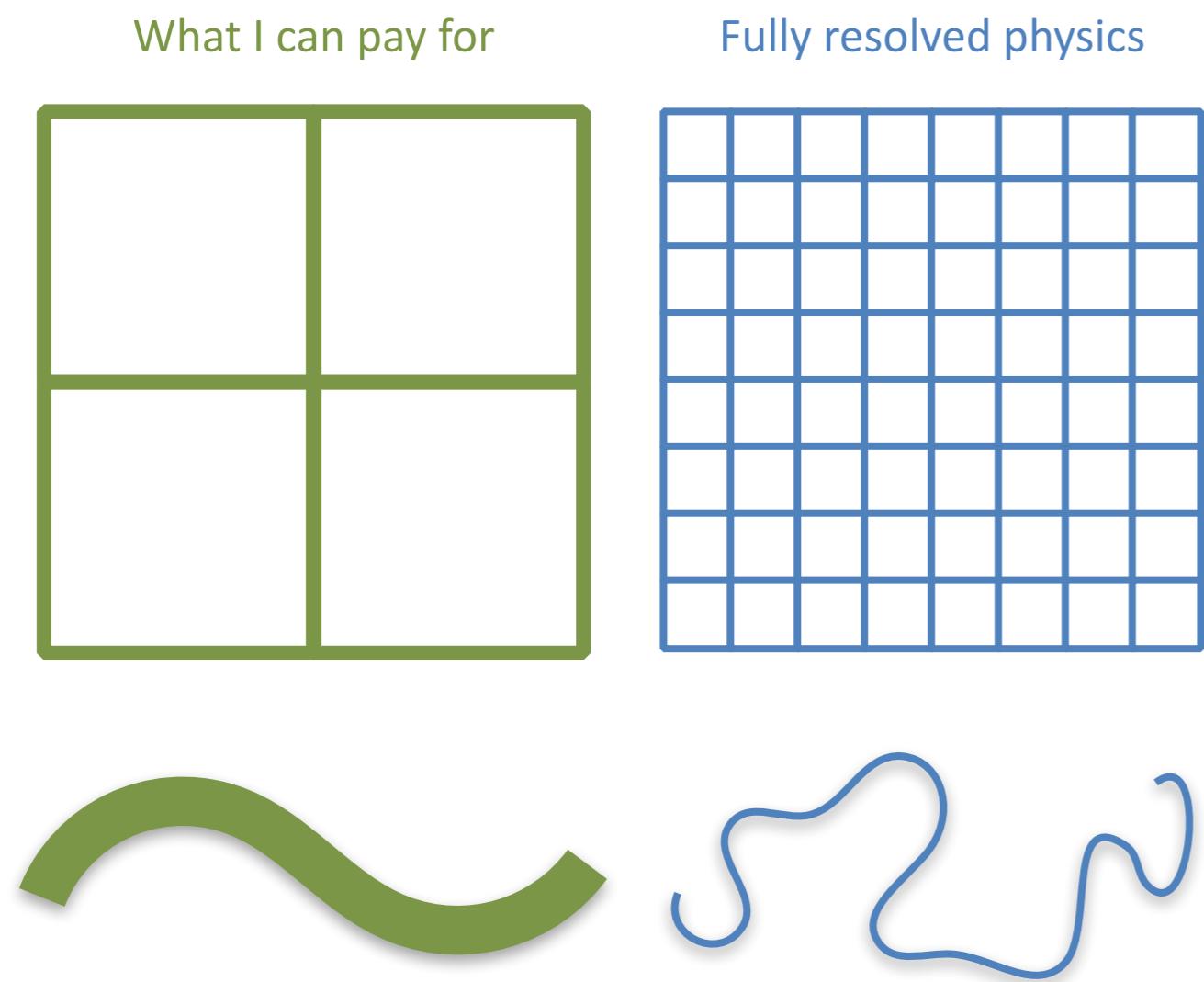
V. Xing, A. Misdariis, G. Staffelbach, C. Lapeyre





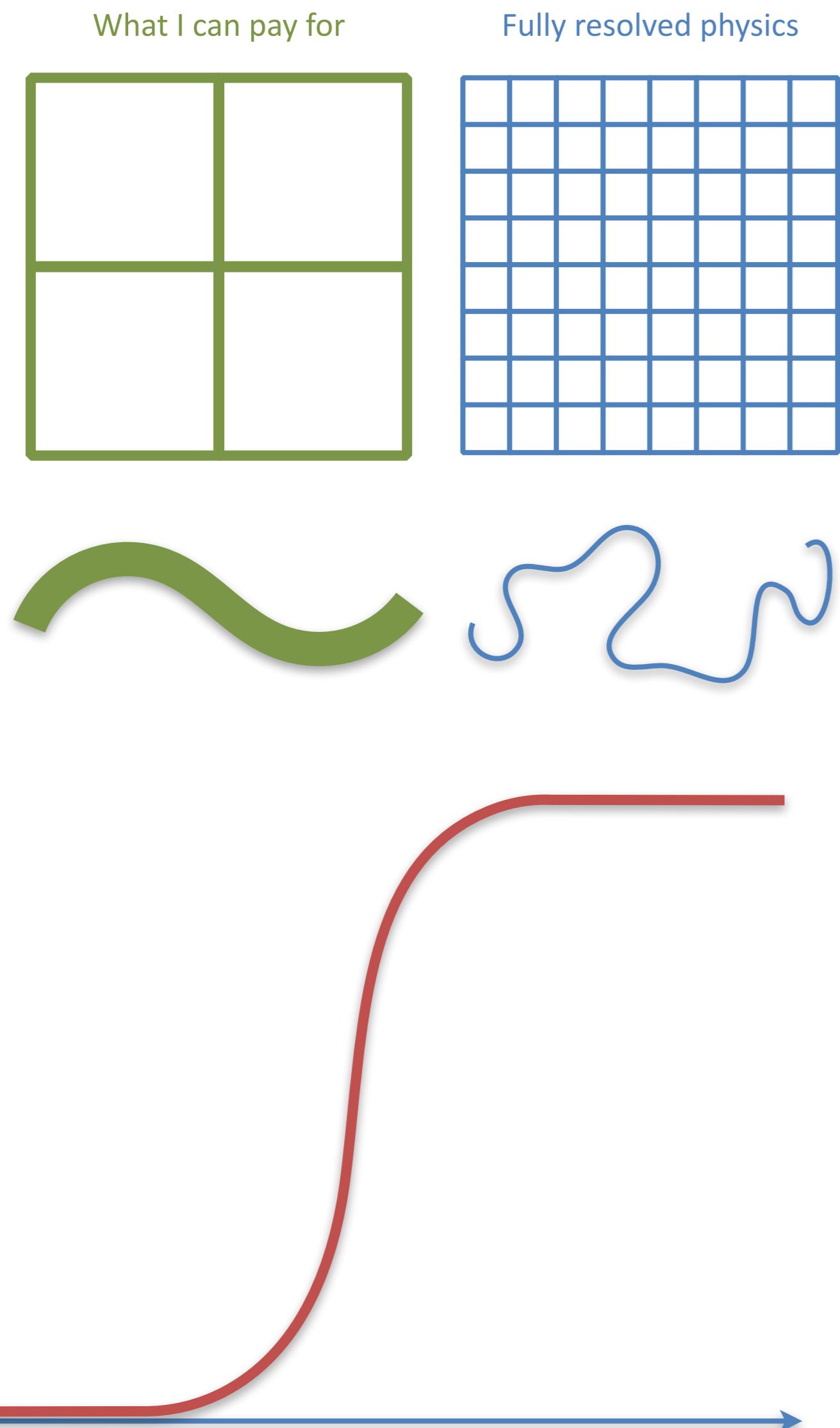
2. Data-driven discretization

Solving fine structures



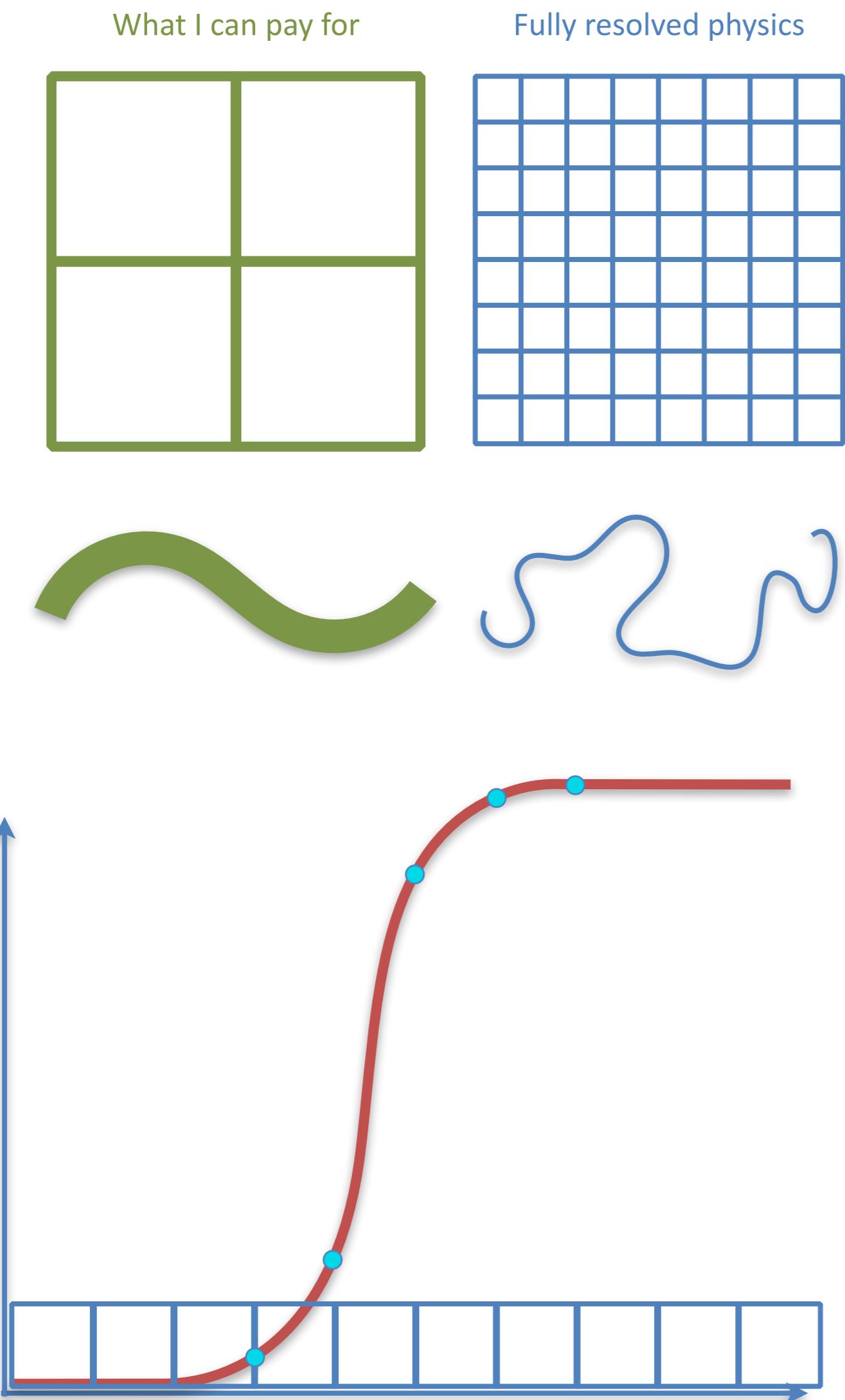
Bar-Sinai, Y., Hoyer, S., Hickey, J., & Brenner, M. P. (2019). Learning data-driven discretizations for partial differential equations. *Proceedings of the National Academy of Sciences*, 116(31), 15344-15349.

Solving fine structures



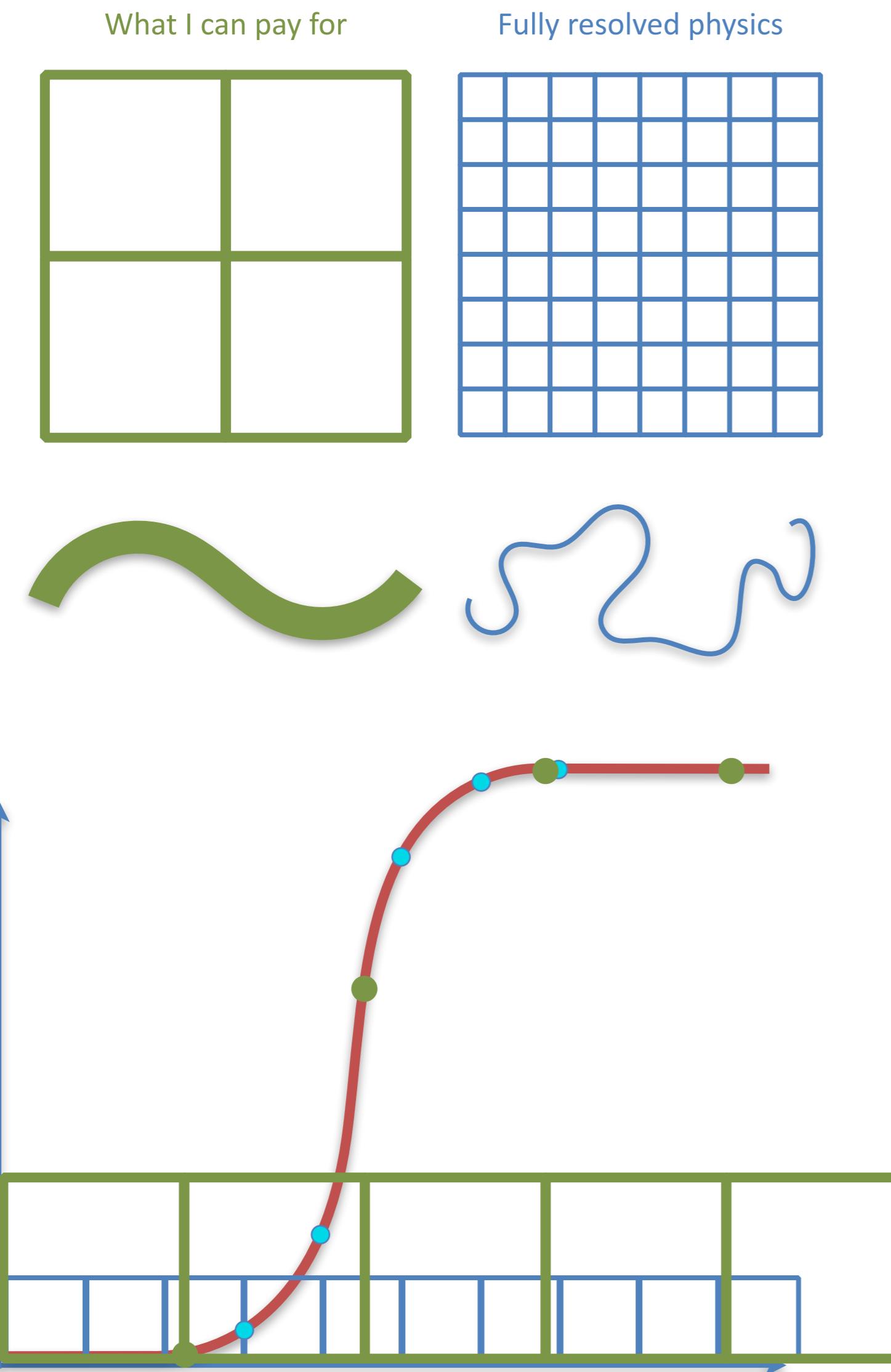
Bar-Sinai, Y., Hoyer, S., Hickey, J., & Brenner, M. P. (2019). Learning data-driven discretizations for partial differential equations. *Proceedings of the National Academy of Sciences*, 116(31), 15344-15349.

Solving fine structures



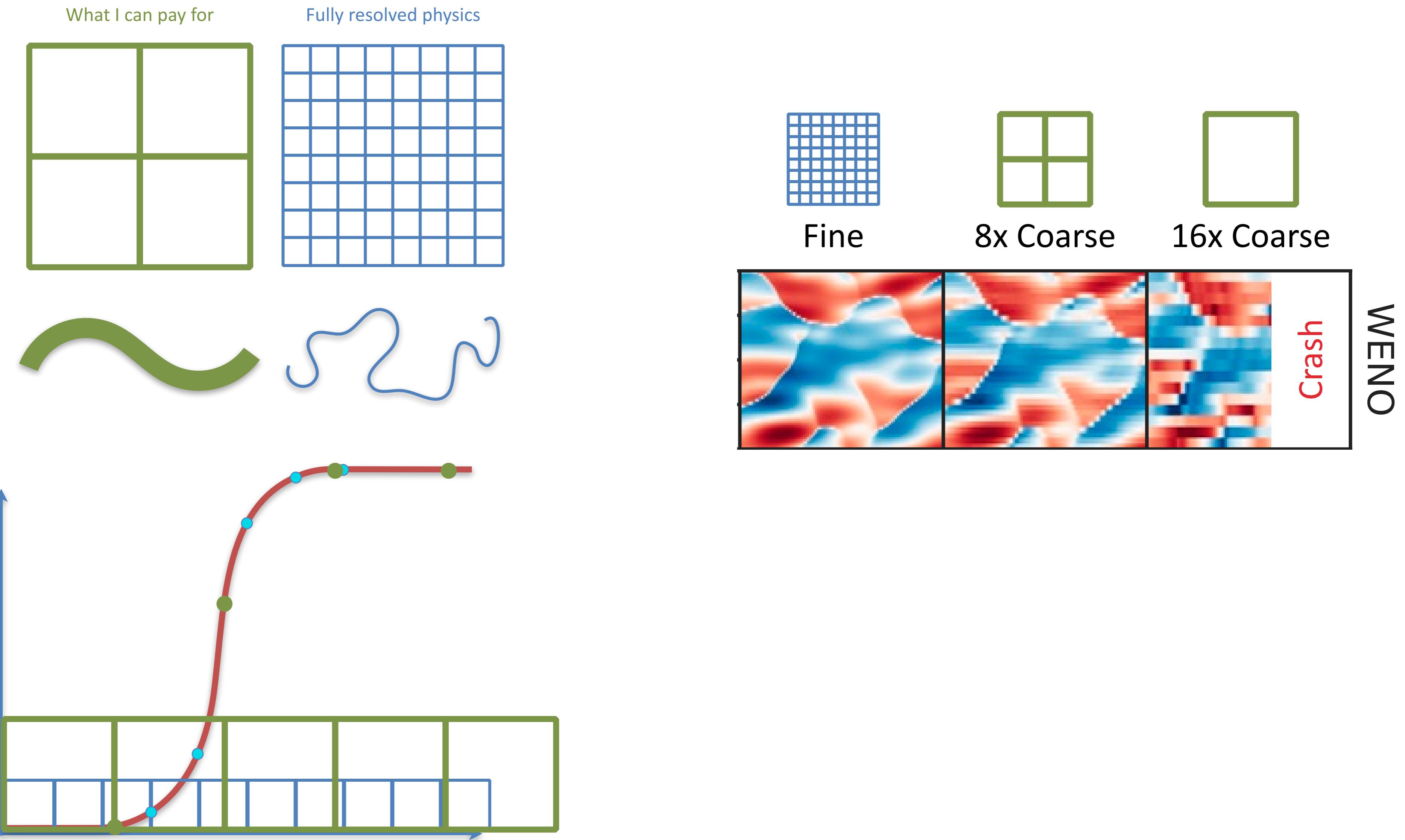
Bar-Sinai, Y., Hoyer, S., Hickey, J., & Brenner, M. P. (2019). Learning data-driven discretizations for partial differential equations. *Proceedings of the National Academy of Sciences*, 116(31), 15344-15349.

Solving fine structures



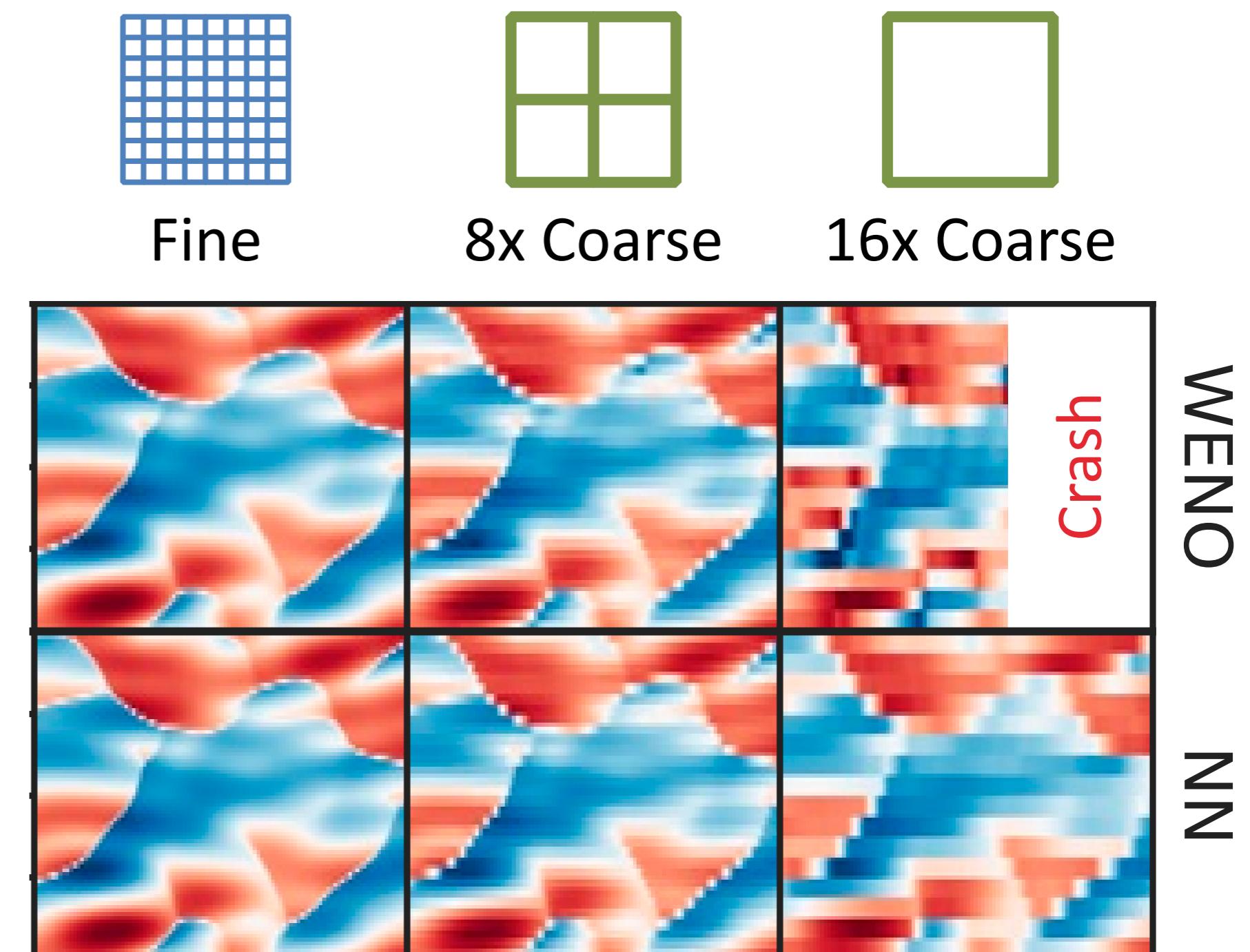
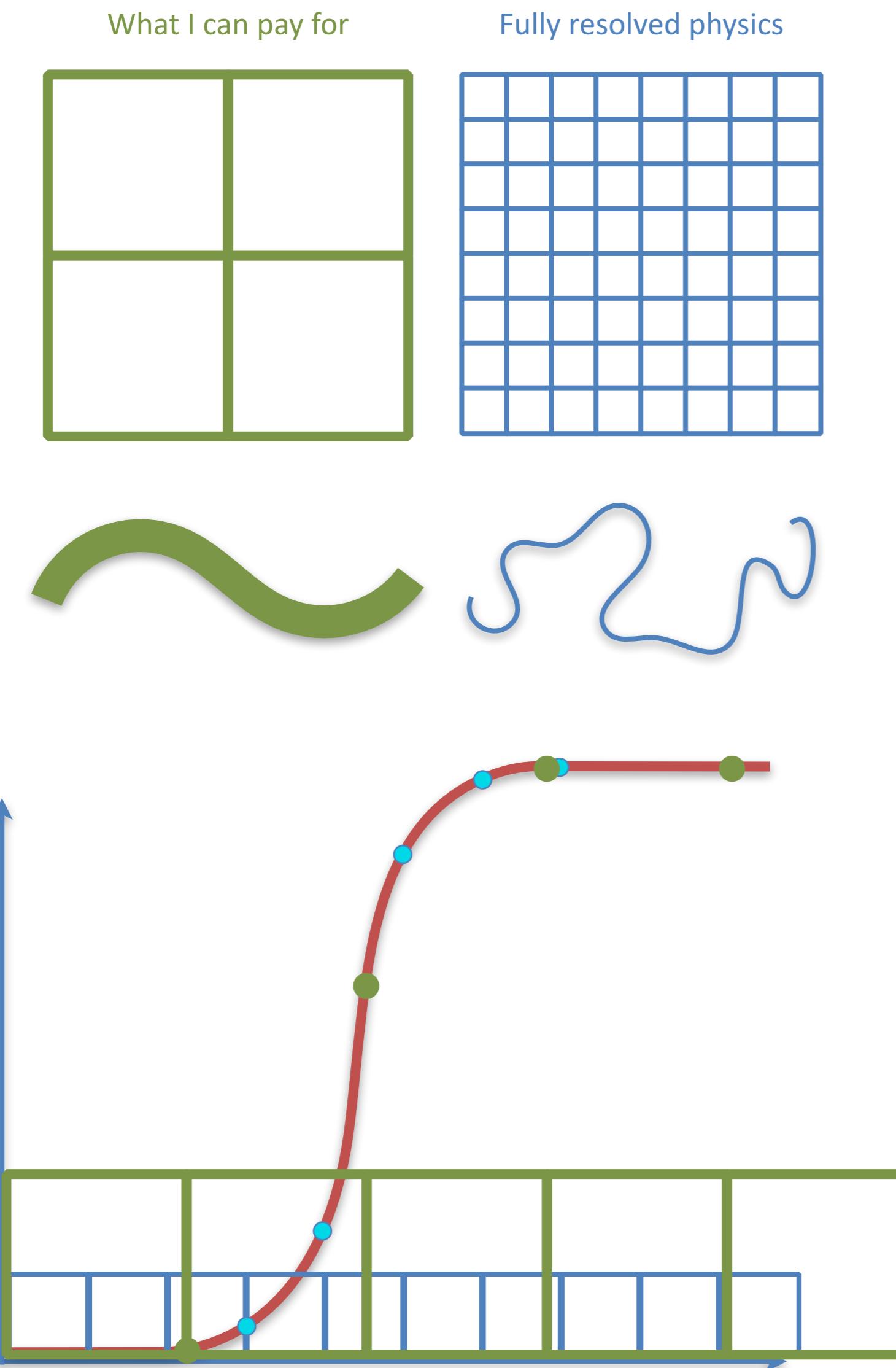
Bar-Sinai, Y., Hoyer, S., Hickey, J., & Brenner, M. P. (2019). Learning data-driven discretizations for partial differential equations. *Proceedings of the National Academy of Sciences*, 116(31), 15344-15349.

Solving fine structures

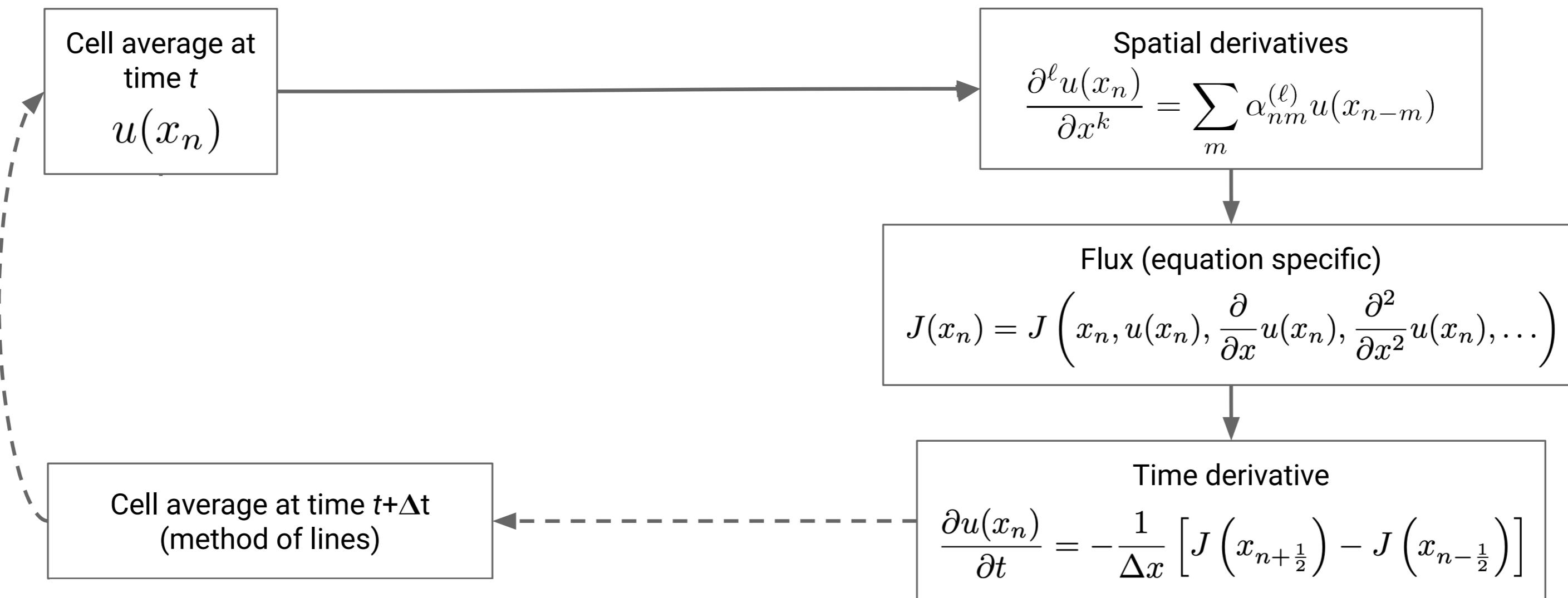


Bar-Sinai, Y., Hoyer, S., Hickey, J., & Brenner, M. P. (2019). Learning data-driven discretizations for partial differential equations. *Proceedings of the National Academy of Sciences*, 116(31), 15344-15349.

Solving fine structures



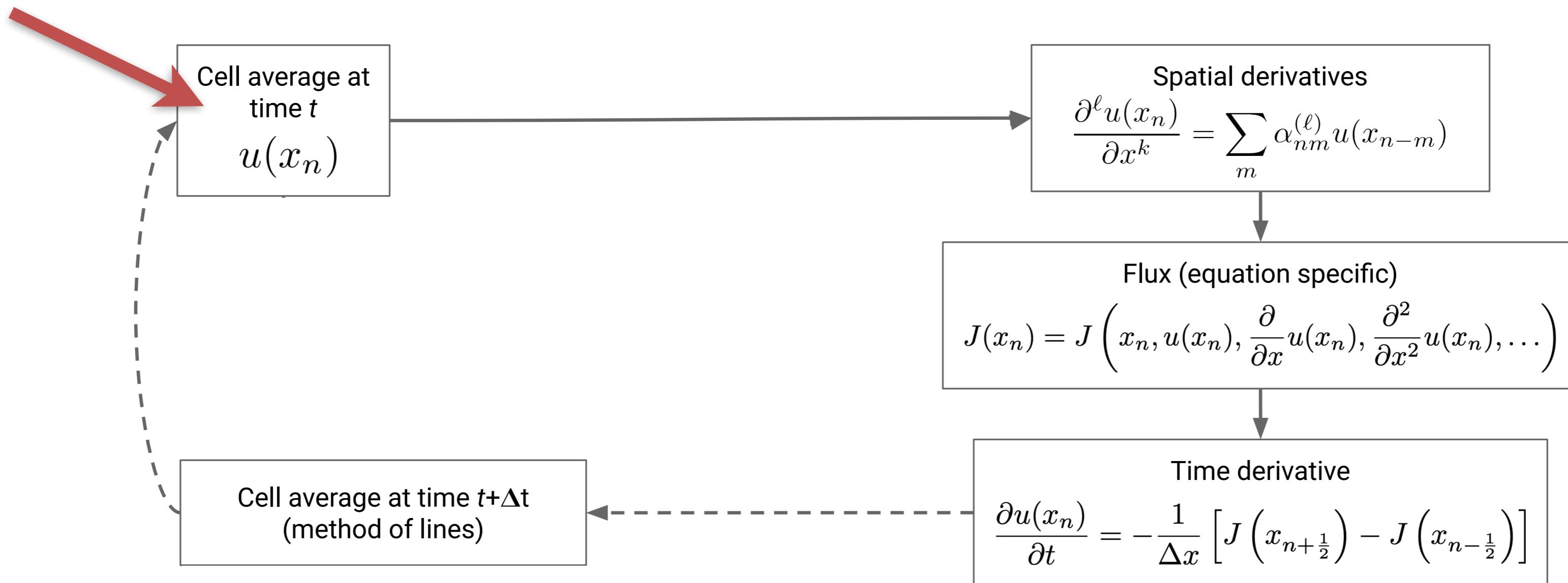
Data Driven Discretization



- One of the less intrusive approaches
- Objective: achieve better gradient estimation on coarse meshes \Leftrightarrow run same simulation on coarser mesh

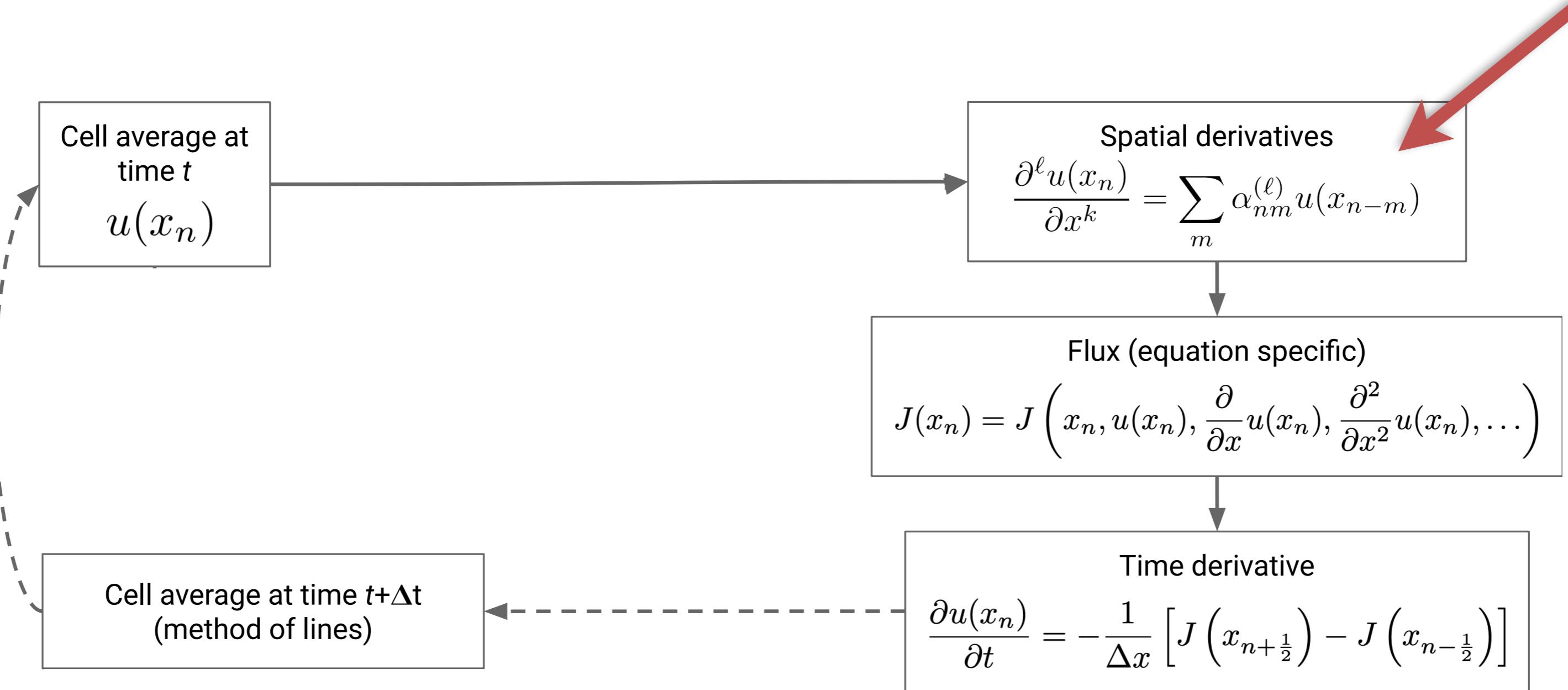
Bar-Sinai, Y., Hoyer, S., Hickey, J., & Brenner, M. P. (2019). Learning data-driven discretizations for partial differential equations. *Proceedings of the National Academy of Sciences*, 116(31), 15344-15349.

Data Driven Discretization



- One of the less intrusive approaches
- Objective: achieve better gradient estimation on coarse meshes \Leftrightarrow run same simulation on coarser mesh

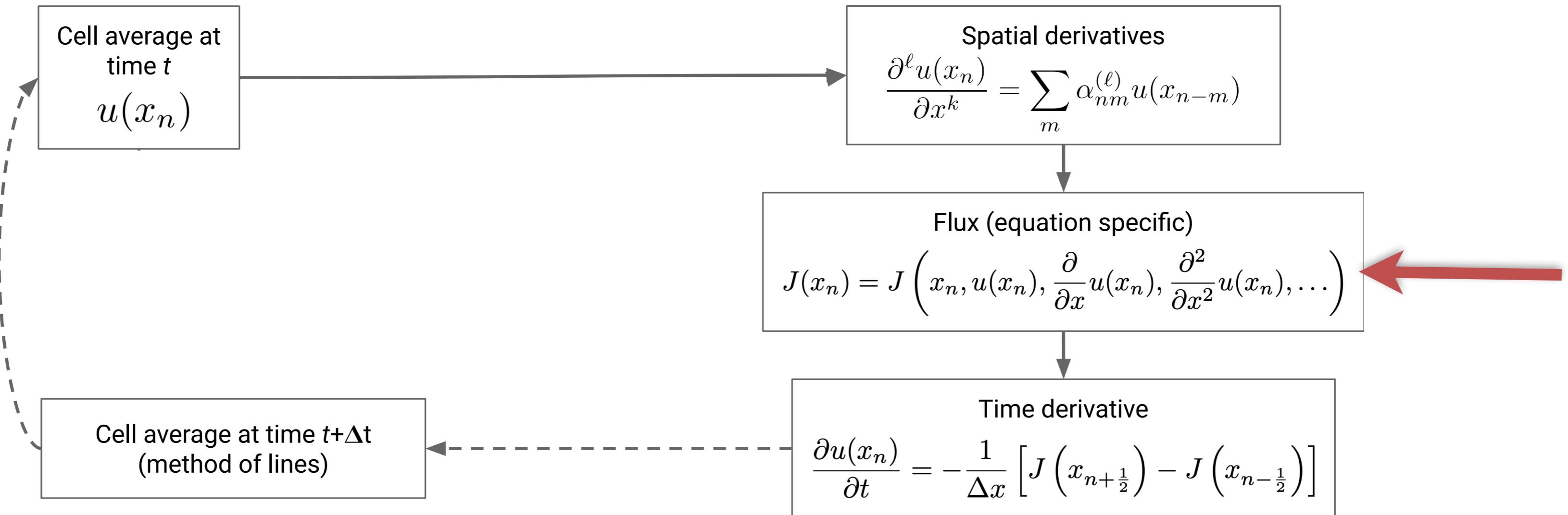
Data Driven Discretization



- One of the less intrusive approaches
- Objective: achieve better gradient estimation on coarse meshes \Leftrightarrow run same simulation on coarser mesh

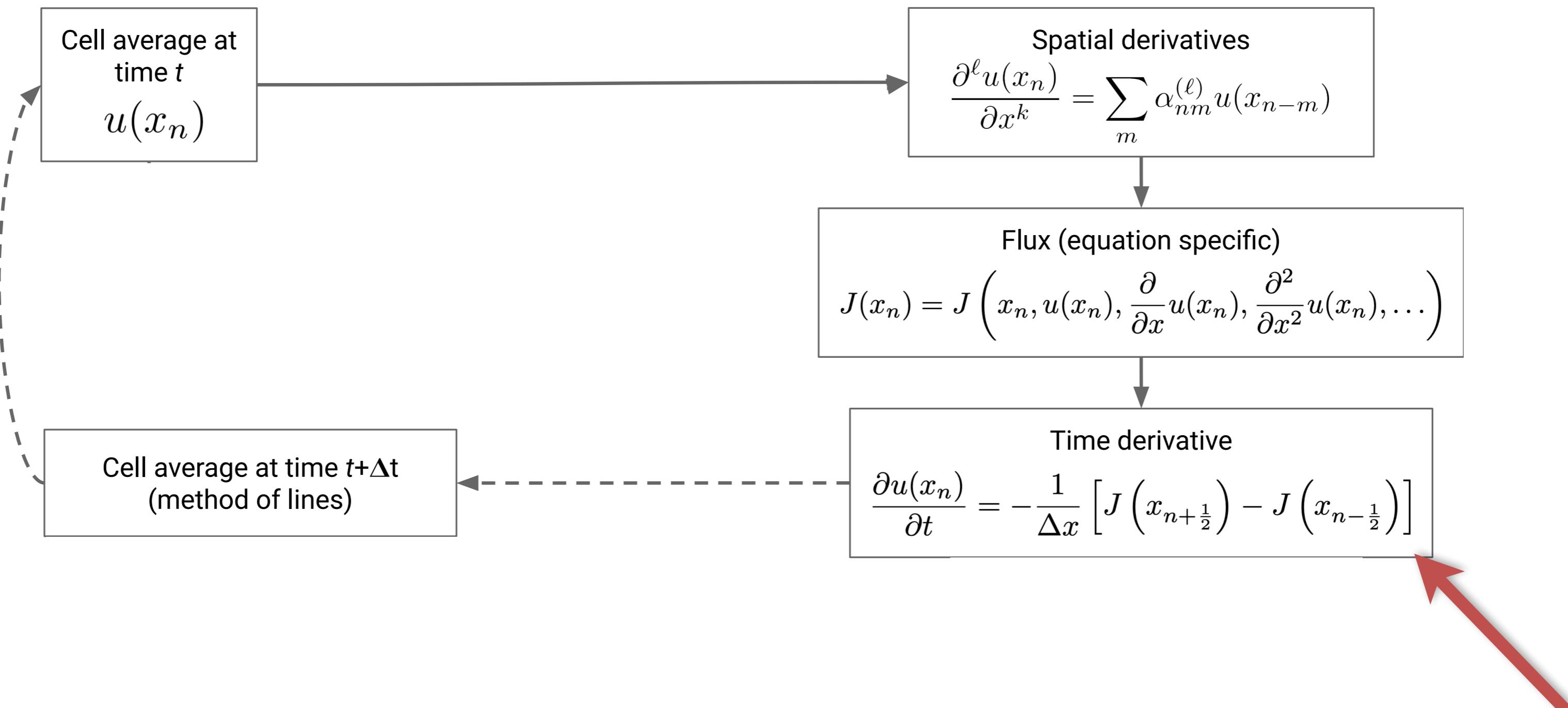
Bar-Sinai, Y., Hoyer, S., Hickey, J., & Brenner, M. P. (2019). Learning data-driven discretizations for partial differential equations. *Proceedings of the National Academy of Sciences*, 116(31), 15344-15349.

Data Driven Discretization



- One of the less intrusive approaches
- Objective: achieve better gradient estimation on coarse meshes \Leftrightarrow run same simulation on coarser mesh

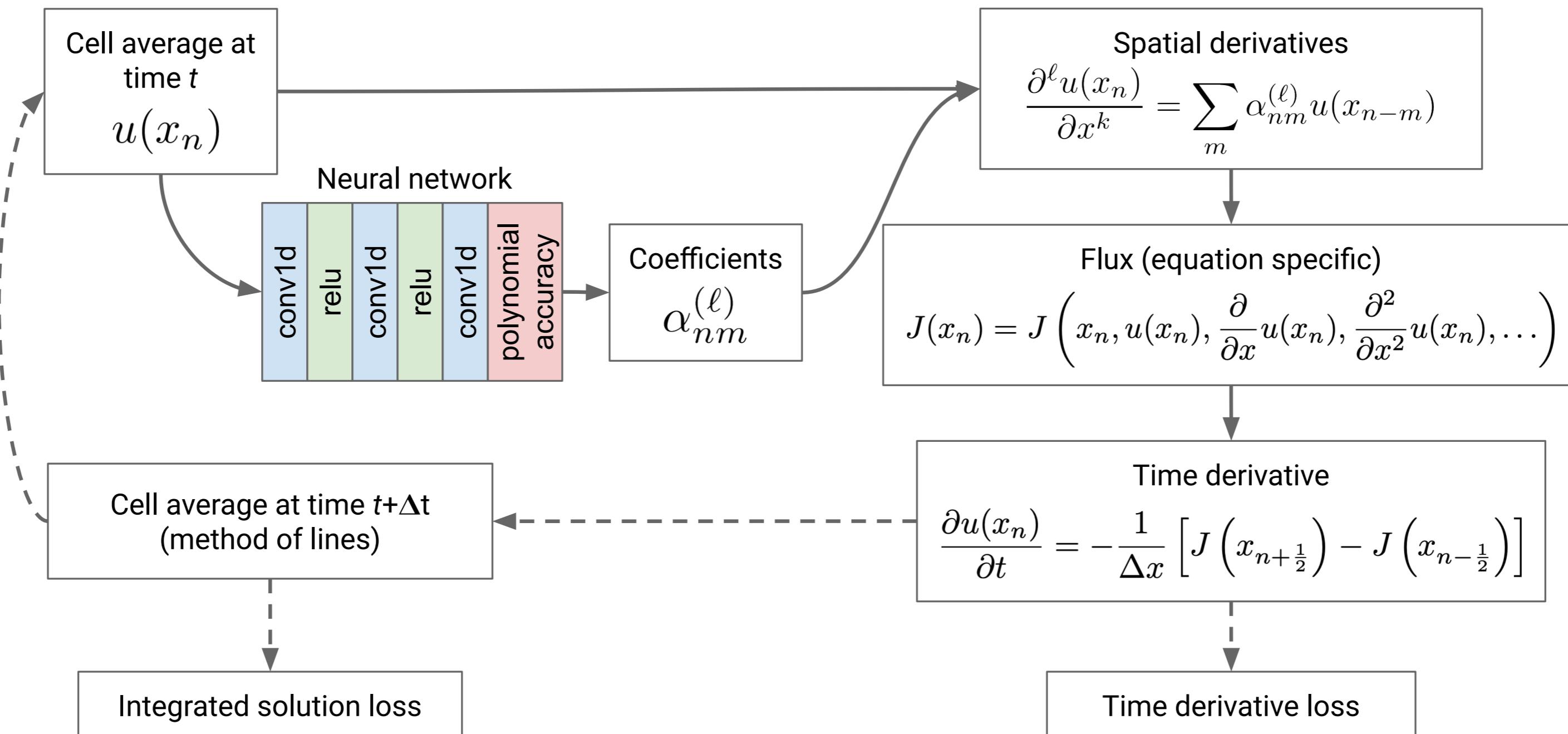
Data Driven Discretization



- One of the less intrusive approaches
- Objective: achieve better gradient estimation on coarse meshes \Leftrightarrow run same simulation on coarser mesh

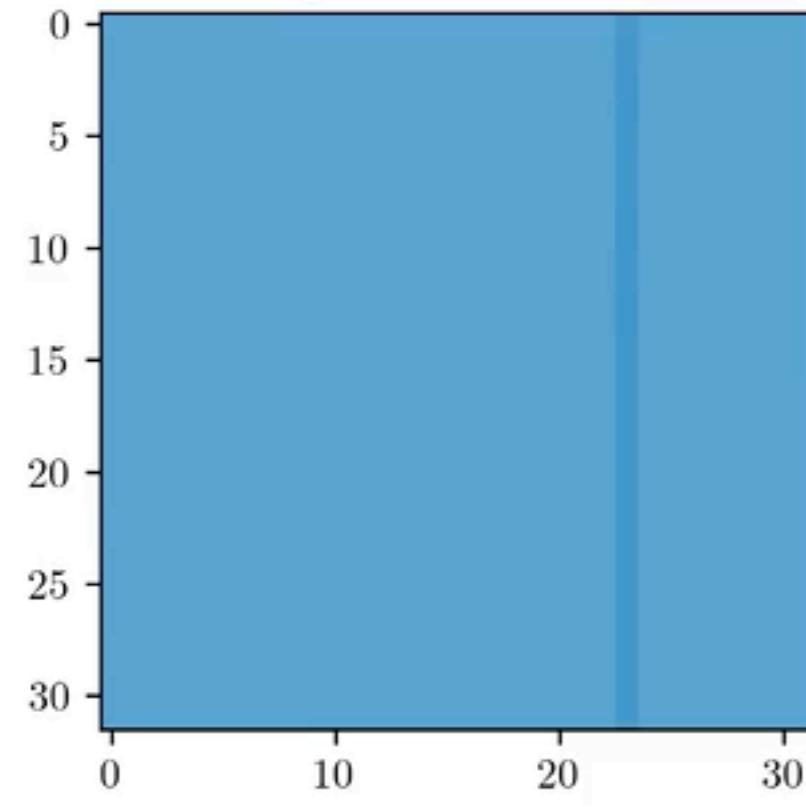
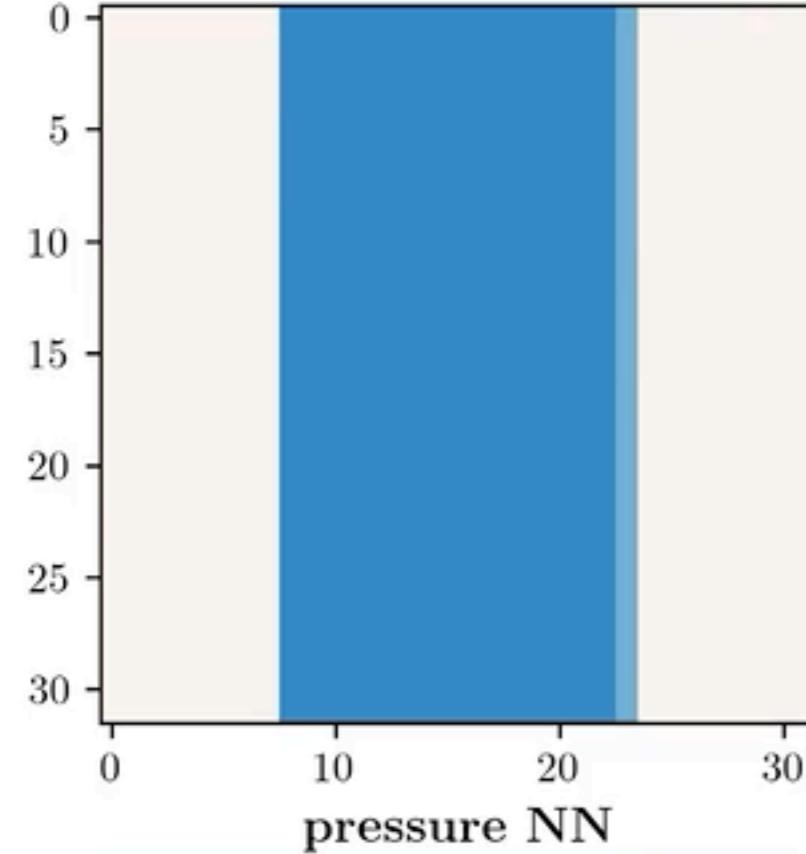
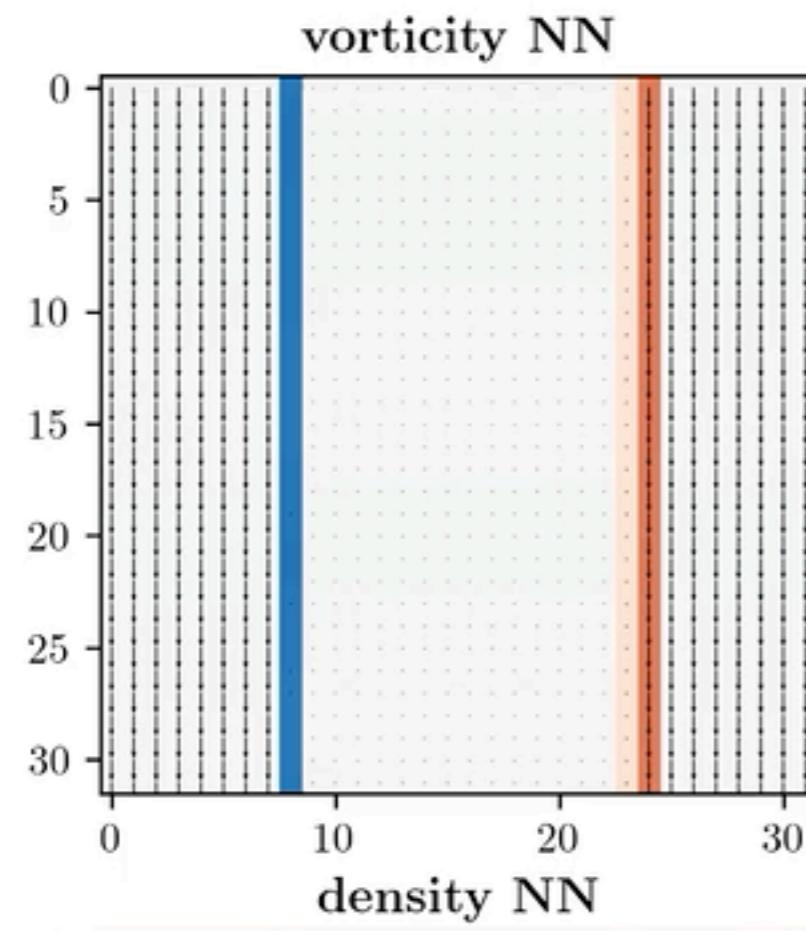
Bar-Sinai, Y., Hoyer, S., Hickey, J., & Brenner, M. P. (2019). Learning data-driven discretizations for partial differential equations. *Proceedings of the National Academy of Sciences*, 116(31), 15344-15349.

Data Driven Discretization

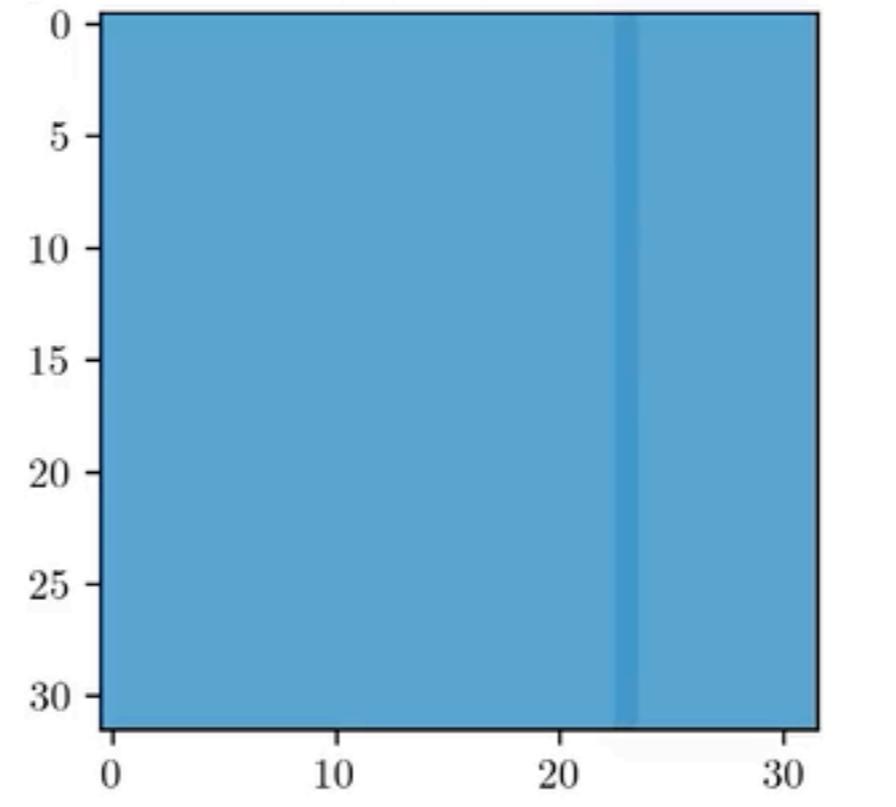
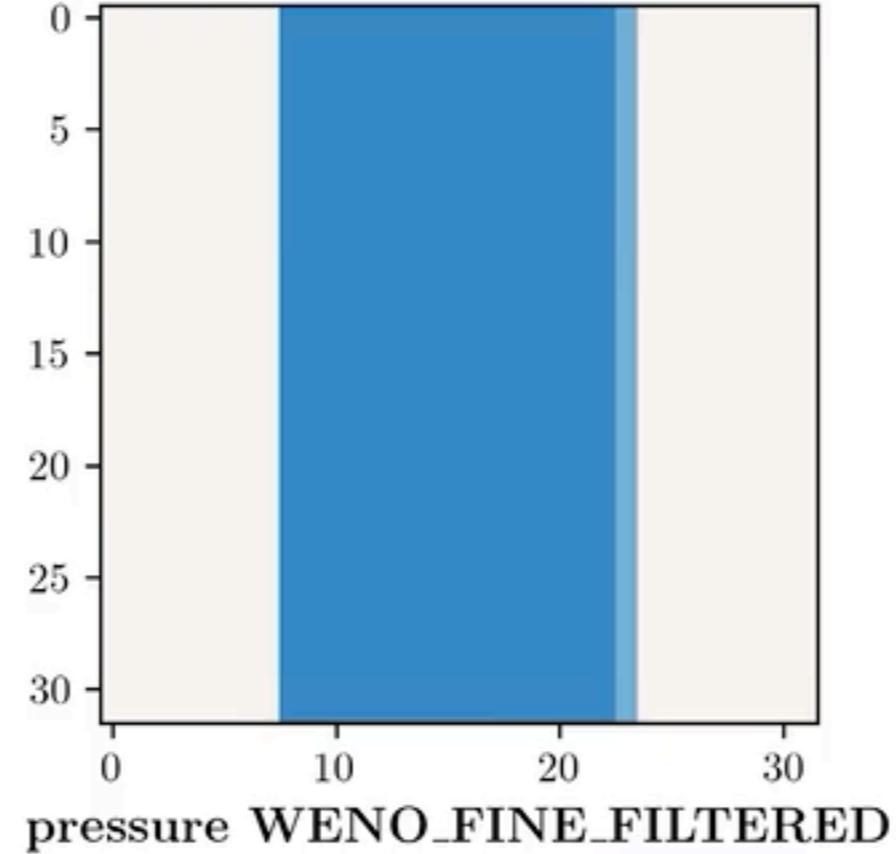
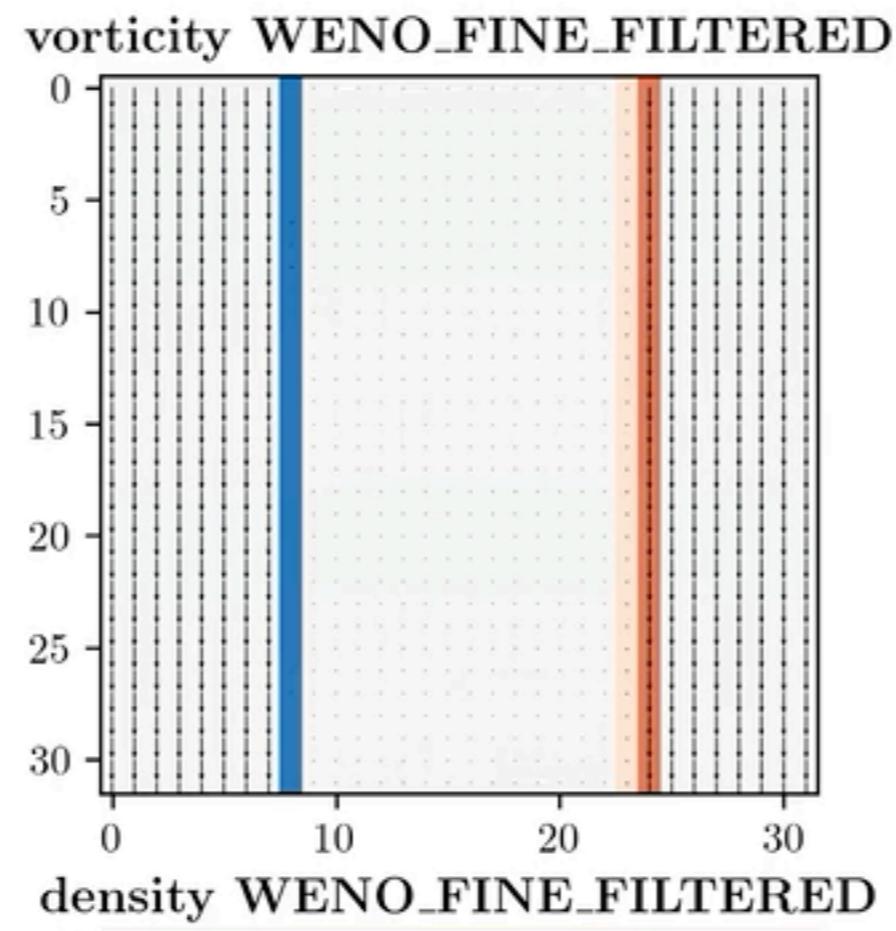


- One of the less intrusive approaches
- Objective: achieve better gradient estimation on coarse meshes \Leftrightarrow run same simulation on coarser mesh

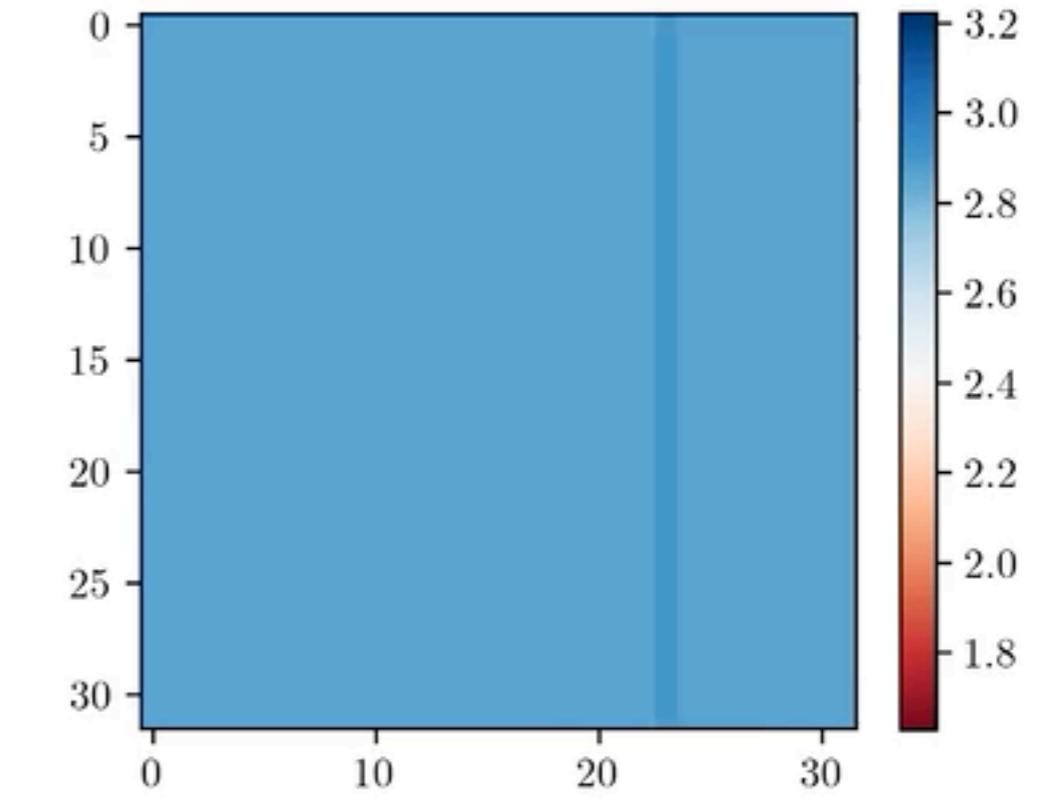
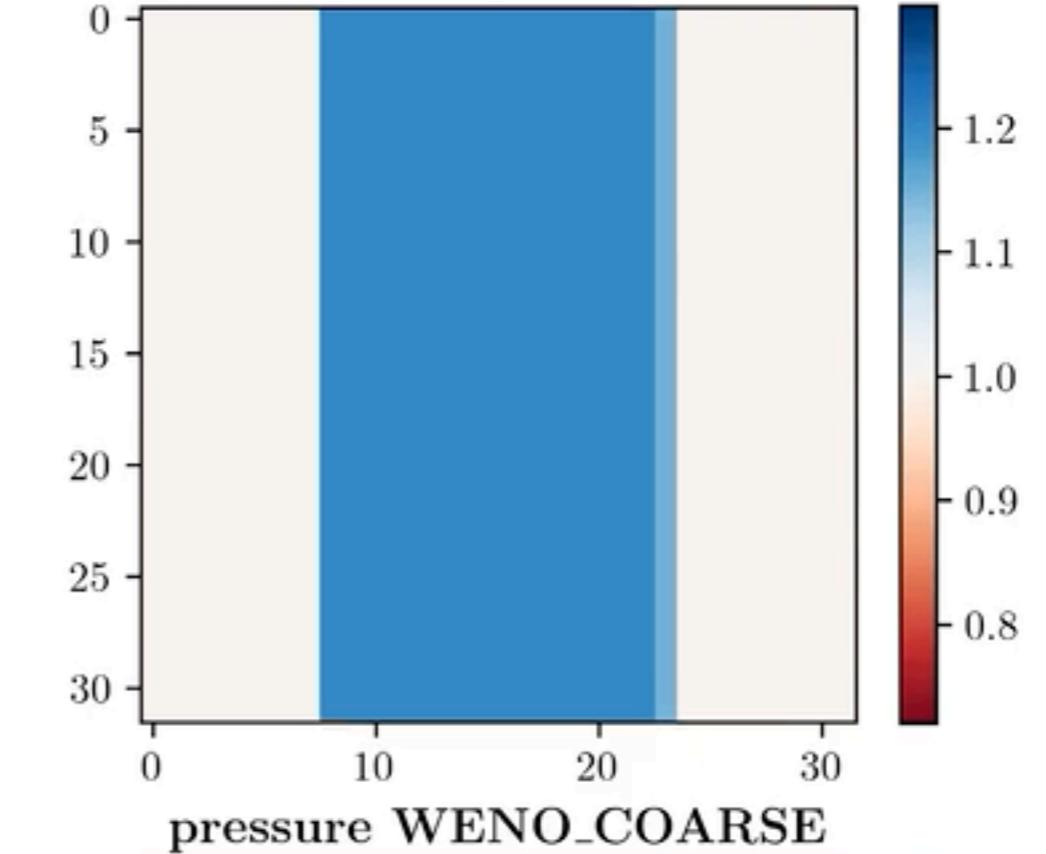
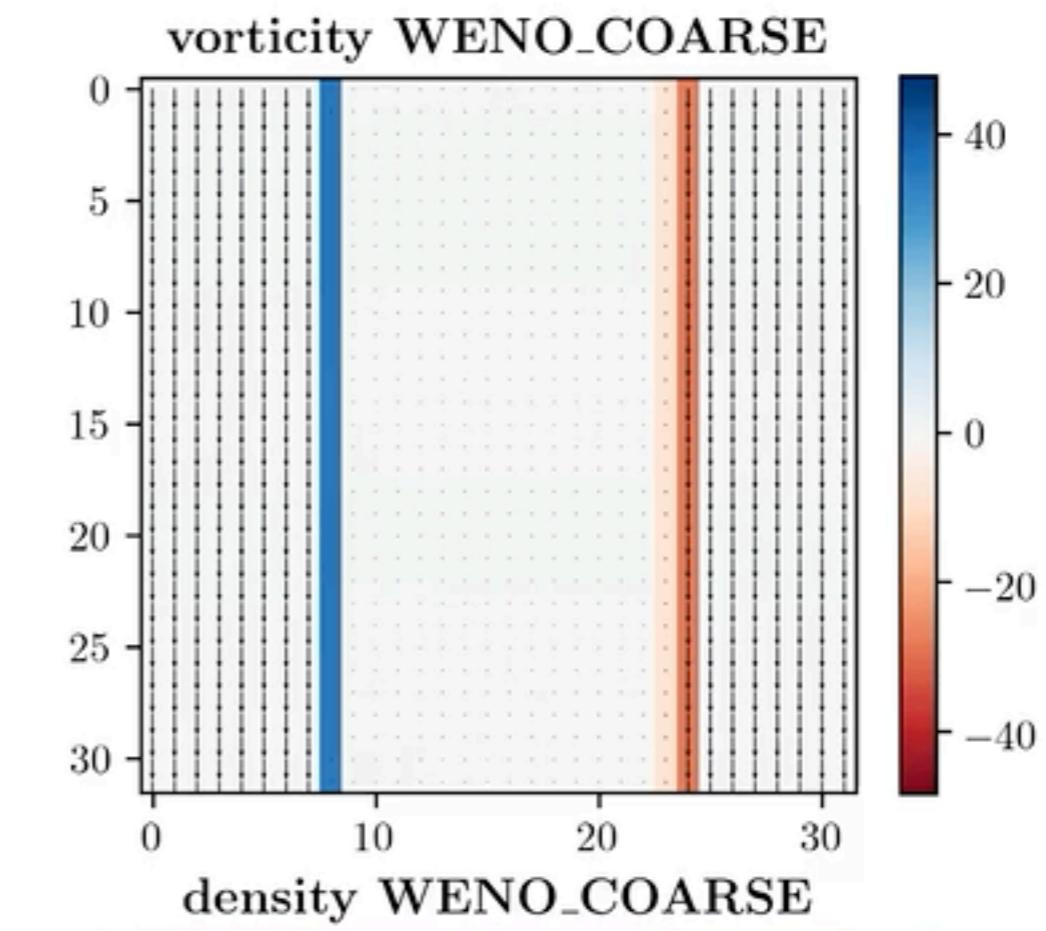
Bar-Sinai, Y., Hoyer, S., Hickey, J., & Brenner, M. P. (2019). Learning data-driven discretizations for partial differential equations. *Proceedings of the National Academy of Sciences*, 116(31), 15344-15349.



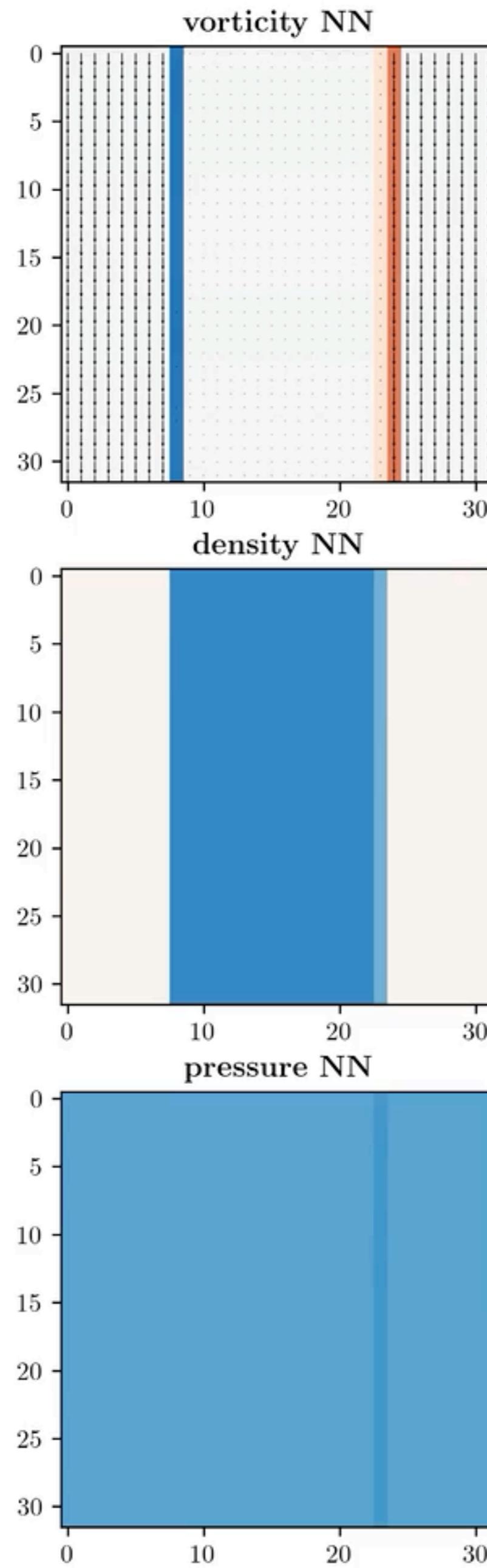
Coarse LES with NN



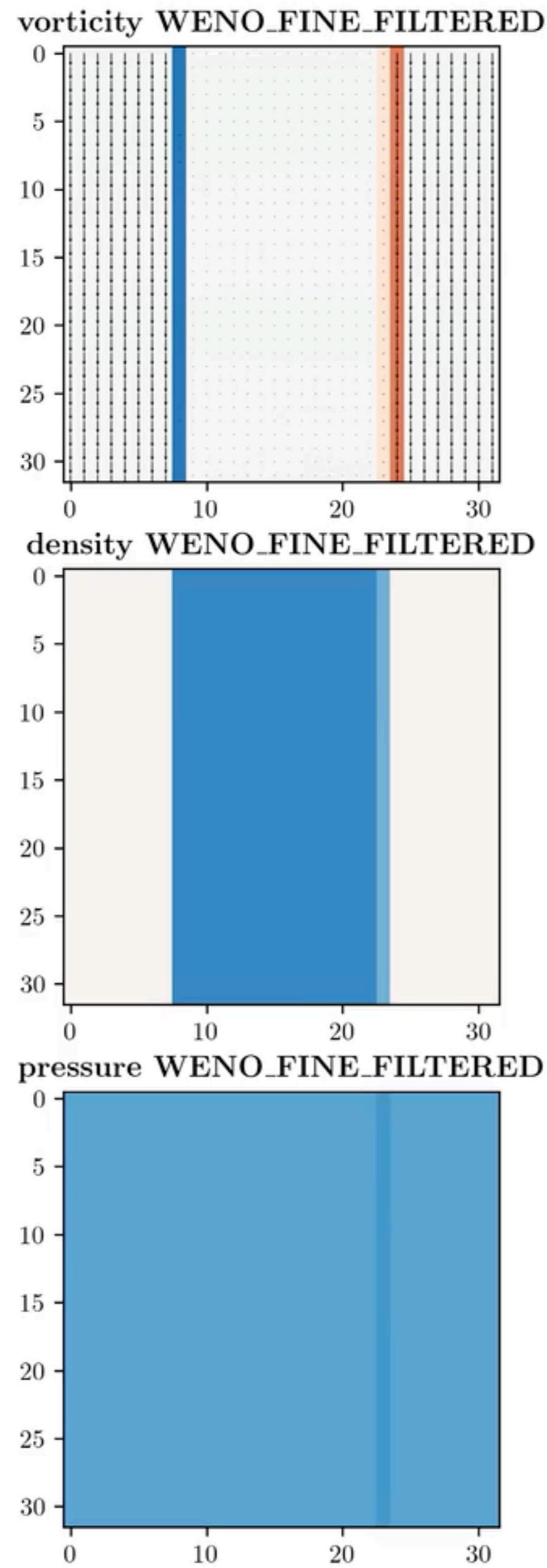
« Truth » (DNS)



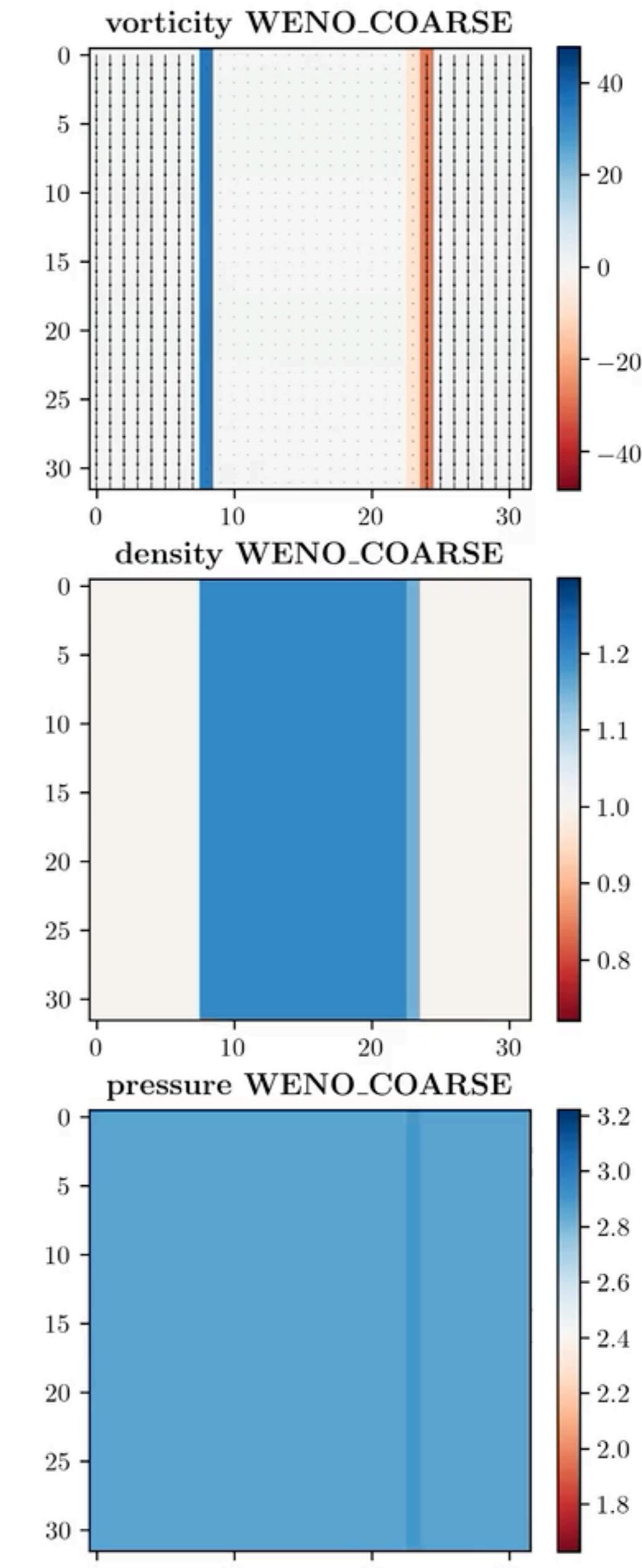
Coarse LES



Coarse LES with NN



« Truth » (DNS)

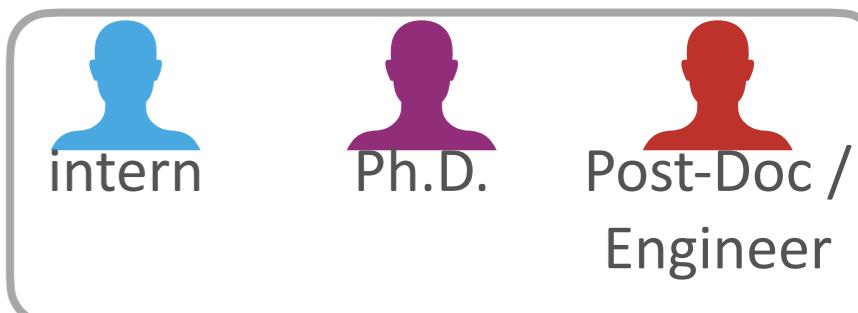
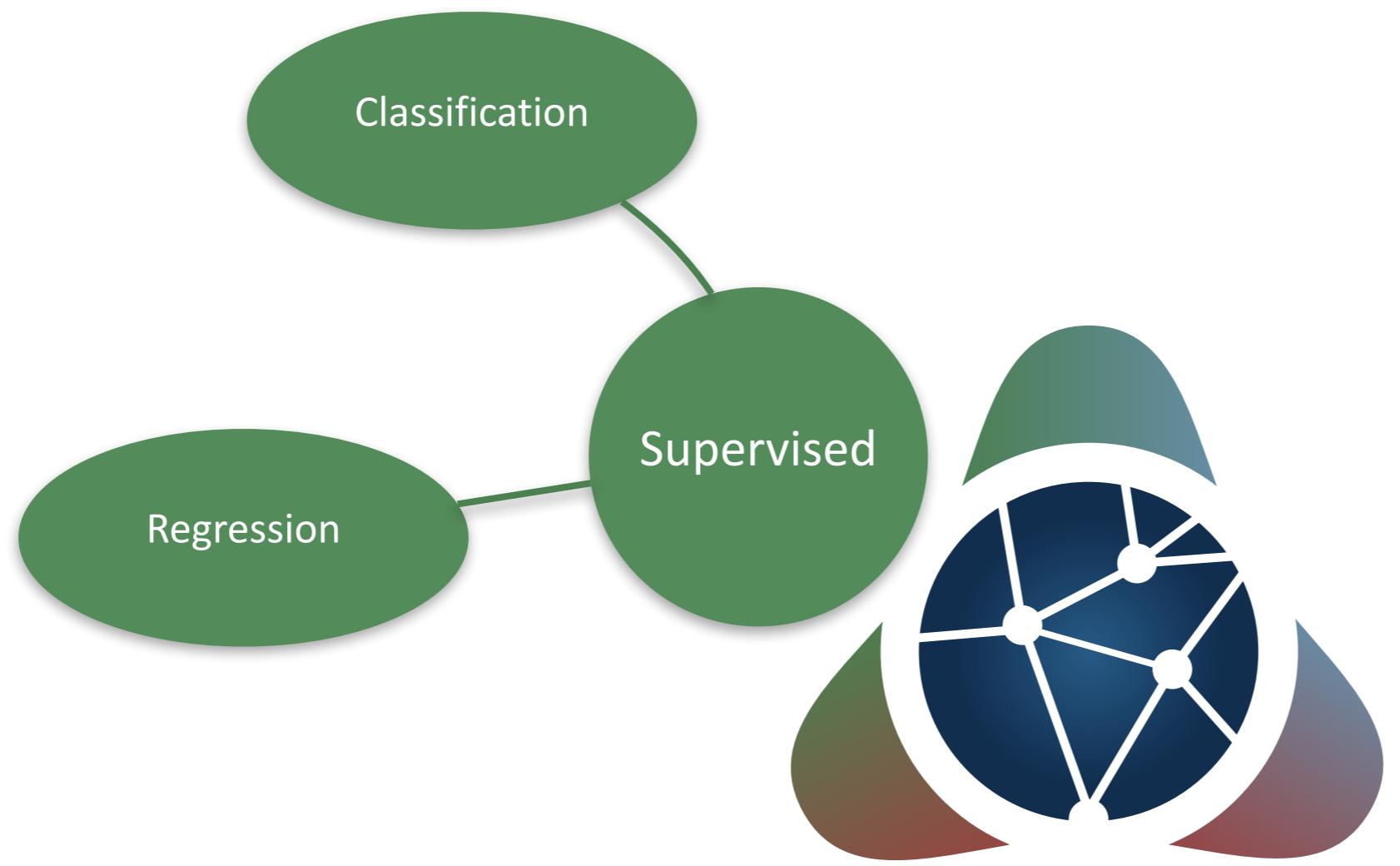


Coarse LES

Great idea, difficult execution

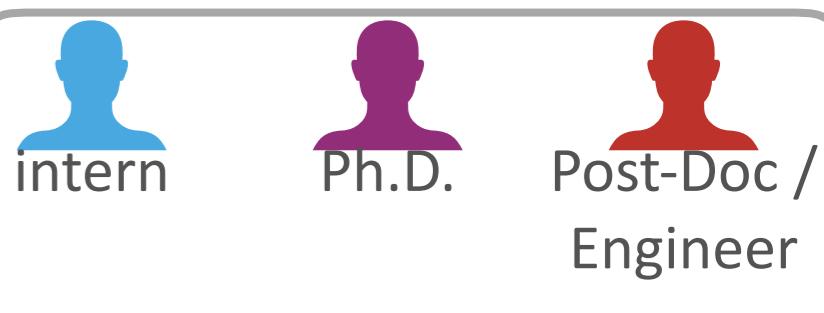
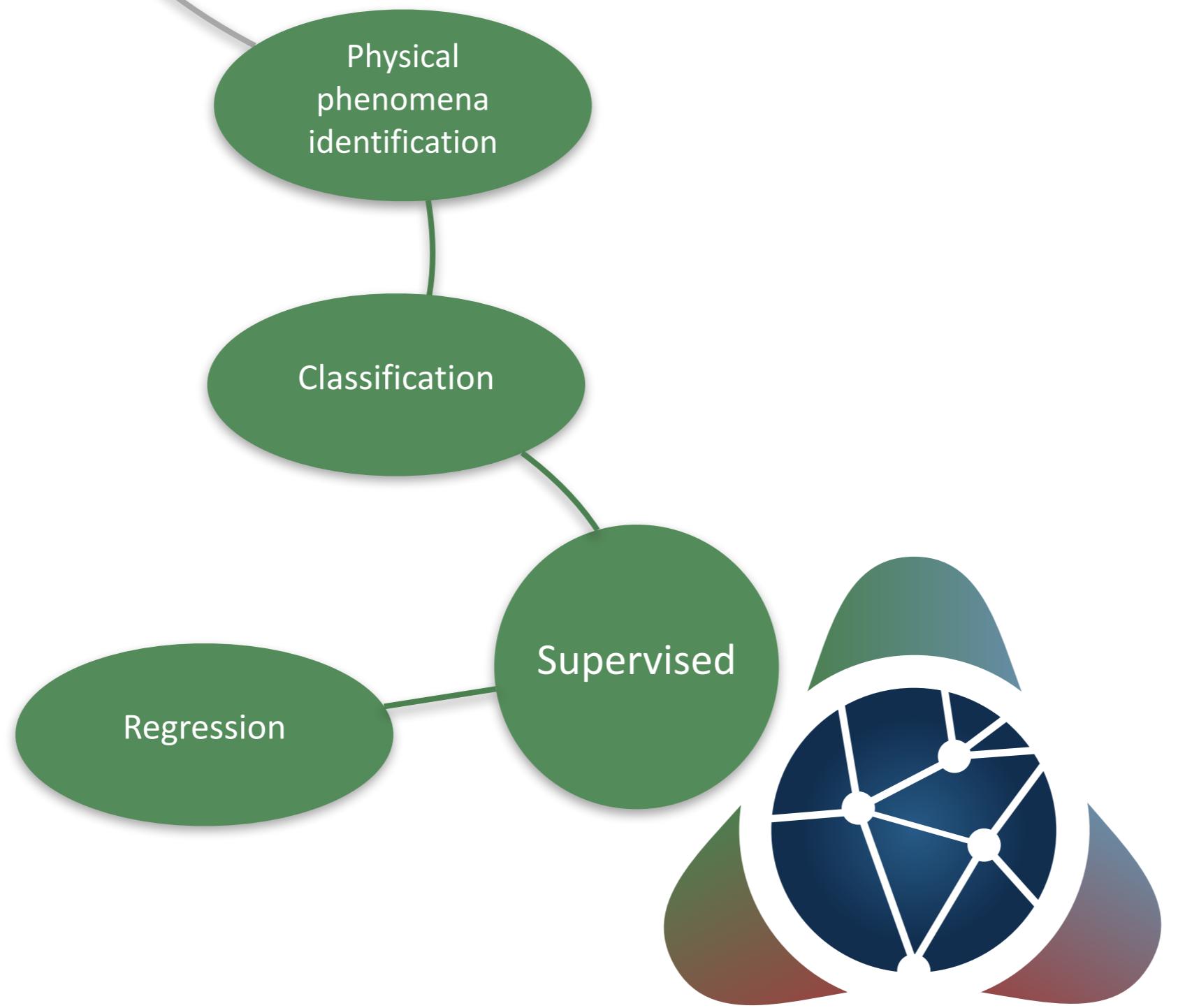
- Challenge #1: differentiability
 - NN require the chain to be differentiable *i.e. you must rewrite your CFD solver in a deep learning framework*
 - Several solvers with this tech under development (e.g. PhiFlow [1] at TUM)
- Challenge #2: time stability
 - Supervised learning (error wrt next iteration) leaves room for small errors that accumulate => divergence
 - *BUT* training in a supervised manner long term doesn't seem to work: turbulent paths differ, and punishing the network for difference to DNS doesn't work anymore

Concluding remarks





Predictive
Maintenance





Ronan Paugam
Nicolas Cazard

Forest fire
front tracking



Michele **AIRBUS**
Lazzara

Predictive
Maintenance

Image
segmentation

Physical
phenomena
identification

Classification

Regression

Supervised





Ronan Paugam
Nicolas Cazard



Predictive Maintenance
Michele Lazzara
AIRBUS

Forest fire front tracking

Image segmentation

Physical phenomena identification



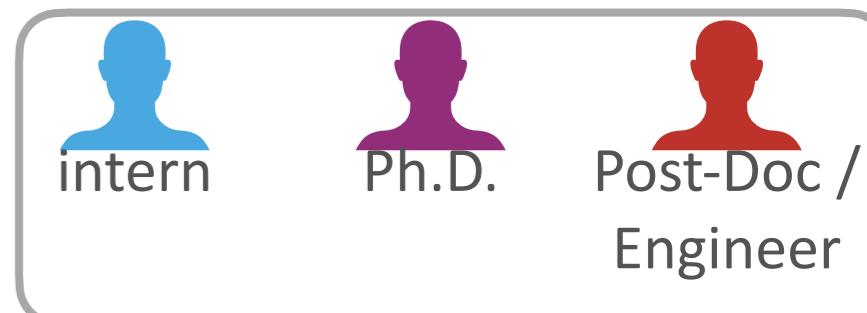
Virtual mechanic

Sound classification

Classification

Regression

Supervised





Ronan Paugam

Nicolas Cazard



Predictive
Maintenance

Forest fire
front tracking

Image
segmentation

Physical
phenomena
identification



Virtual
mechanic



Replacing local
physical models
with CNNs

Sound classification

Regression

Classification

Supervised





Forest fire front tracking

Image segmentation

Sound classification

Regression

Classification

Physical phenomena identification

Supervised



Virtual mechanic



Replacing local physical models with CNNs

Time series forecasting





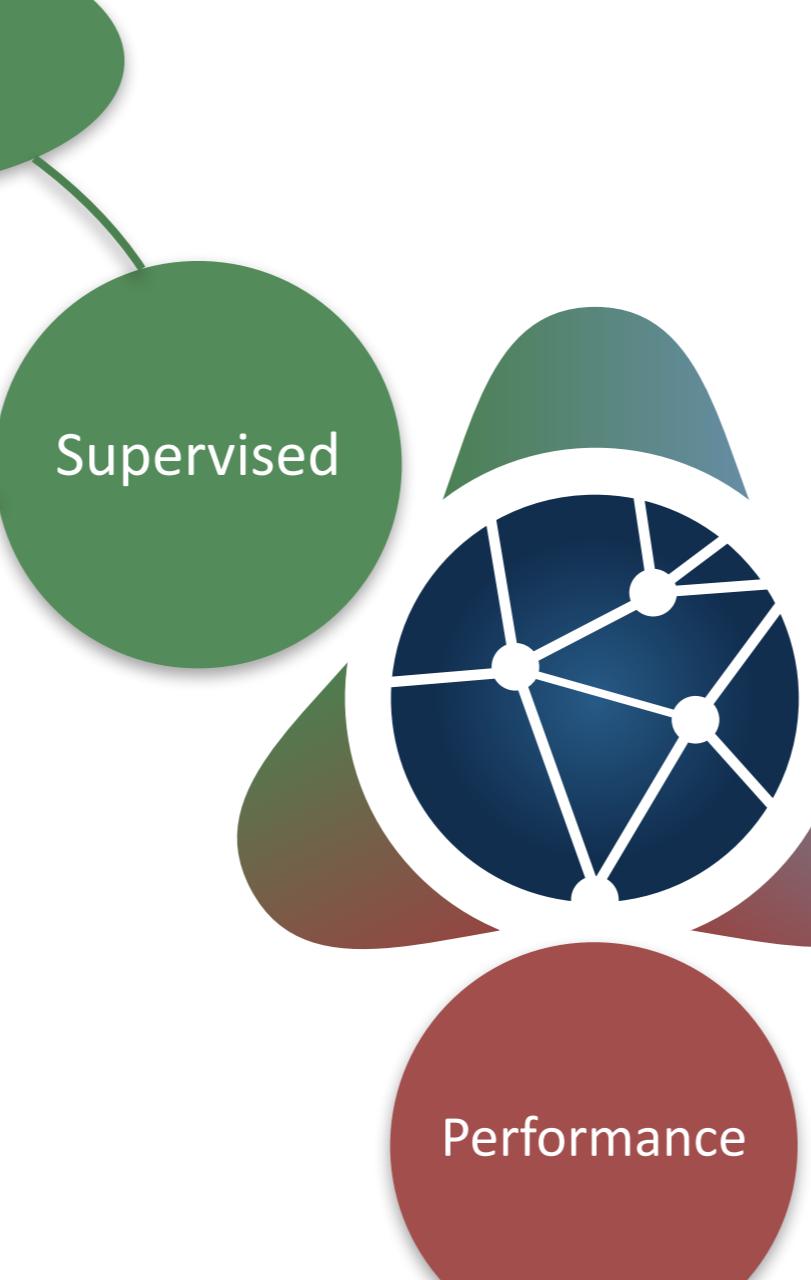
Forest fire front tracking

Image segmentation

Sound classification

Classification

Regression



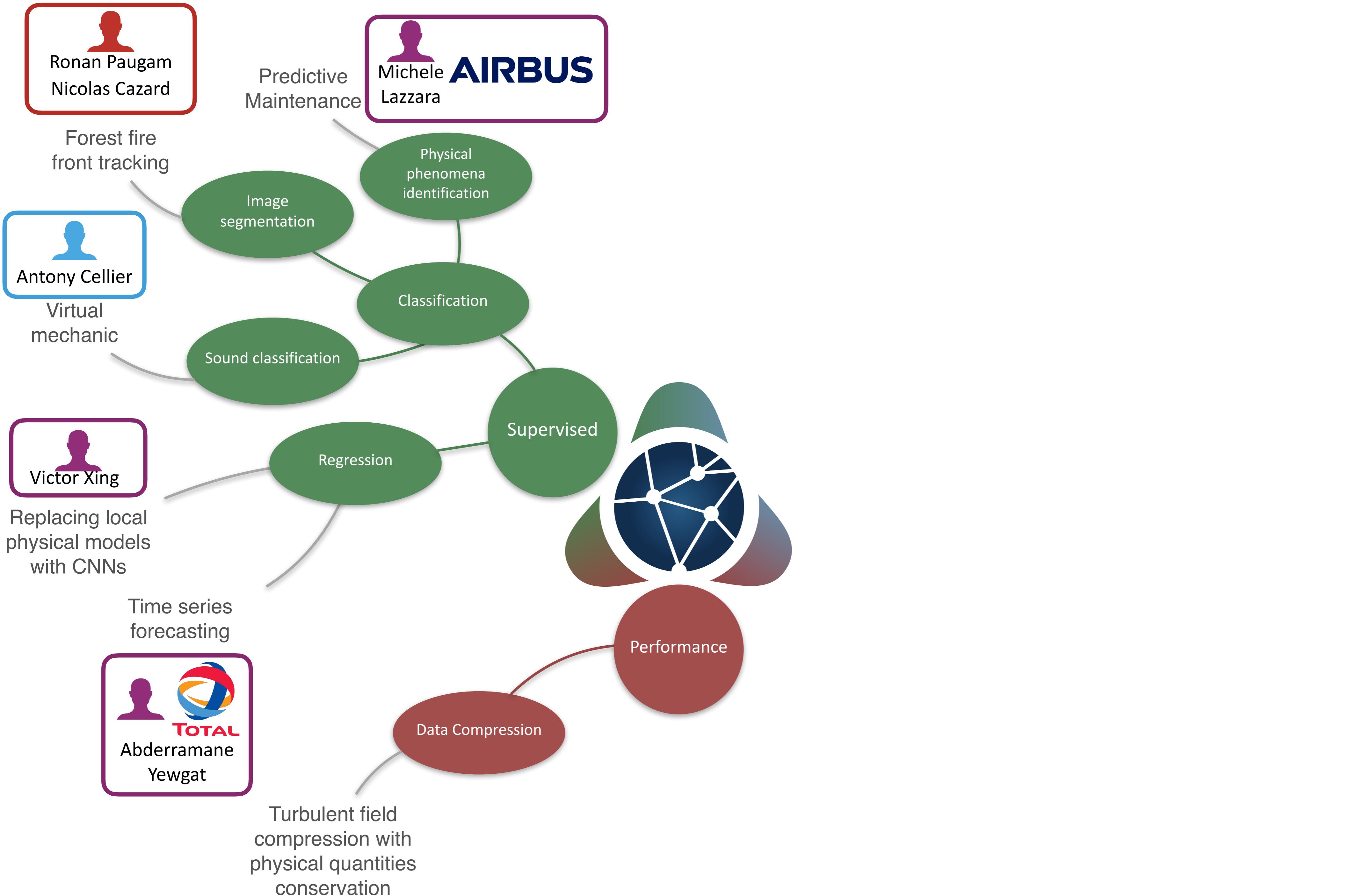
Virtual mechanic

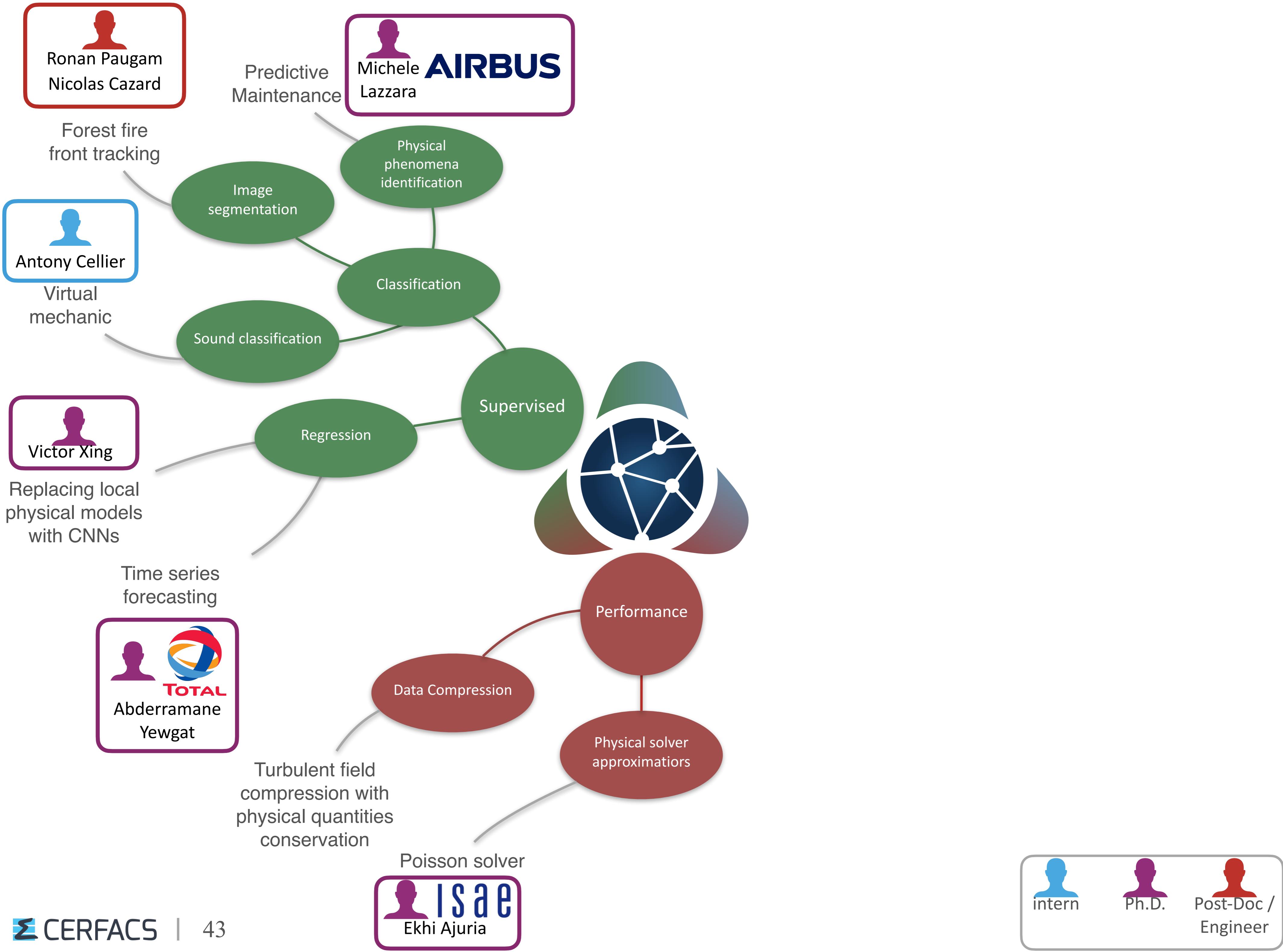


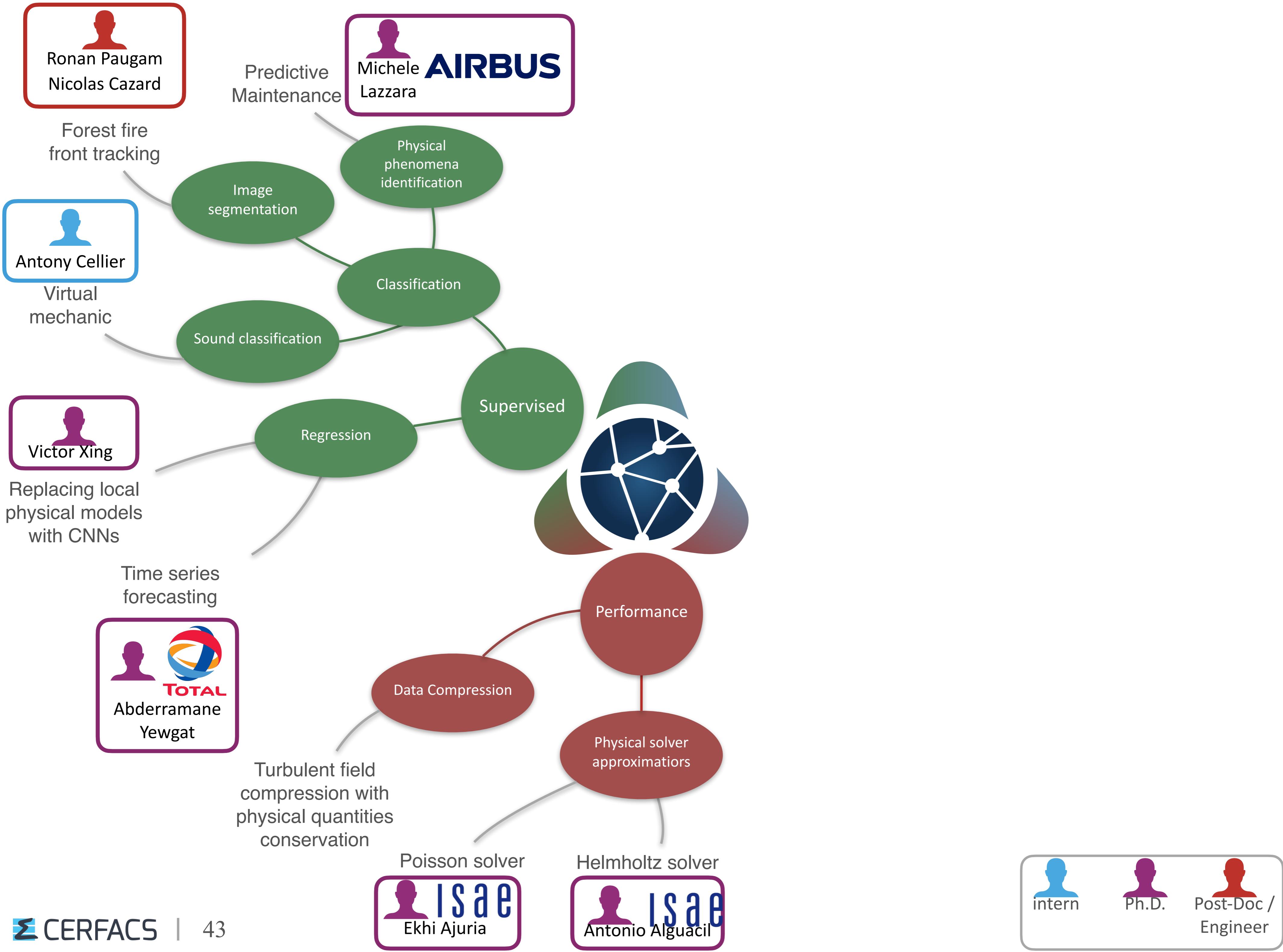
Replacing local physical models with CNNs

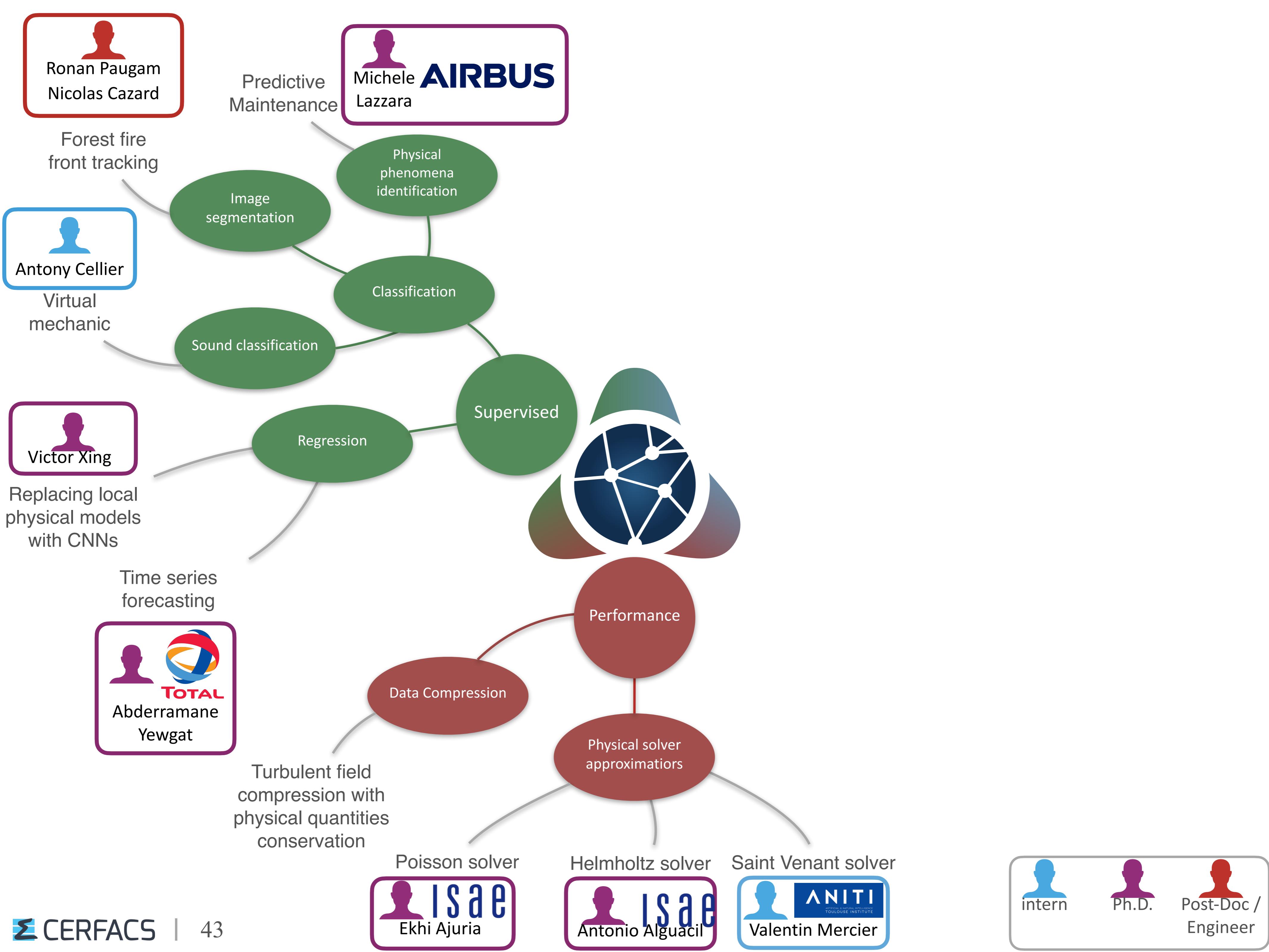
Time series forecasting

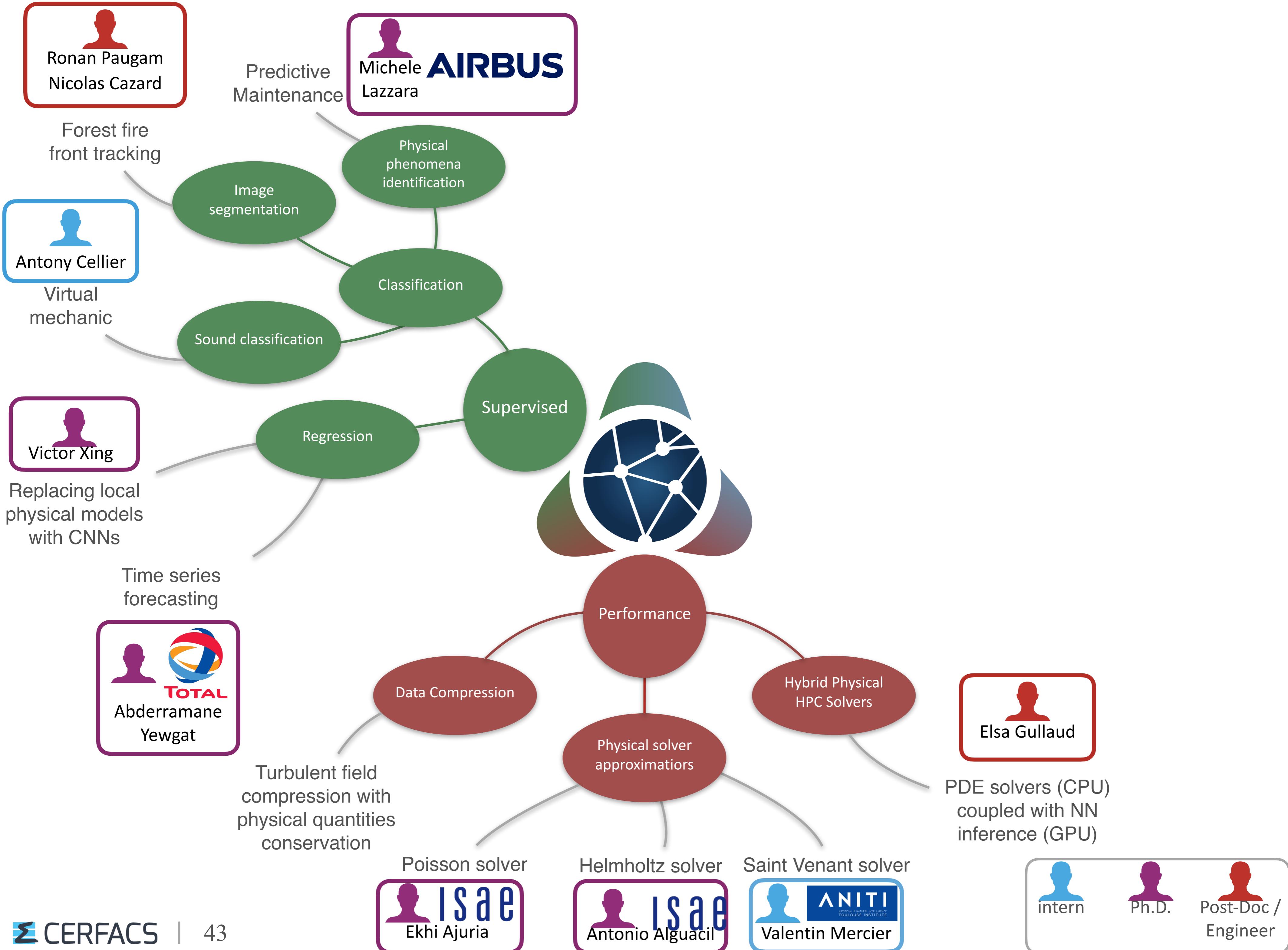


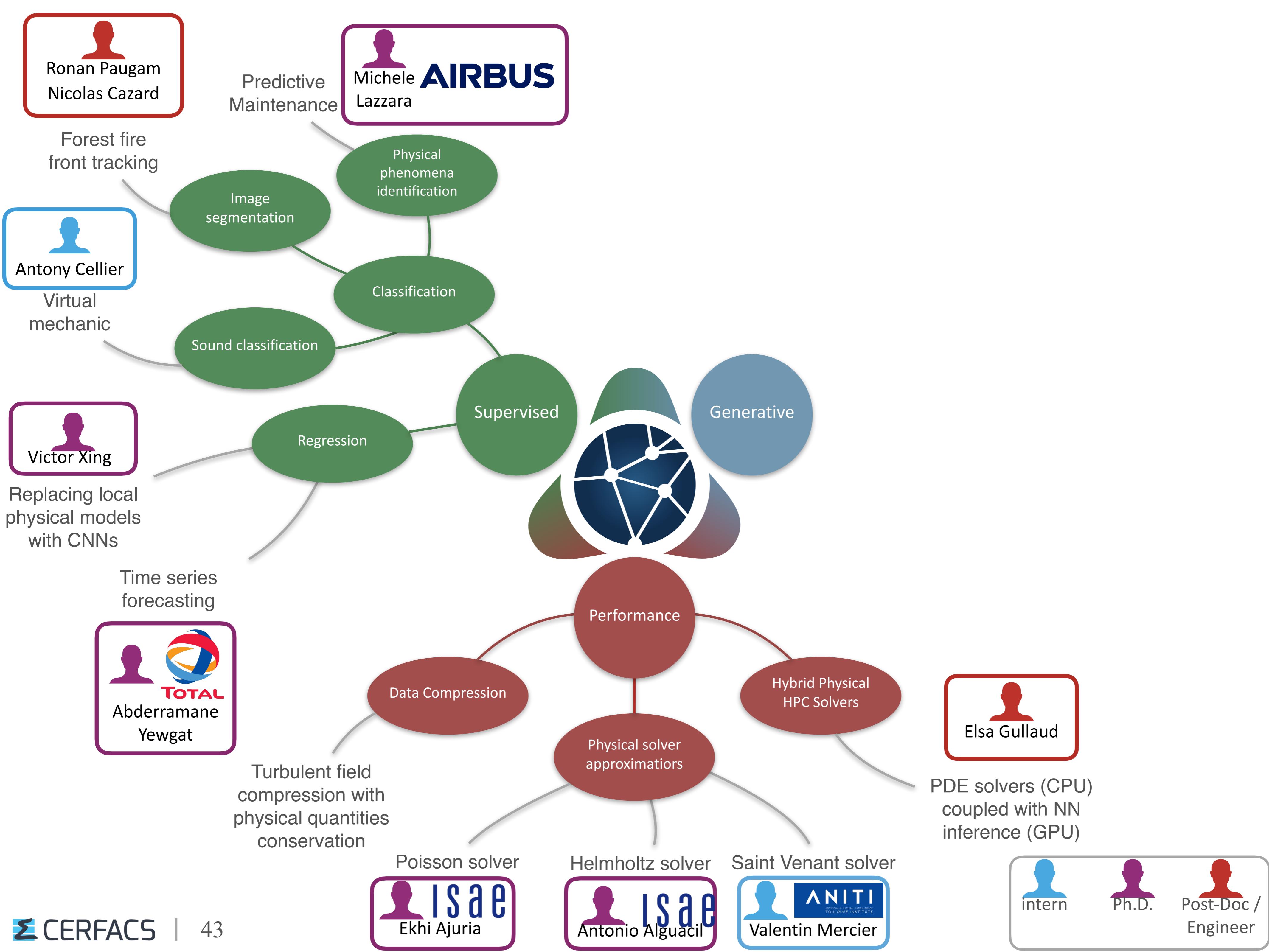


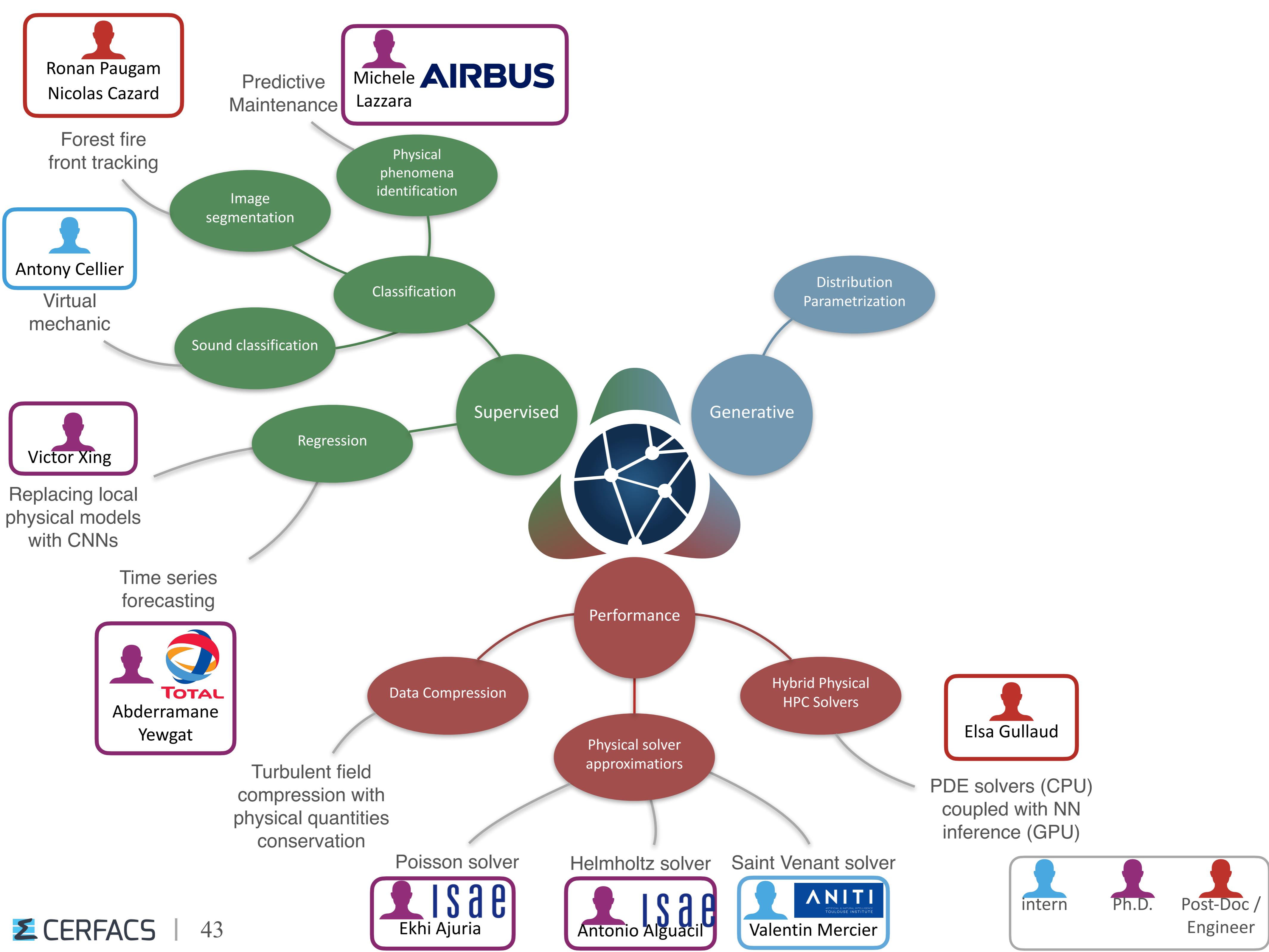


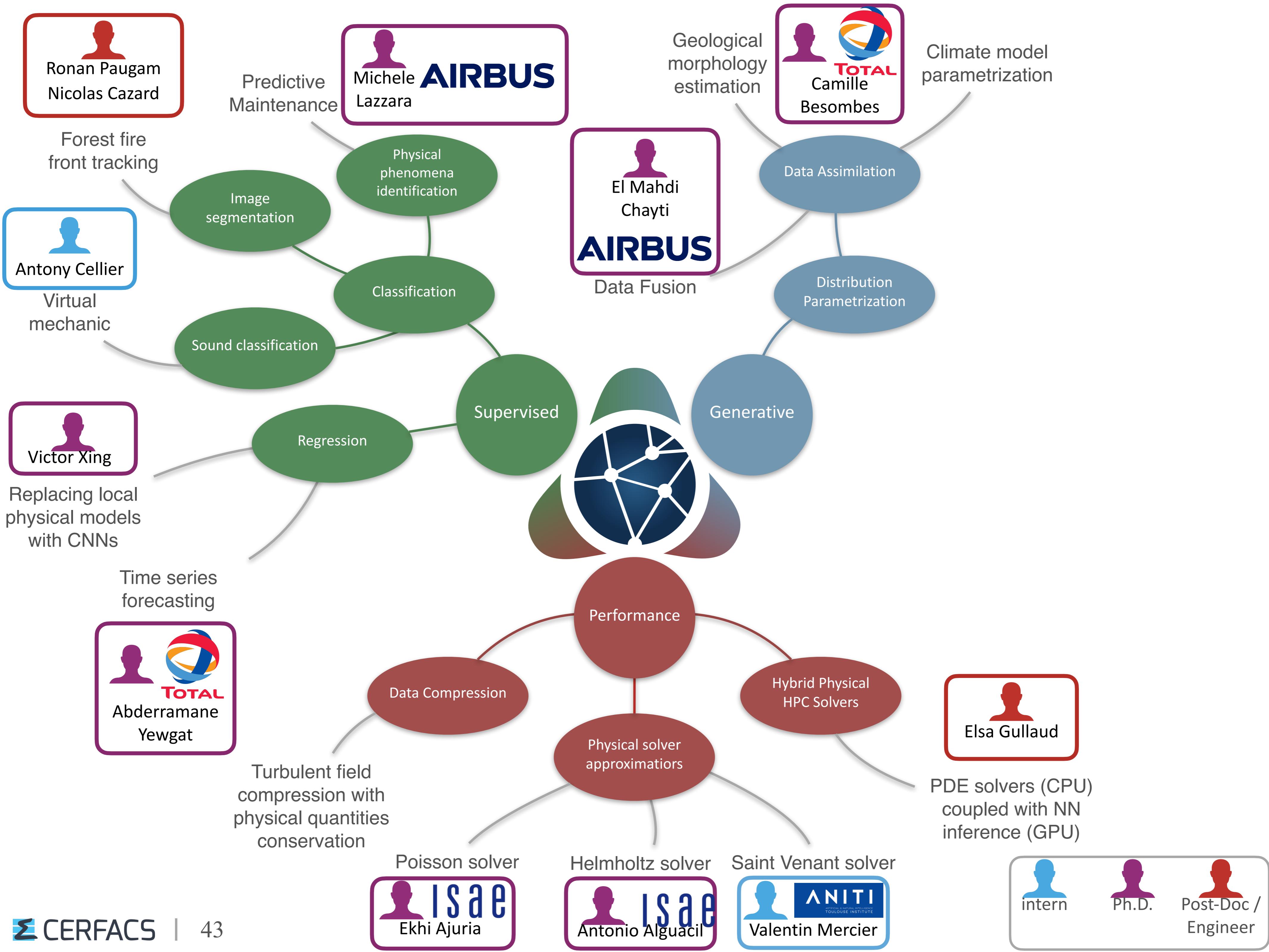


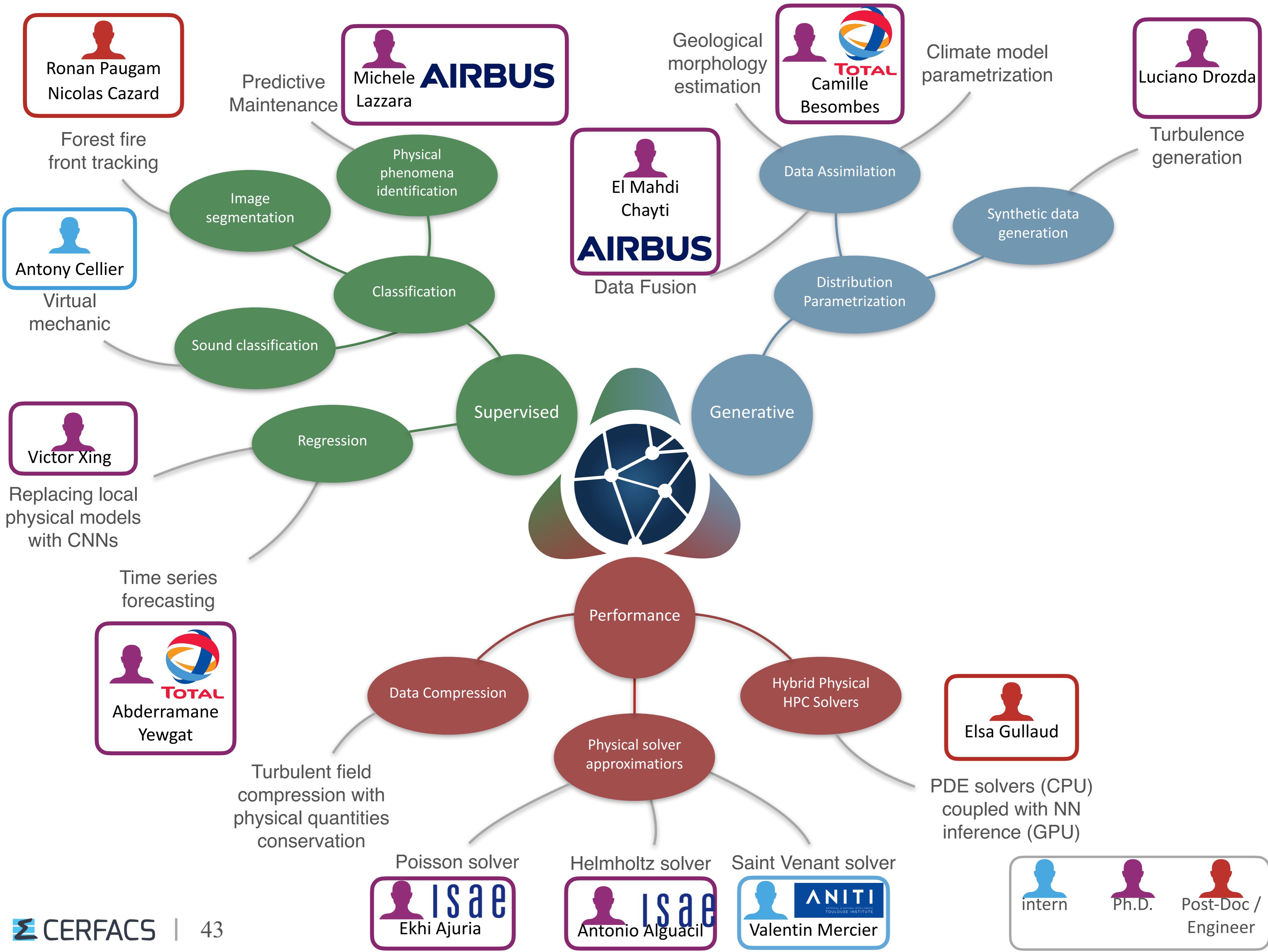


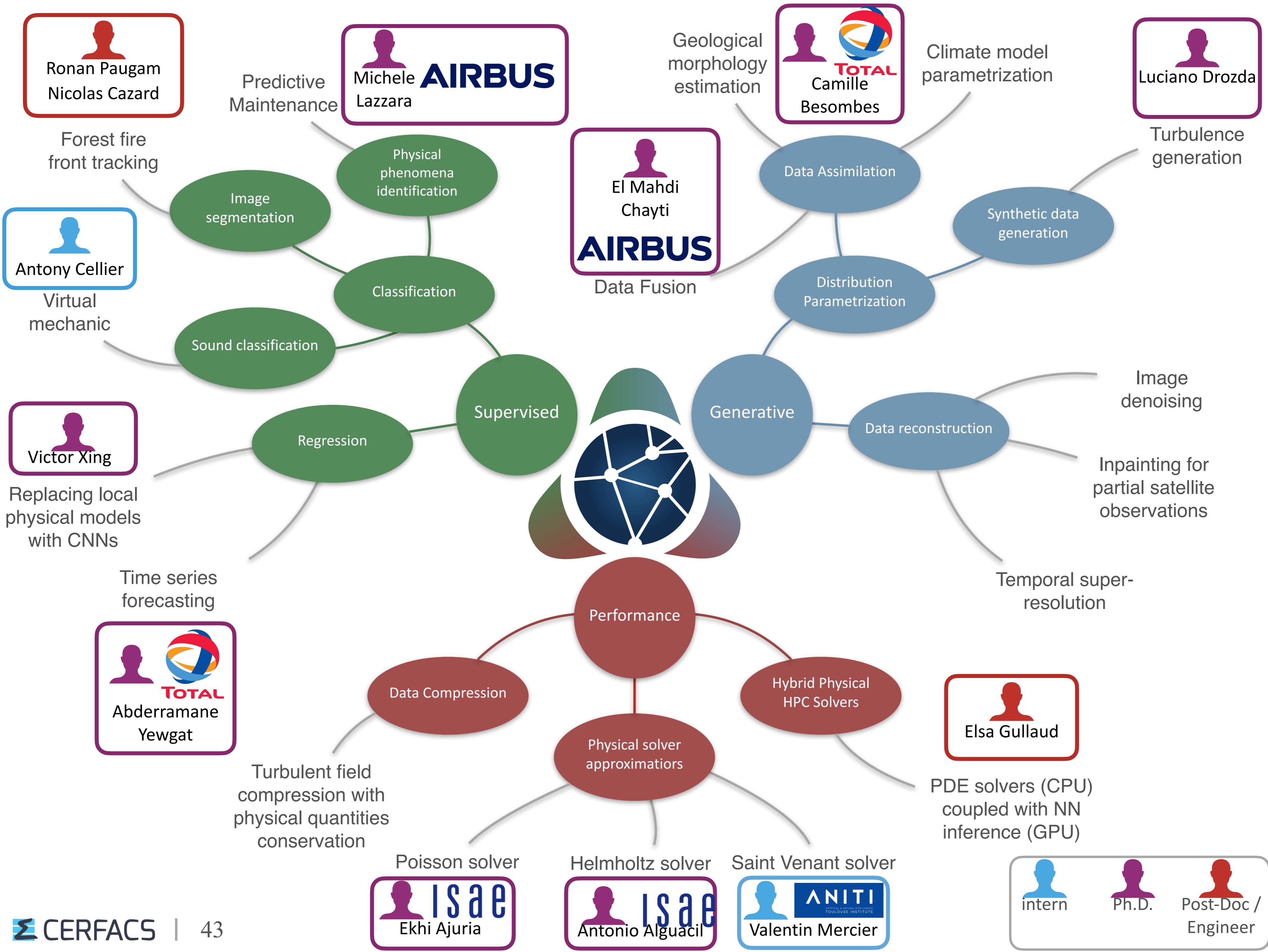


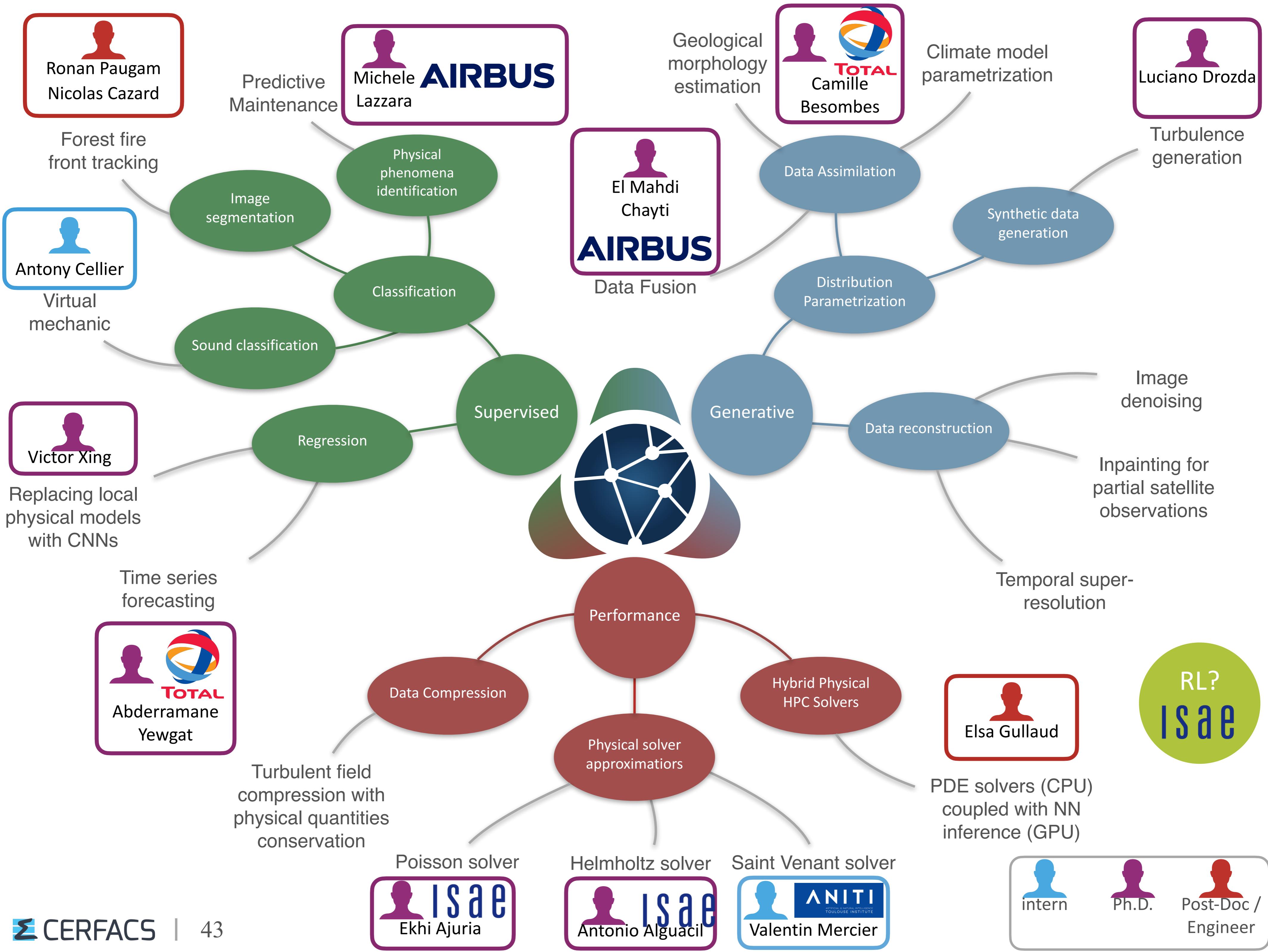












Thank you

- Papers:

- Lapeyre, C.J., Misdariis, A., Cazard, N., Veynante, D. & Poinsot, T. (2019). Training convolutional neural networks to estimate turbulent sub-grid scale reaction rates. *Combustion and Flame*, 203, 255-264.

- Conferences:

- Lapeyre, C. J., Cazard, N., Roy, P. T., Ricci, S., & Zaoui, F. (2019). Reconstruction of Hydraulic Data by Machine Learning. SimHydro 2019, Nice, France, June 12-14, arXiv:1903.01123.
- Lapeyre, C.J., Misdariis, A., Cazard, N., Xing, V., Veynante, D. & Poinsot, T. (2019). A convolutional neural network-based efficiency function for sub-grid flame-turbulence interaction in LES. 16th International Conference on Numerical Combustion, May 6-8 2015, Avignon France.
- Ronan Paugam, Melanie Rochoux, Nicolas Cazard, Corentin Lapeyre, William Mell, Joshua Johnston, and Martin Wooster: Computing High Resolution Fire Behavior Metrics from Prescribed Burn using Handheld Airborne Thermal Camera Observations. The 6th International Fire Behaviour and Fuels Conference, Marseilles, May 2019.
- Ronan Paugam, Melanie Rochoux, Nicolas Cazard, Corentin Lapeyre, William Mell, Joshua Johnston, and Martin Wooster. Journée de télédétection et incendie Organisée par IRSTEA, Aix, Decembre 2018.
- Lapeyre, C.J., Misdariis, A., Cazard, N, Poinsot, T. Replacing a sub-grid closure model with a trained deep convolutional neural network. HiFiLeD Symposium, November 14-16th 2018, Brussels Belgium.

- Other:

- Lapeyre, C.J., Misdariis, A., Cazard, N. & Poinsot, T (2018). A-posteriori evaluation of a deep convolutional neural network approach to subgrid-scale flame surface estimation. Proc. CTR Summer Program, 349-358.